

# Introduction To Small Signal And Averaged Switch Modeling

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Seminar Prepared For APEC 2015

# Seminar Introduction

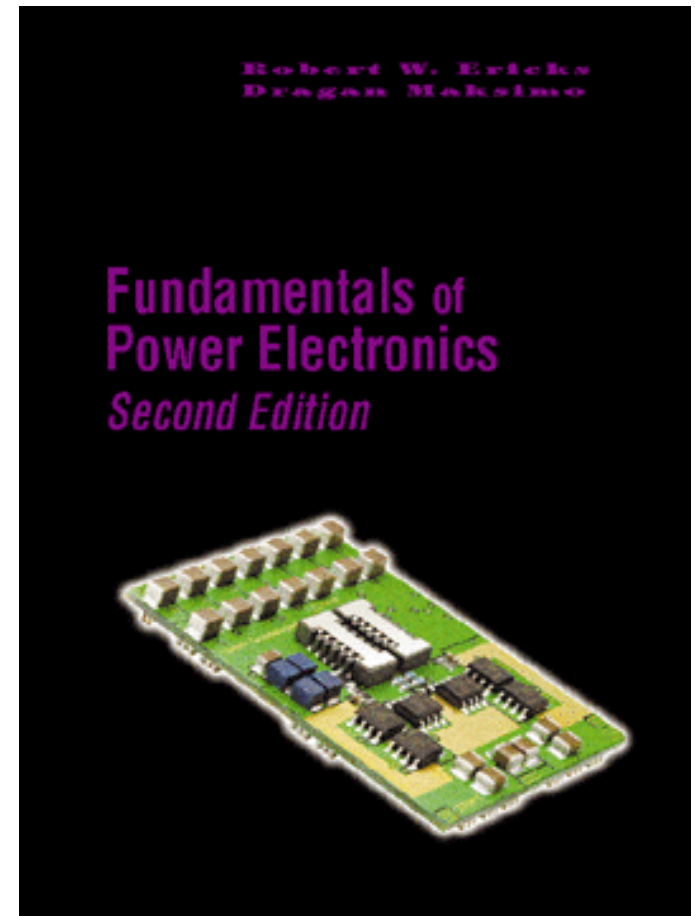
- This Is An Introductory Seminar
  - Why Do We Need Small Signal Modeling?
  - Small Signal Model Derivation
  - Deriving Transfer Functions From The Small Signal Model
  - Averaged Switch Modeling
- Detailed Examples (All The Algebra)

# Seminar Introduction: Not Discussed

- Models For Discontinuous Conduction Mode
- Control Loop Design
  - Error Amp/Compensator Design
  - Pole-Zero Placement
  - Loop Stability

# Seminar Introduction

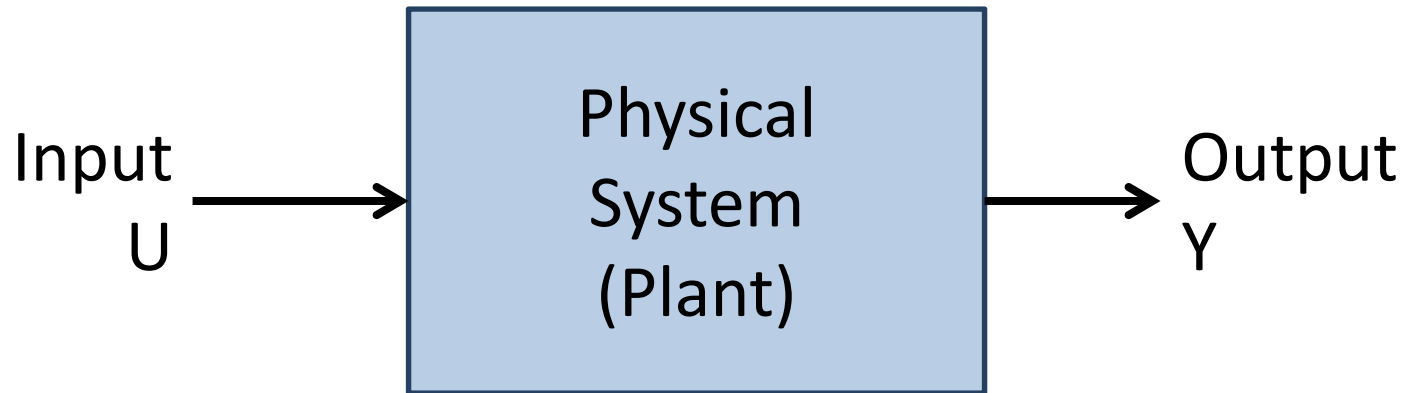
- Much Of This Seminar Is Based On Material From “Fundamentals Of Power Electronics”, 2<sup>nd</sup> Edition, Erickson & Maksimovic, Kluwer Academic Publishers, ISBN 0-7923-7270-0
  - Chapter 7, AC Equivalent Circuit Modeling
  - Chapter 8, Converter Transfer Functions



# Seminar Introduction

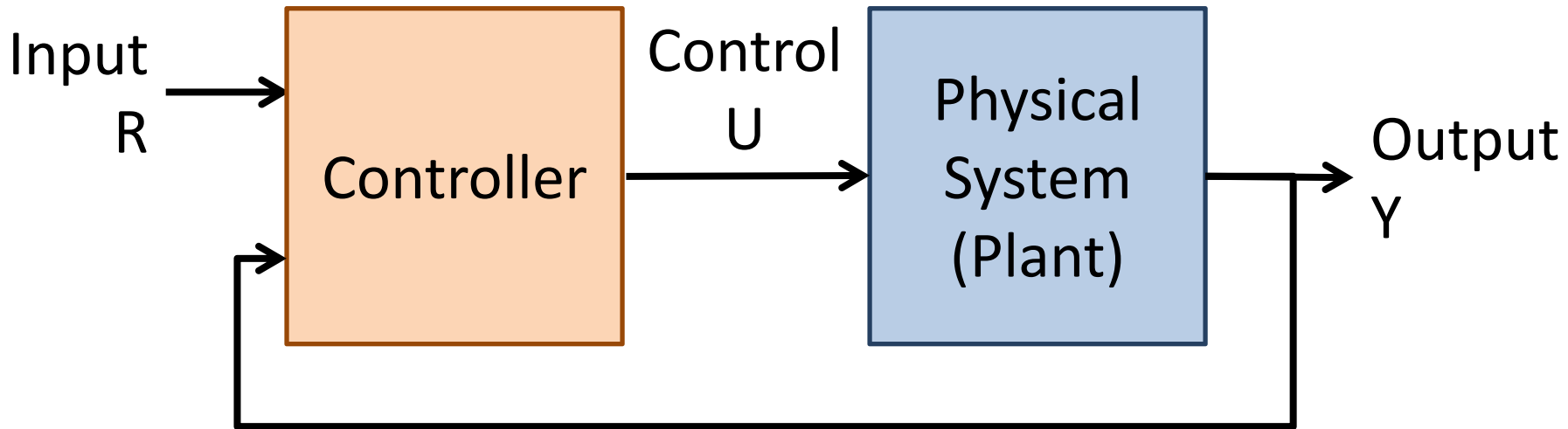
- Timing
  - 90 Minutes Presentation
  - 30 Minute Break
  - 90 Minutes Presentation
- Ask Questions At Any Time
- Fill Out The Survey Form!

# Controls 101 Review



Issue: The Actual Output  
Is Not The Desired Output

# Feedback



Goals:

- Make the output track the reference input
- Reject disturbances

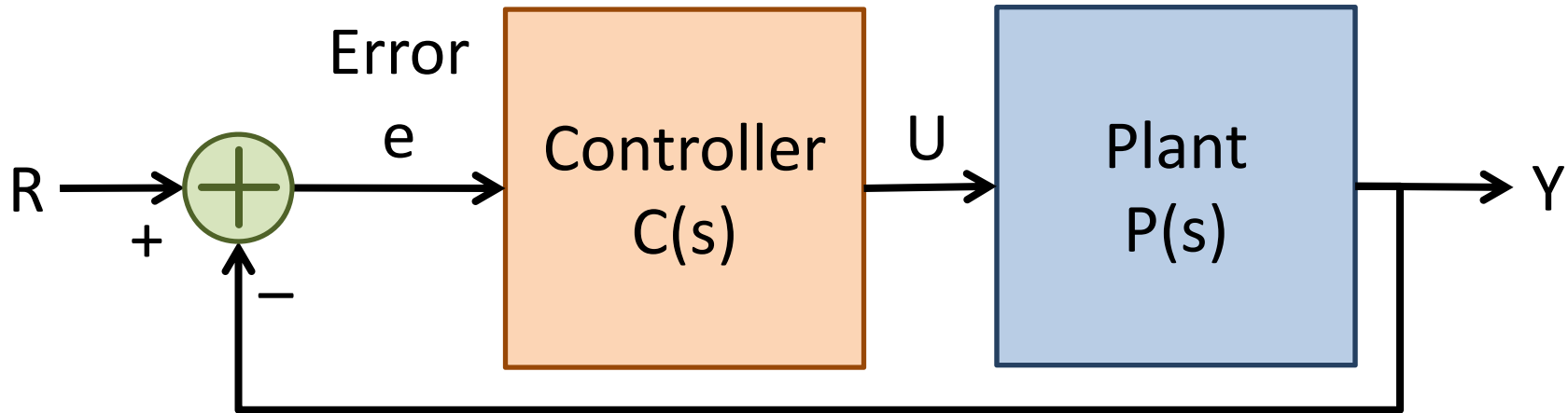
Requirement: Remain stable at all times

# Stability

- Bounded Input-Bounded Output (BIBO)
  - Finite input results in finite output
- Lyapunov
  - System has an equilibrium point or points
  - Small disturbance from equilibrium results in small change in output
  - Exponential: Output change decays in time



# Design And Analysis



- Time domain solutions too tedious
- Transform to frequency or s domain

$$Y(s) = \frac{P(s) \cdot C(s)}{1 + P(s) \cdot C(s)} \cdot R(s)$$

$$H(s) = \frac{Y(s)}{R(s)} = \frac{P(s) \cdot C(s)}{1 + P(s) \cdot C(s)}$$

# Design And Analysis

## Stable Means

This Term Can Never Be Equal To Zero

$H(s)$  Has No Poles In RHP

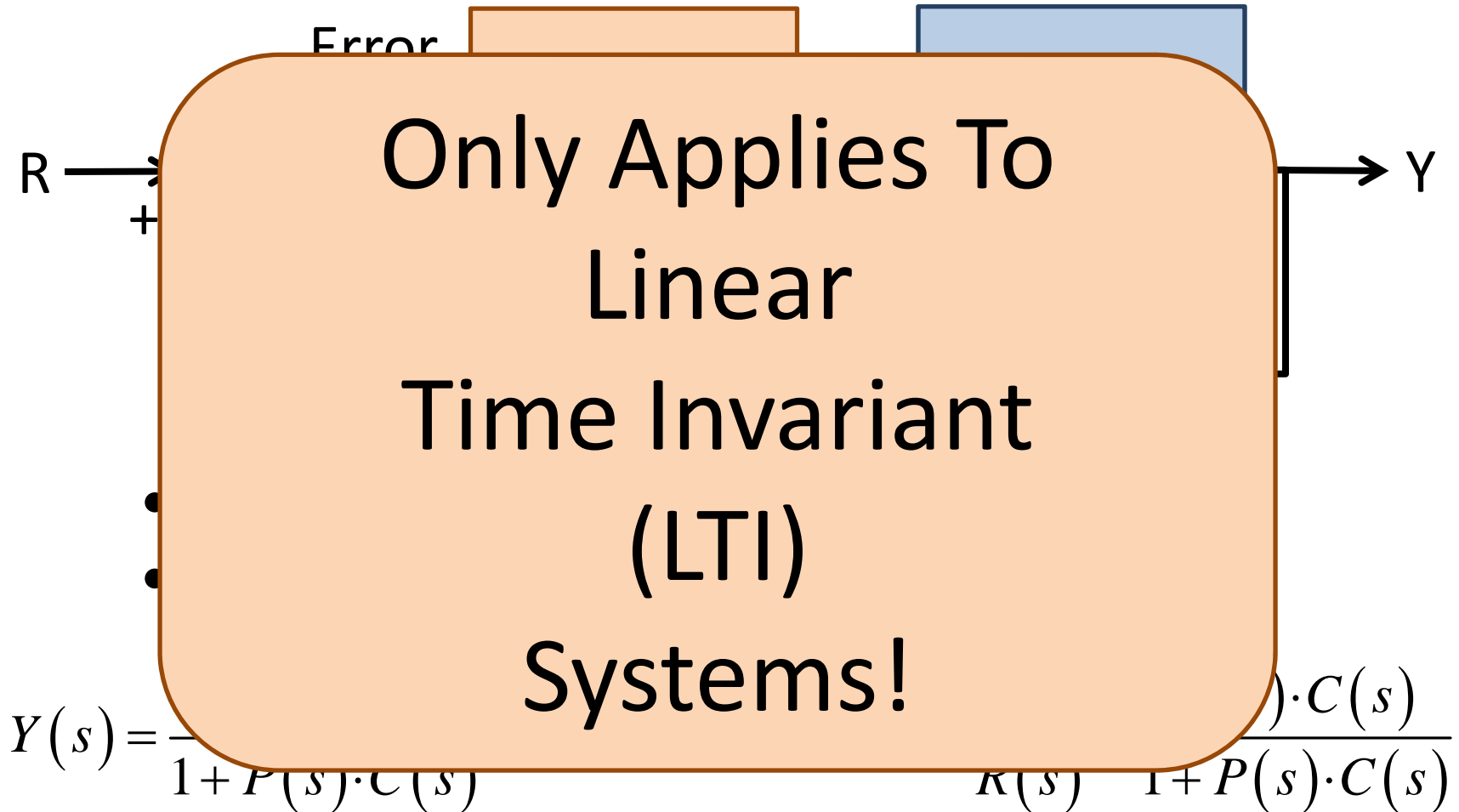
No RHP Poles In  $P(s)$  Or  $C(s)$

Cancelled By Matching RHP Zeroes

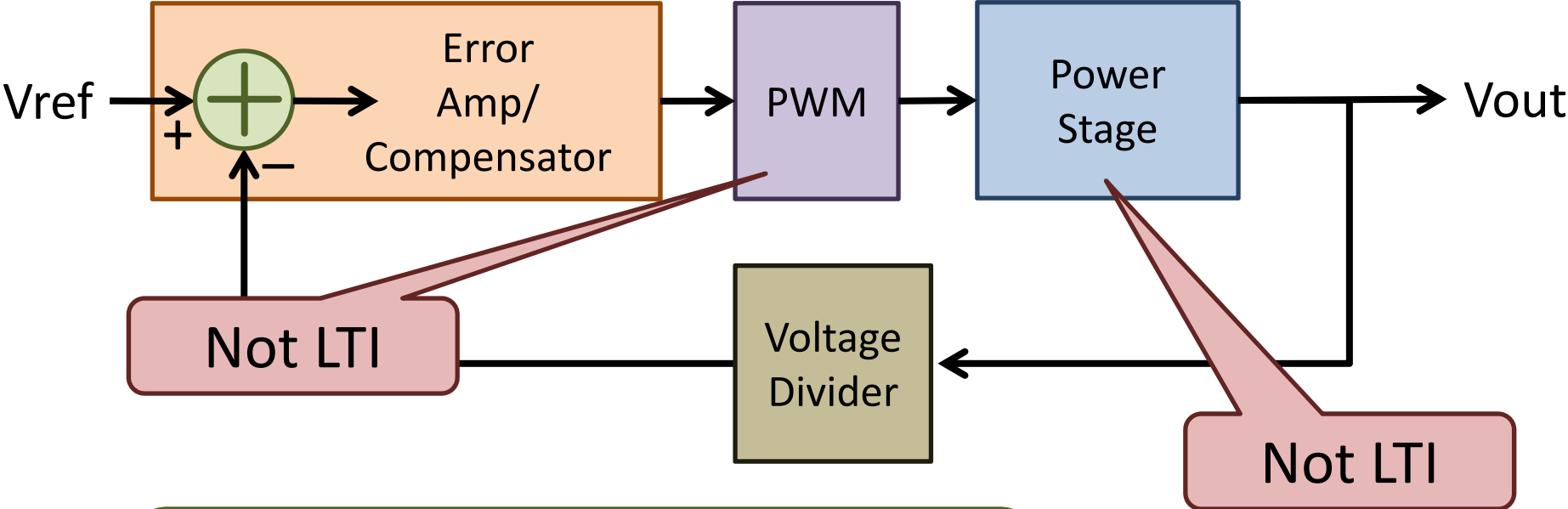
$$Y(s) = \frac{P(s) \cdot C(s)}{1 + P(s) \cdot C(s)} \cdot R(s)$$

$$H(s) = \frac{Y(s)}{R(s)} = \frac{P(s) \cdot C(s)}{1 + P(s) \cdot C(s)}$$

# Design And Analysis

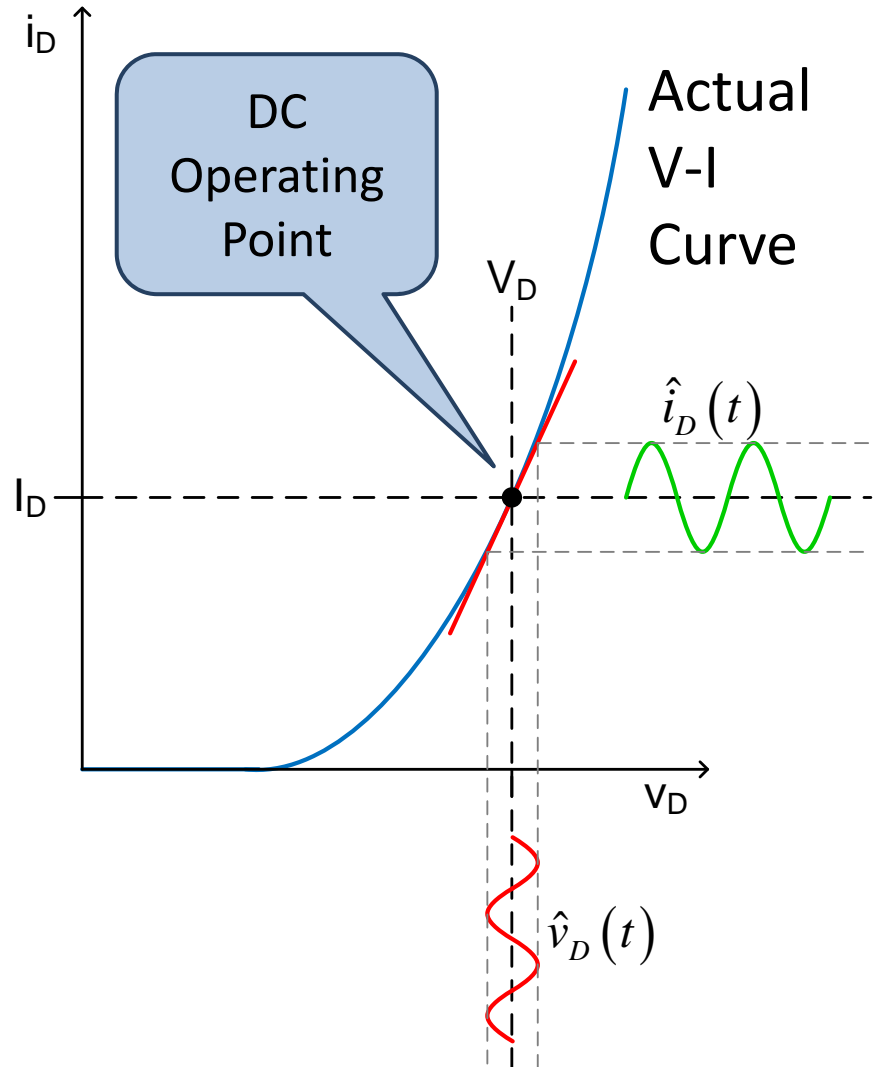
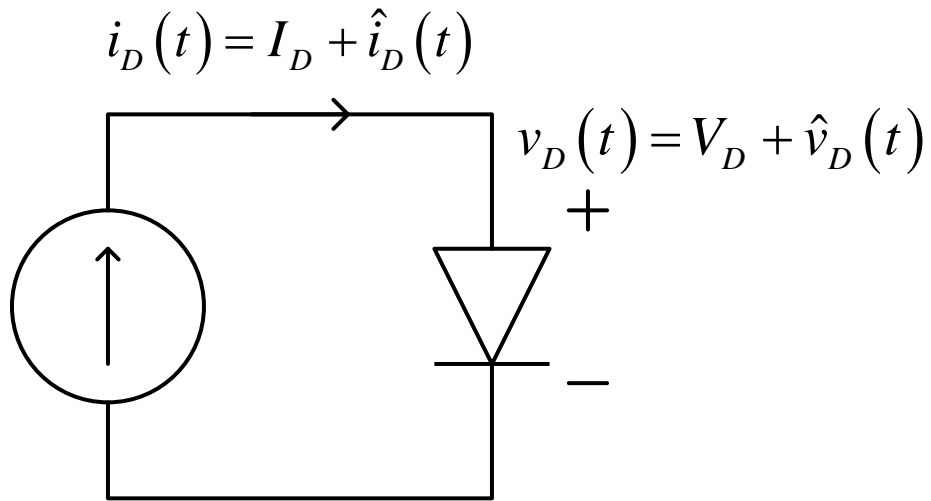


# Power Supply Model

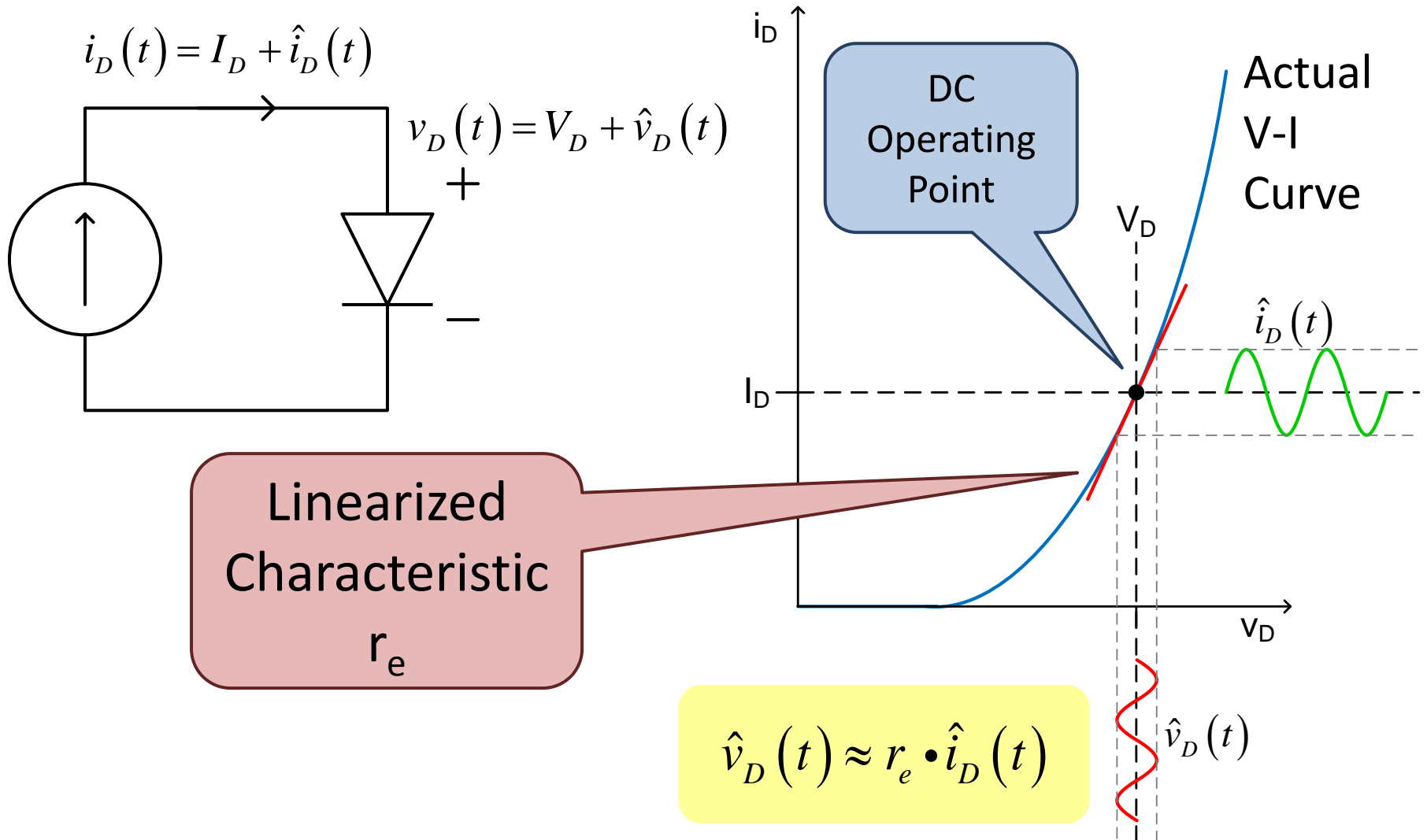


We Need Circuit Models Valid In The s-Domain

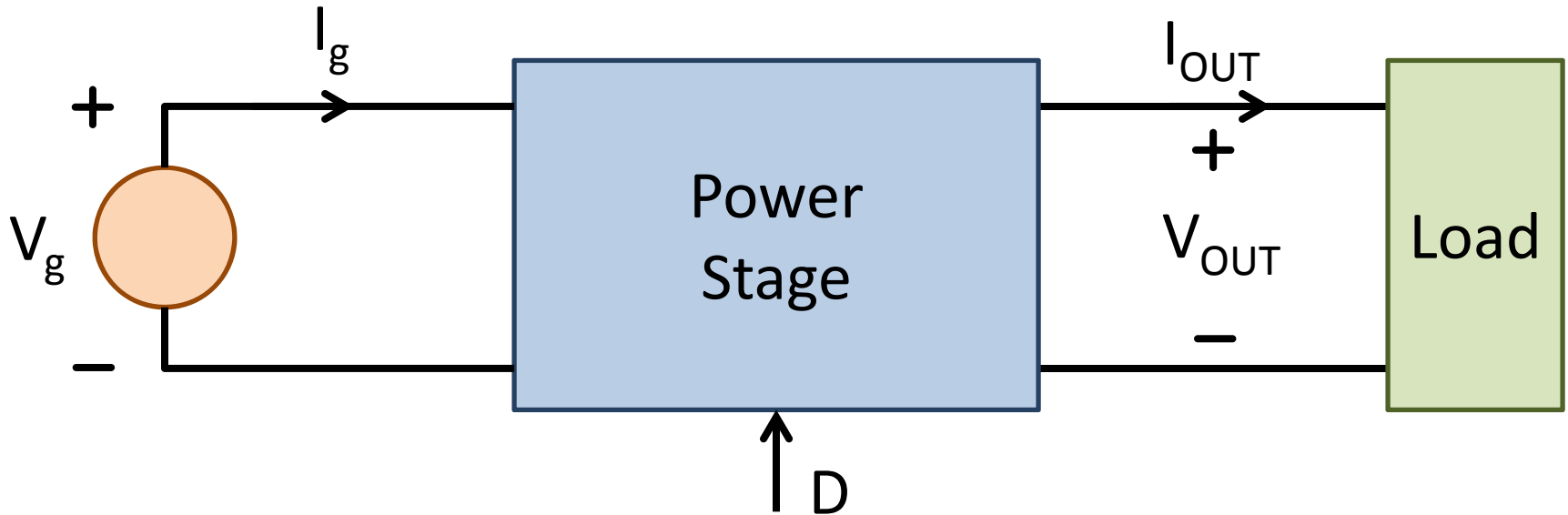
# Small Signal Modeling



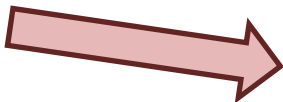
# Small Signal Modeling



# DC Model



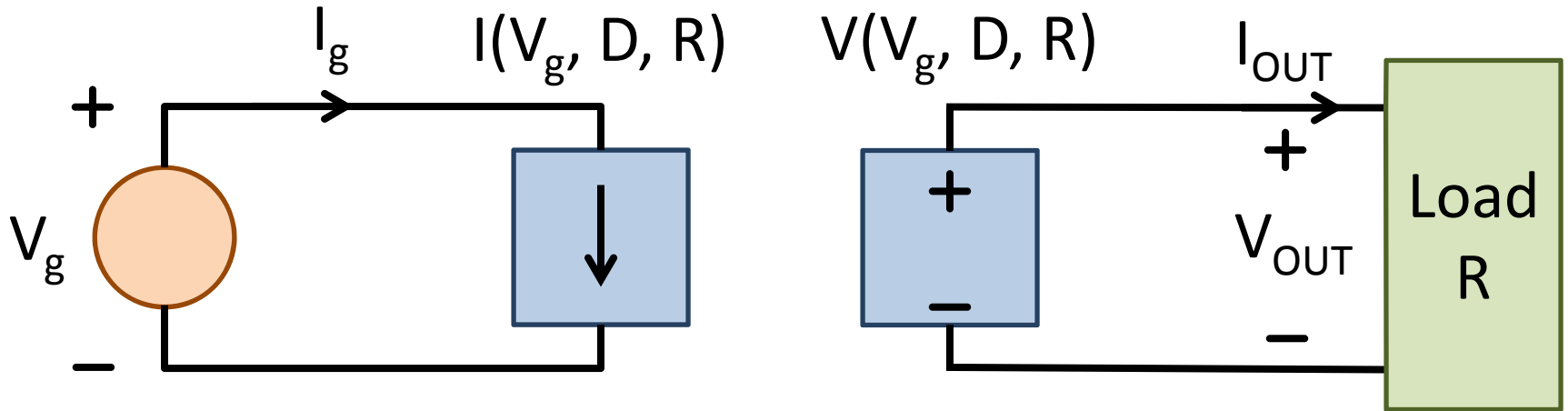
## Inputs

- Input Voltage,  $V_g$
  - Control Input,  $D$
  - Load
- 
- Resistance,  $R$
  - Current,  $I_{LOAD}$
  - Voltage,  $V_{LOAD}$

## Outputs

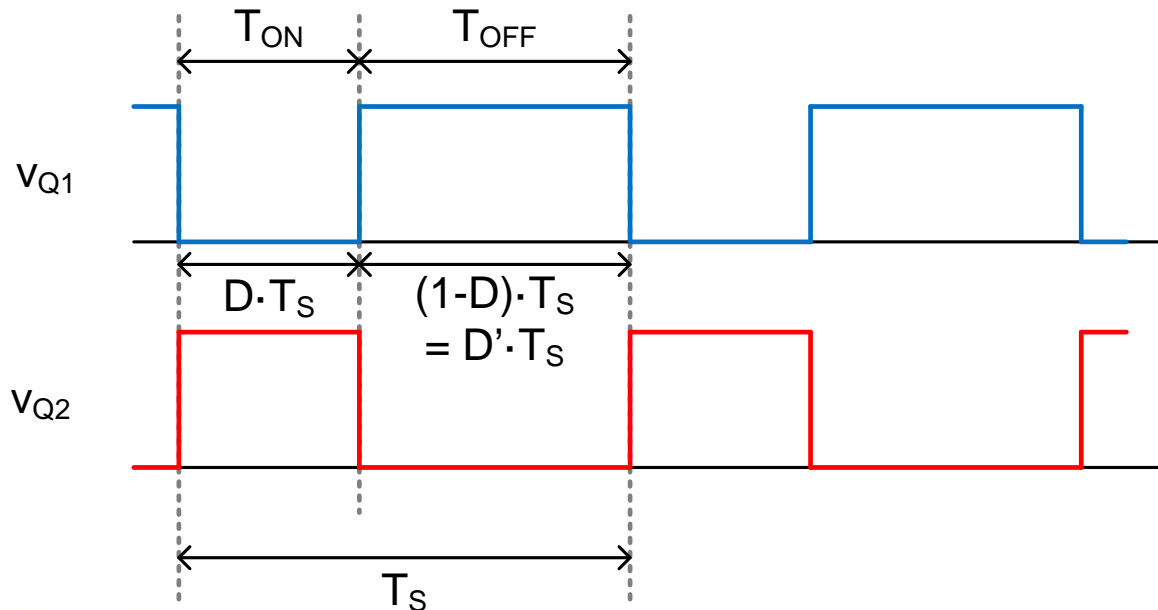
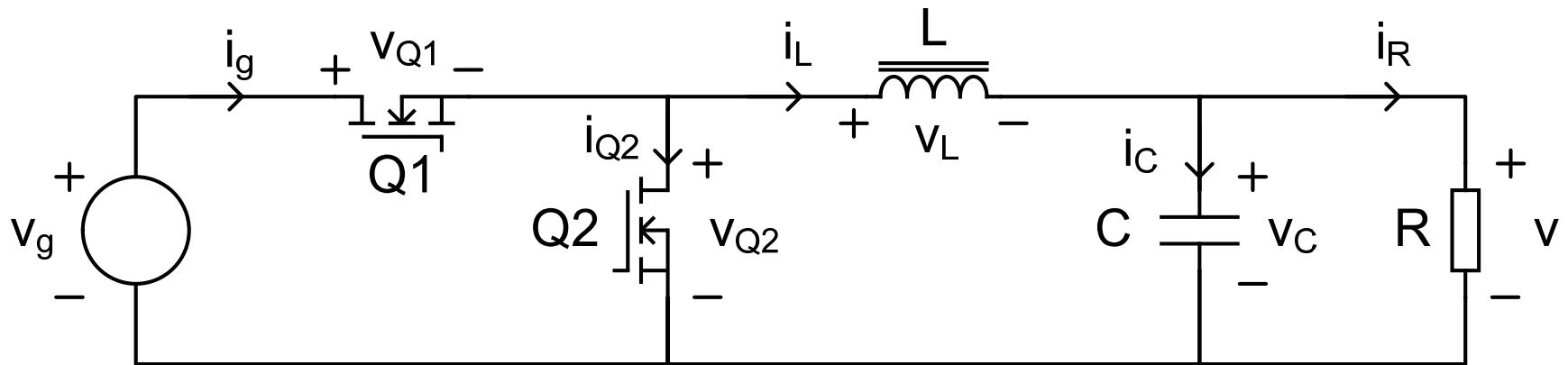
- Output Voltage,  $V_{OUT}$
- Input Current,  $I_g$

# DC Model





# Buck Converter DC Model



# Solving The Output Voltage

$$\langle v_L(t) \rangle_{T_S} = \langle v_L(t) \rangle = \frac{1}{T_S} \cdot \int_0^{T_S} v_L(t) dt = 0$$

Inductor Volt-Second Balance

$$\frac{1}{T_S} \cdot \int_0^{T_S} v_L(t) dt = \frac{1}{T_S} \left( \int_0^{T_{on}} v_L(t) dt + \int_{T_{ON}}^{T_S} v_L(t) dt \right) = 0$$

$$\int_0^{T_{on}} (v_g - v_C(t)) dt + \int_{T_{ON}}^{T_S} (-v_C(t)) dt = 0$$

Small Ripple Approximation

$$v_g(t) = V_g + \tilde{v}_g(t)$$

$$|\tilde{v}_g(t)| \ll V_g$$

$$v_g(t) = V_g + \tilde{v}_g(t) \approx V_g$$

$$v_C(t) = V_C + \tilde{v}_C(t)$$

$$|\tilde{v}_C(t)| \ll V_C$$

$$v_C(t) = V_C + \tilde{v}_C(t) \approx V_C$$

# Solving The Output Voltage

$$\int_0^{T_{on}} (V_g - V_C) dt + \int_{T_{ON}}^{T_S} (-V_C) dt = 0$$

$$(V_g - V_C) \cdot T_{ON} - V_C \cdot (T_S - T_{ON}) = 0$$

$$(V_g - V_C) \cdot D \cdot T_S - V_C \cdot (T_S - D \cdot T_S) = 0$$

$$(V_g - V_C) \cdot D - V_C \cdot (1 - D) = 0$$

$$D \cdot V_g - D \cdot V_C - V_C + D \cdot V_C = 0$$

$$D \cdot V_g - V_C = 0$$

$$V_C = D \cdot V_g$$

# Solving The Inductor Current

$$\langle i_C(t) \rangle_{T_S} = \langle i_C(t) \rangle = 0$$

Capacitor Charge Balance

$$\frac{1}{T_S} \cdot \int_0^{T_S} i_C(t) dt = \frac{1}{T_S} \cdot \left( \int_0^{T_{on}} i_C(t) dt + \int_{T_{ON}}^{T_S} i_C(t) dt \right) = 0$$

$$\int_0^{T_{on}} i_C(t) dt + \int_{T_{ON}}^{T_S} i_C(t) dt = 0$$

$$\int_0^{T_{on}} \left( i_L(t) - \frac{1}{R} \cdot v_C(t) \right) dt + \int_{T_{ON}}^{T_S} \left( i_L(t) - \frac{1}{R} \cdot v_C(t) \right) dt = 0$$

$$\int_0^{T_S} \left( i_L(t) - \frac{1}{R} \cdot v_C(t) \right) dt = 0$$

# Solving The Inductor Current

$$v_C(t) \approx V_C$$

$$i_L(t) = I_L + \tilde{i}_L(t)$$

$$|\tilde{i}_L(t)| \ll I_L$$

$$i_L(t) = I_L + \tilde{i}_L(t) \approx I_L$$

Small Ripple Approximation

$$\int_0^{T_s} \left( I_L - \frac{1}{R} \cdot V_C \right) dt = 0$$

$$\left( I_L - \frac{1}{R} \cdot V_C \right) \cdot T_s = 0$$

$$I_L - \frac{1}{R} \cdot V_C = 0$$

$$I_L = \frac{1}{R} \cdot V_C$$

# Solving The Input Current

$$\langle i_g(t) \rangle_{T_S} = \langle i_g(t) \rangle = I_g = \frac{1}{T_S} \cdot \int_0^{T_S} i_g(t) dt$$

$$I_g = \frac{1}{T_S} \cdot \left( \int_0^{T_{ON}} i_g(t) dt + \int_0^{T_{OFF}} i_g(t) dt \right)$$

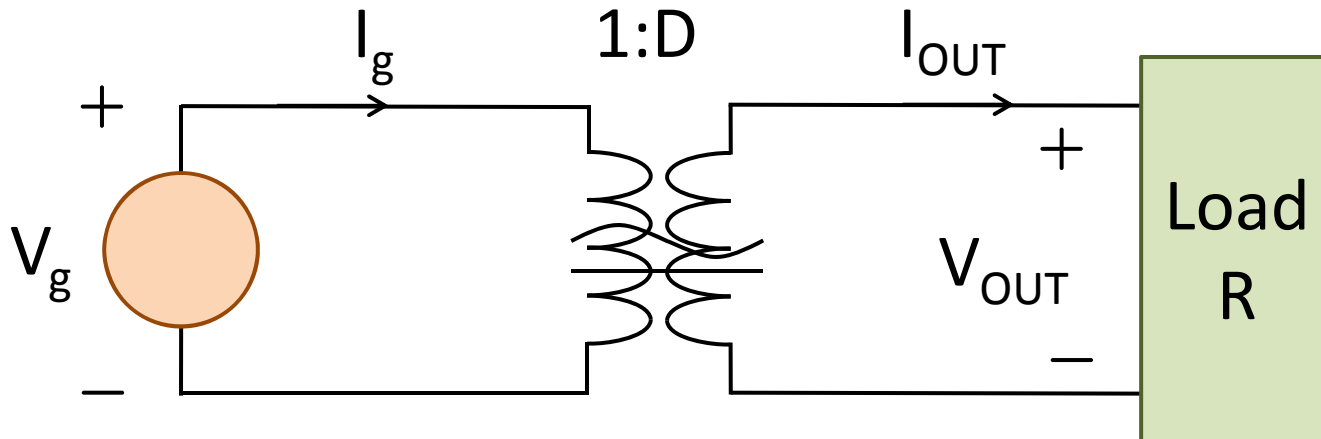
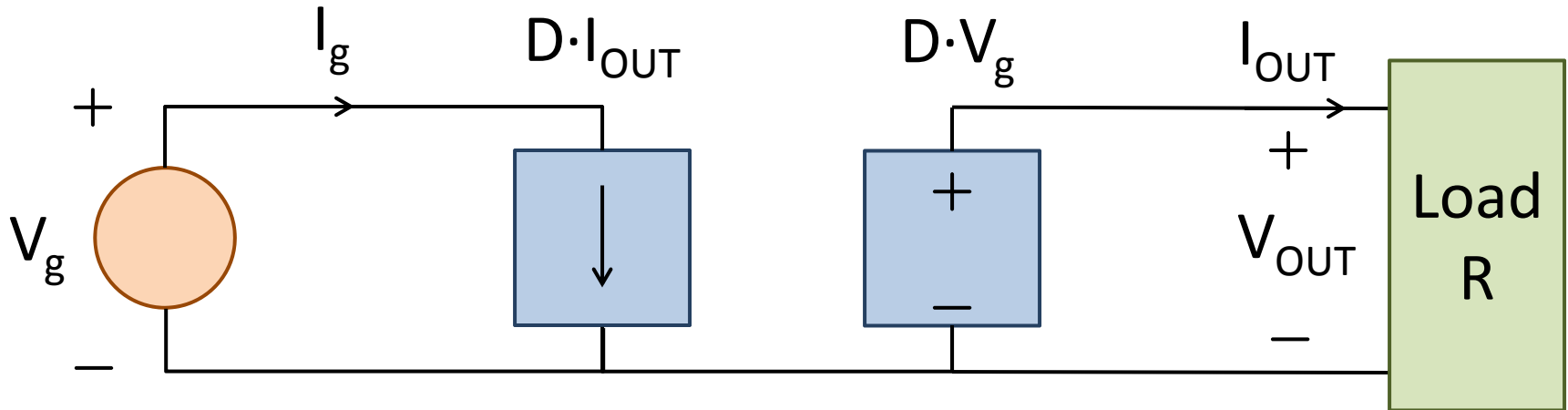
$$= \frac{1}{T_S} \cdot \left( \int_0^{T_{ON}} i_g(t) dt + \int_0^{T_{OFF}} 0 dt \right) = \frac{1}{T_S} \cdot \int_0^{T_{ON}} i_g(t) dt$$

$$i_g(t) = i_L(t) \approx I_L$$

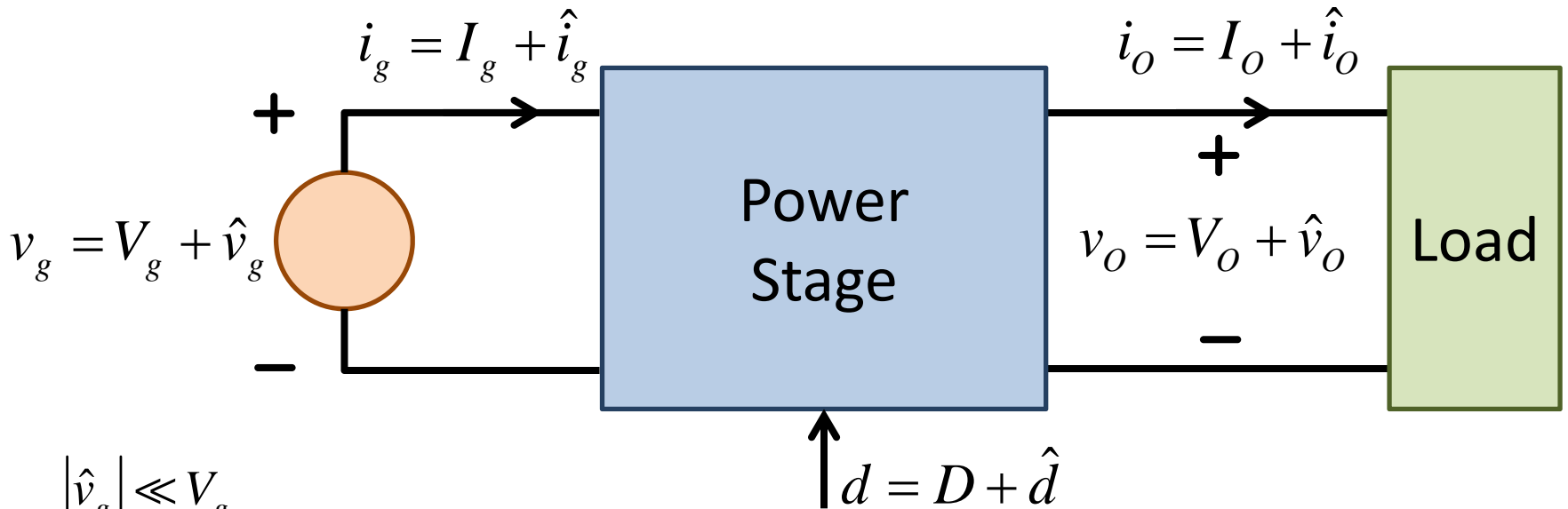
From The  
Small Ripple  
Approximation

$$I_g = \frac{1}{T_S} \cdot I_L \cdot T_{ON} = \frac{1}{T_S} \cdot I_L \cdot D \cdot T_S = D \cdot I_L = D \cdot \frac{1}{R} \cdot V_C = D \cdot I_{OUT}$$

# Buck Converter DC Model



# AC (Small Signal) Modeling



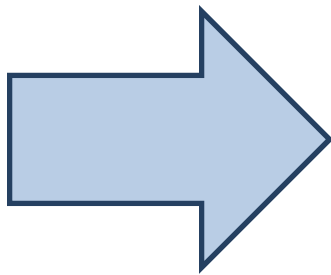
$$|\hat{v}_g| \ll V_g$$

$$|\hat{i}_g| \ll I_g$$

$$|\hat{v}_o| \ll V_o$$

$$|\hat{i}_o| \ll I_o$$

$$|\hat{d}| \ll D$$

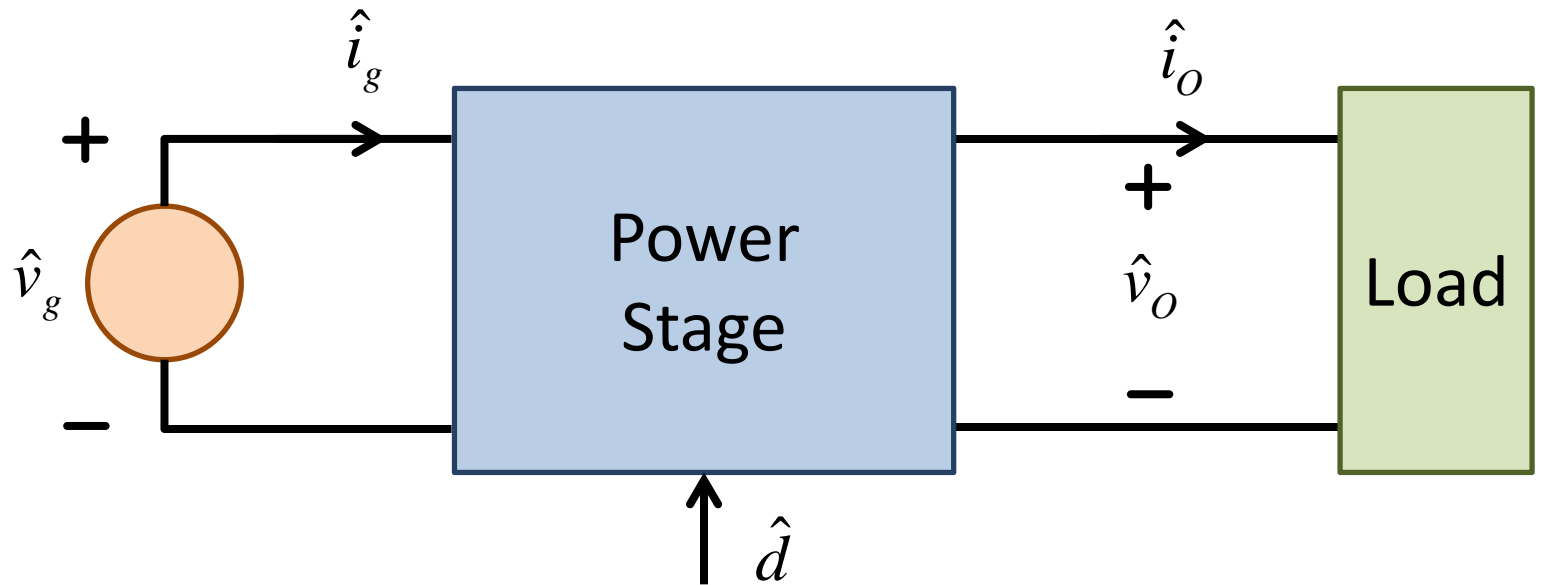


Small  
Signal  
Modeling

How Small is Small?  
Small Enough The  
System Remains  
Linear



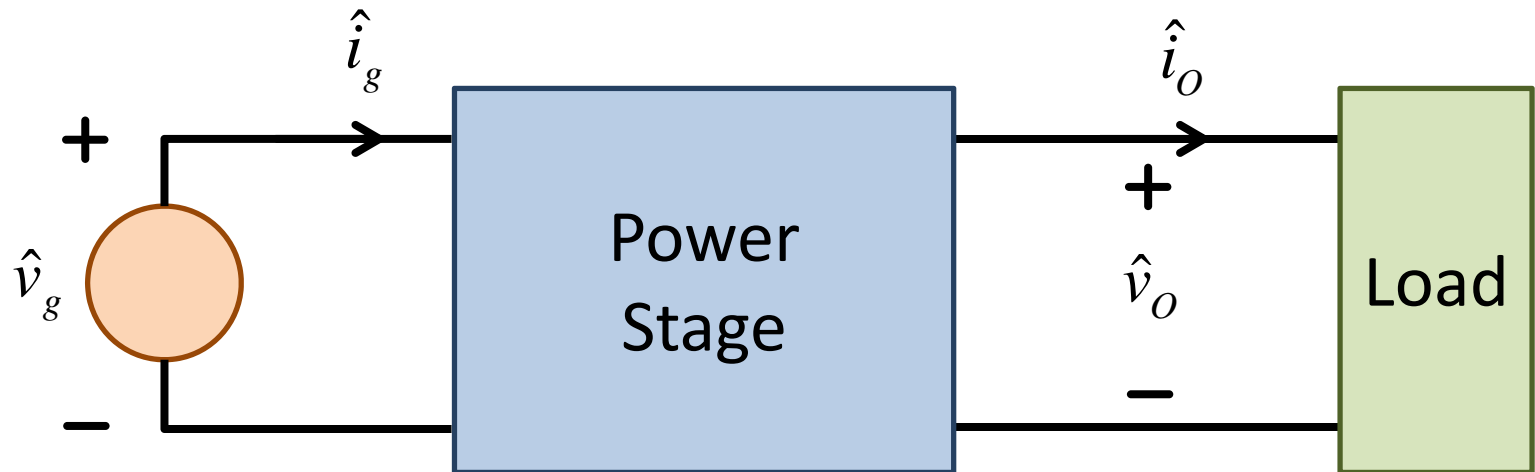
# AC Modeling



Control To Output  
Transfer Function

$$G_{vd} = \left. \frac{\hat{v}_o}{\hat{d}} \right|_{\hat{v}_g=0}$$

# AC Modeling



Audio-susceptibility

Input Impedance

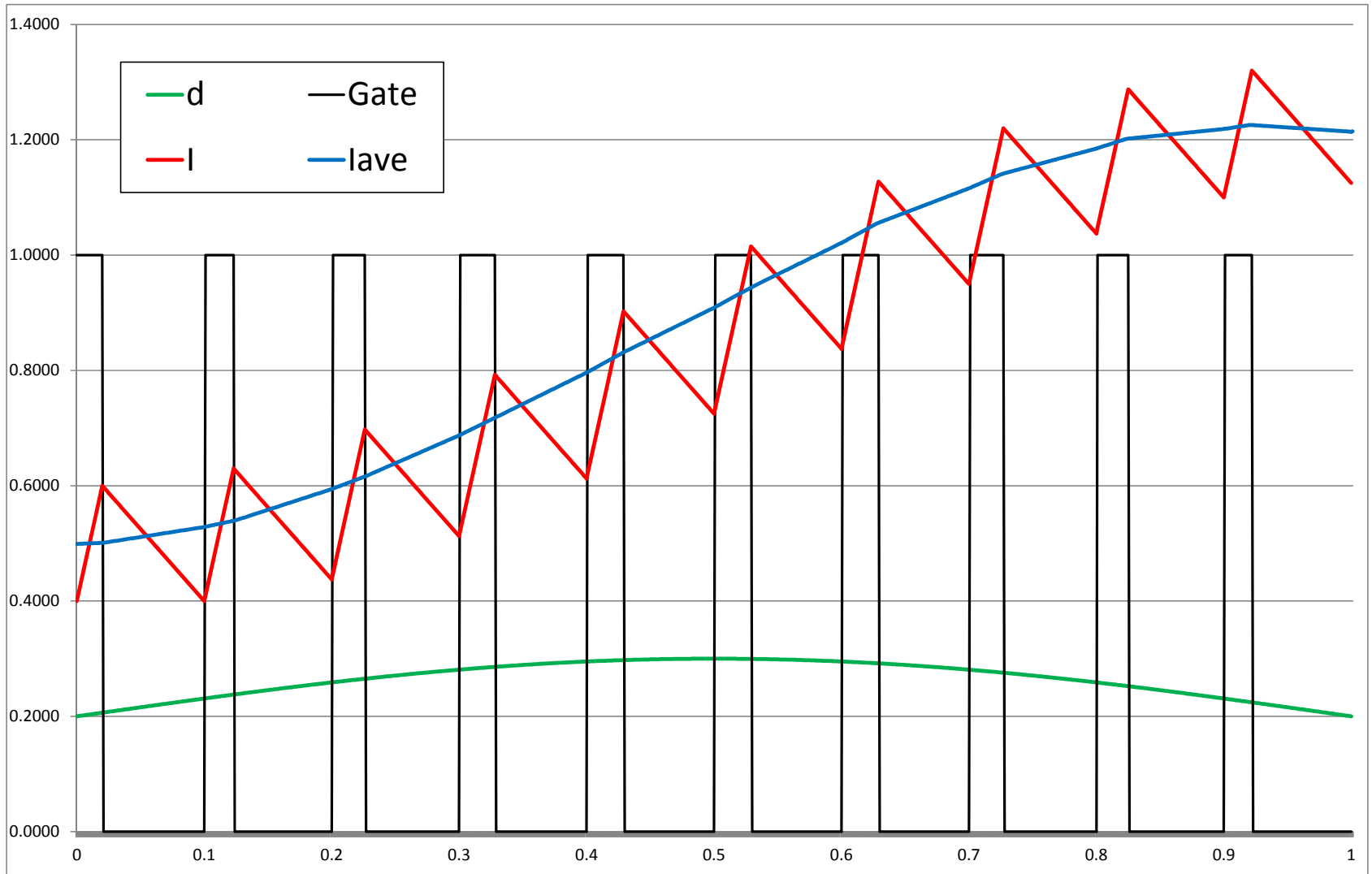
Output Impedance

$$G_{vg} = \left. \frac{\hat{v}_o}{\hat{v}_g} \right|_{\hat{d}=0}$$

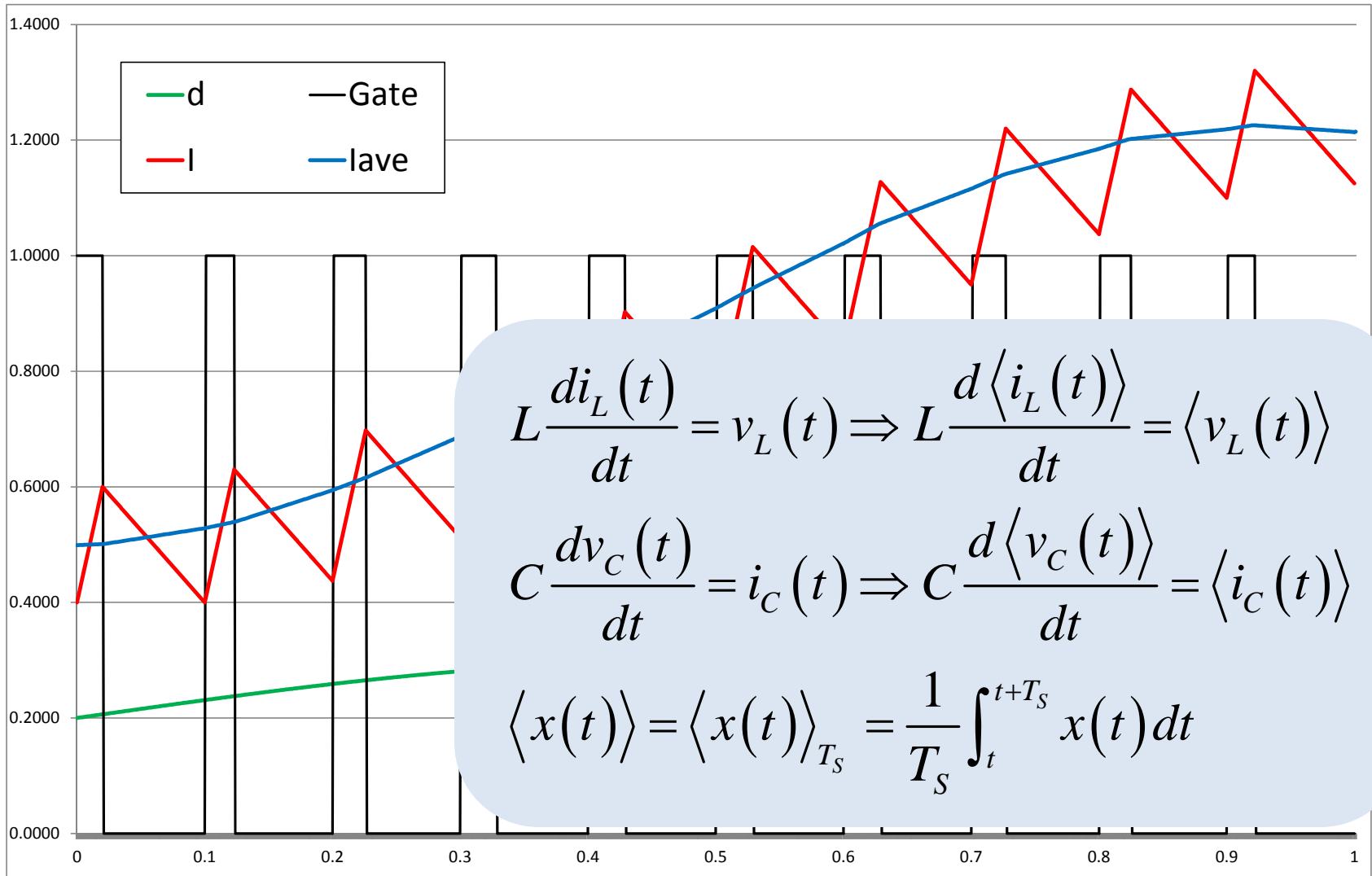
$$Z_i = \left. \frac{\hat{v}_g}{\hat{i}_g} \right|_{\hat{d}=0}$$

$$Z_o = \left. \frac{\hat{v}_o}{\hat{i}_o} \right|_{\hat{d}=0, \hat{v}_g=0}$$

# Averaging



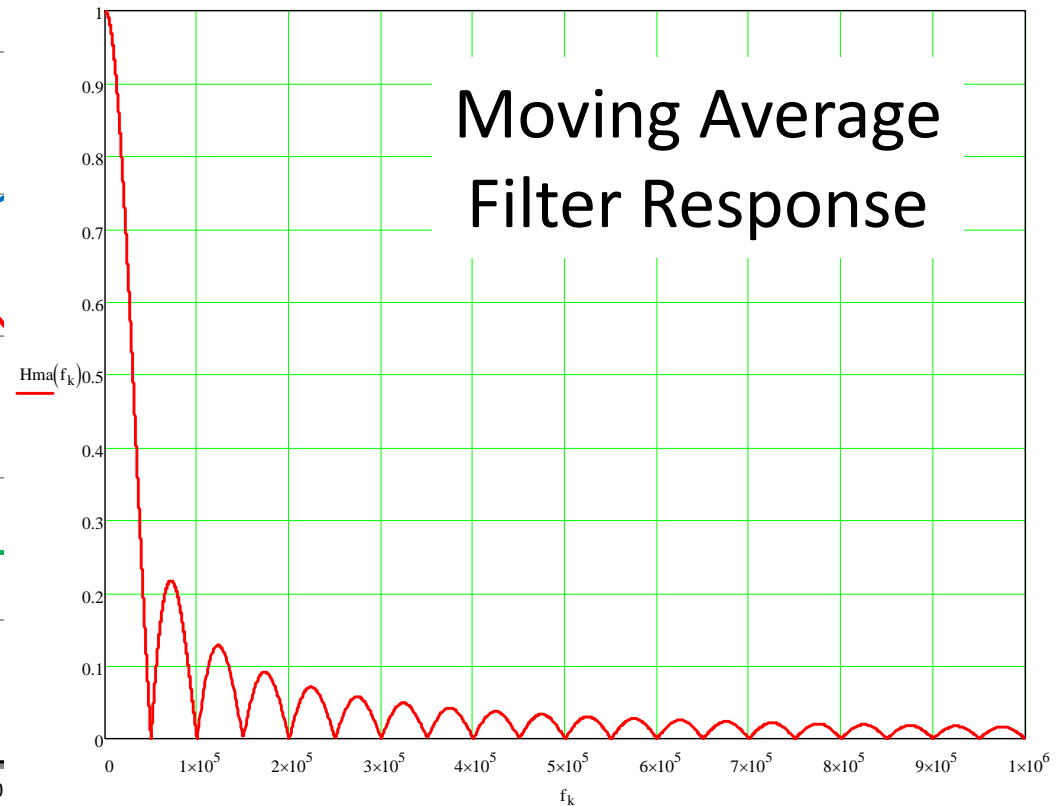
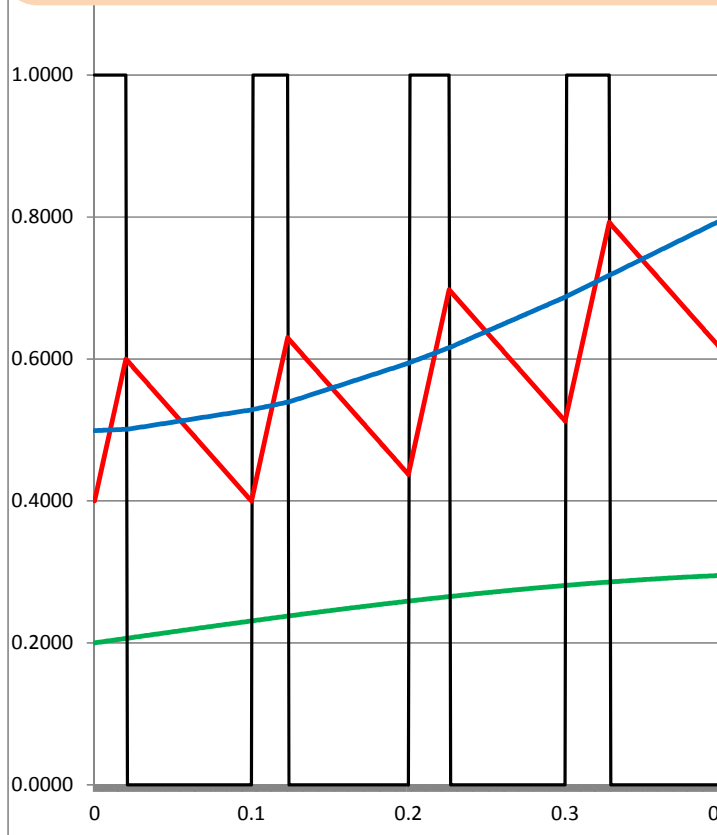
# Averaging



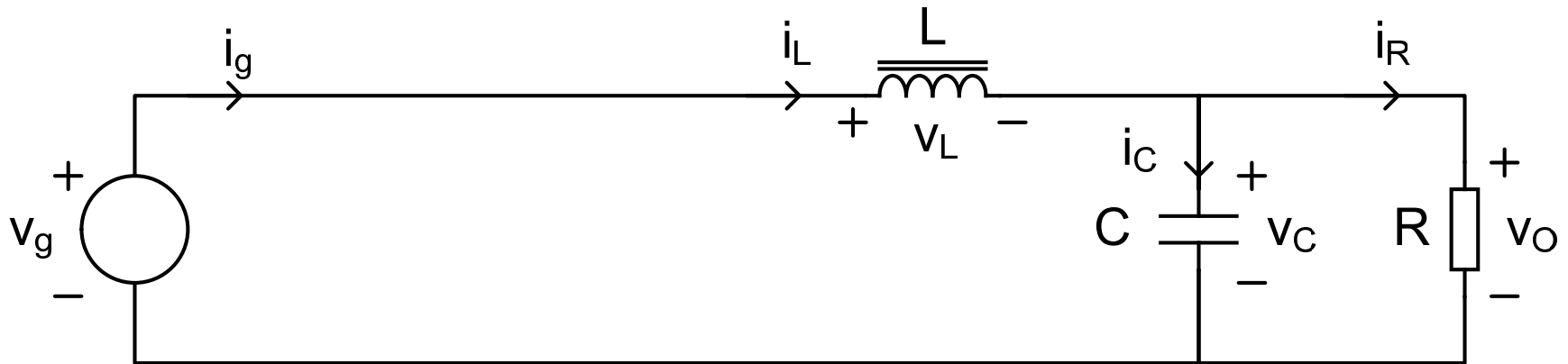
# Another View Of Averaging



$$\langle x(t) \rangle = \langle x(t) \rangle_{T_S} = \frac{1}{T_S} \cdot \int_t^{t+T_S} x(t) dt$$



# Modeling The Buck Converter: On Time

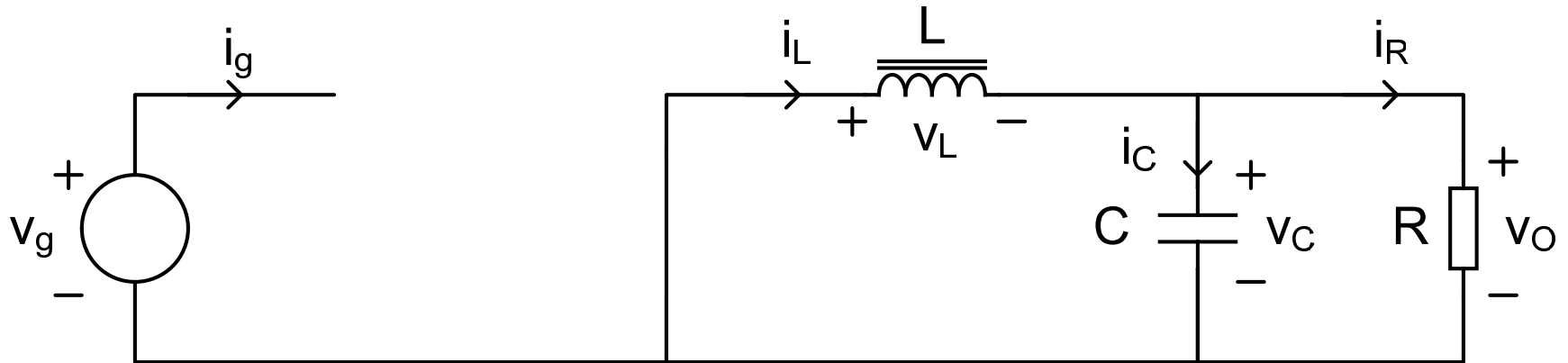


$$v_L(t) = L \frac{di_L(t)}{dt} = v_g(t) - v_O(t) \approx \langle v_g(t) \rangle - \langle v_C(t) \rangle$$

$$i_C(t) = C \frac{dv_C(t)}{dt} = i_L(t) - \frac{1}{R} v_C(t) \approx \langle i_L(t) \rangle - \frac{1}{R} \langle v_C(t) \rangle$$

Small Ripple Approximation

# Modeling The Buck Converter: Off Time



$$v_L(t) = L \frac{di_L(t)}{dt} = -v_C(t) \approx -\langle v_C(t) \rangle$$

$$i_C(t) = C \frac{dv_C(t)}{dt} = i_L(t) - \frac{1}{R} v_C(t) \approx \langle i_L(t) \rangle - \frac{1}{R} \langle v_C(t) \rangle$$

# Averaging The Inductor Voltage

$$\begin{aligned}\langle v_L(t) \rangle &= \frac{1}{T_s} \int_t^{t+T_s} v_L(\tau) d\tau \\ &\approx d(t) \cdot (\langle v_g(t) \rangle - \langle v_C(t) \rangle) + d'(t) \cdot (-\langle v_C(t) \rangle) \\ &= d(t) \cdot (\langle v_g(t) \rangle - \langle v_C(t) \rangle) + (1 - d(t)) \cdot (-\langle v_C(t) \rangle) \\ &= d(t) \cdot \langle v_g(t) \rangle - d(t) \cdot \langle v_C(t) \rangle - \langle v_C(t) \rangle + d(t) \cdot \langle v_C(t) \rangle \\ &= d(t) \cdot \langle v_g(t) \rangle - \langle v_C(t) \rangle\end{aligned}$$

$$\langle v_L(t) \rangle = L \frac{d \langle i_L(t) \rangle}{dt} = d(t) \cdot \langle v_g(t) \rangle - \langle v_C(t) \rangle$$



# Averaging The Capacitor Current

$$\begin{aligned}\langle i_C(t) \rangle &= d(t) \cdot \left( \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle \right) + d'(t) \cdot \left( \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle \right) \\ &= \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle\end{aligned}$$

$$\langle i_C(t) \rangle = C \frac{d \langle v_C(t) \rangle}{dt} = \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle$$

## Averaging The Input Current

$$\begin{aligned}\langle i_g(t) \rangle &= d(t) \cdot \langle i_L(t) \rangle + d'(t) \cdot 0 \\ &= d(t) \cdot \langle i_L(t) \rangle\end{aligned}$$

# Perturb And Linearize

## DC Operating Point

$$V_g \quad V_C = D \cdot V_g$$

$$I_L = \frac{1}{R} \cdot V_C \quad I_g = D \cdot I_L$$

## Input Perturbation

$$\langle v_g(t) \rangle = V_g + \hat{v}_g(t)$$

$$d(t) = D + \hat{d}(t)$$

## Resulting Output Perturbation

$$\langle i_L(t) \rangle = I_L + \hat{i}_L(t)$$

$$\langle v_C(t) \rangle = V_C + \hat{v}_C(t)$$

$$\langle i_g(t) \rangle = I_g + \hat{i}_g(t)$$

## Small Signal Constraint

$$\begin{aligned} |\hat{v}_g(t)| &\ll |V_g| & |\hat{i}_L(t)| &\ll |I_L| \\ |\hat{d}(t)| &\ll |D| & |\hat{v}_C(t)| &\ll |V_C| \\ & & |\hat{i}_g(t)| &\ll |I_g| \end{aligned}$$

# Perturb And Linearize

$$L \frac{d \langle i_L(t) \rangle}{dt} = d(t) \cdot \langle v_g(t) \rangle - \langle v_C(t) \rangle \quad \text{Averaged Differential Equation}$$

Substitute DC Plus Perturbation For Average Values:

$$L \frac{d(I_L + \hat{i}_L(t))}{dt} = (D + \hat{d}(t)) \cdot (V_g + \hat{v}_g(t)) - (V_C + \hat{v}_C(t))$$

Expand:

$$L \frac{dI_L}{dt} + L \frac{d\hat{i}_L(t)}{dt} = D \cdot V_g + D \cdot \hat{v}_g(t) + V_g \cdot \hat{d}(t) + \hat{d}(t) \cdot \hat{v}_g(t) - V_C - \hat{v}_C(t)$$

# Perturb And Linearize

Collect Terms:

DC Terms Equal Zero

$$L \frac{dI_L}{dt} + L \frac{d\hat{i}_L(t)}{dt} = D \cdot V_g - V_C$$

$$+ D \cdot \hat{v}_g(t) + V_g \cdot \hat{d}(t) - \hat{v}_C(t)$$

$$+ \hat{d}(t) \cdot \hat{v}_g(t)$$

Discard 2<sup>nd</sup> Order Terms

This Leaves A First Order Equation:

$$L \frac{d\hat{i}_L(t)}{dt} = + D \cdot \hat{v}_g(t) + V_g \cdot \hat{d}(t) - \hat{v}_C(t)$$

# Perturb And Linearize

$$C \frac{d\langle v_C(t) \rangle}{dt} = \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle \quad \text{Averaged Differential Equation}$$

Substitute DC Plus Perturbation For Average Values:

$$C \frac{d(V_C + \hat{v}_C(t))}{dt} = I_L + \hat{i}_L(t) - \frac{1}{R} \cdot (V_C + \hat{v}_C(t))$$

Expand:

$$C \frac{dV_C}{dt} + C \frac{d\hat{v}_C(t)}{dt} = I_L - \frac{1}{R} \cdot V_C + \hat{i}_L(t) - \frac{1}{R} \cdot \hat{v}_C(t)$$

DC Terms Equal Zero

$$C \frac{d\hat{v}_C(t)}{dt} = \hat{i}_L(t) - \frac{1}{R} \cdot \hat{v}_C(t)$$

# Perturb And Linearize

$$\langle i_g(t) \rangle = d(t) \cdot \langle i_L(t) \rangle$$

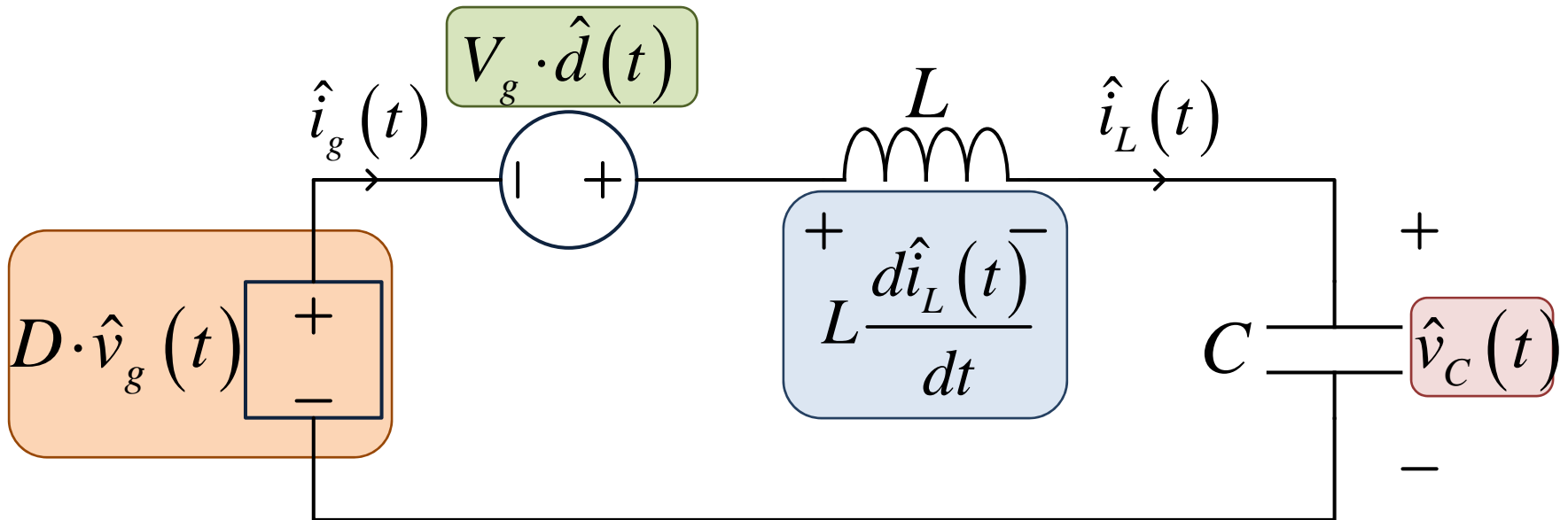
$$\begin{aligned} I_g + \hat{i}_g(t) &= (D + \hat{d}(t)) \cdot (I_L + \hat{i}_L(t)) \\ &= D \cdot I_L + D \cdot \hat{i}_L(t) + I_L \cdot \hat{d}(t) + \hat{d}(t) \cdot \hat{i}_L(t) \end{aligned}$$

$$\hat{i}_g(t) = D \cdot \hat{i}_L(t) + I_L \cdot \hat{d}(t) + \cancel{\hat{d}(t) \cdot \hat{i}_L(t)}$$

$$\hat{i}_g(t) = D \cdot \hat{i}_L(t) + I_L \cdot \hat{d}(t)$$

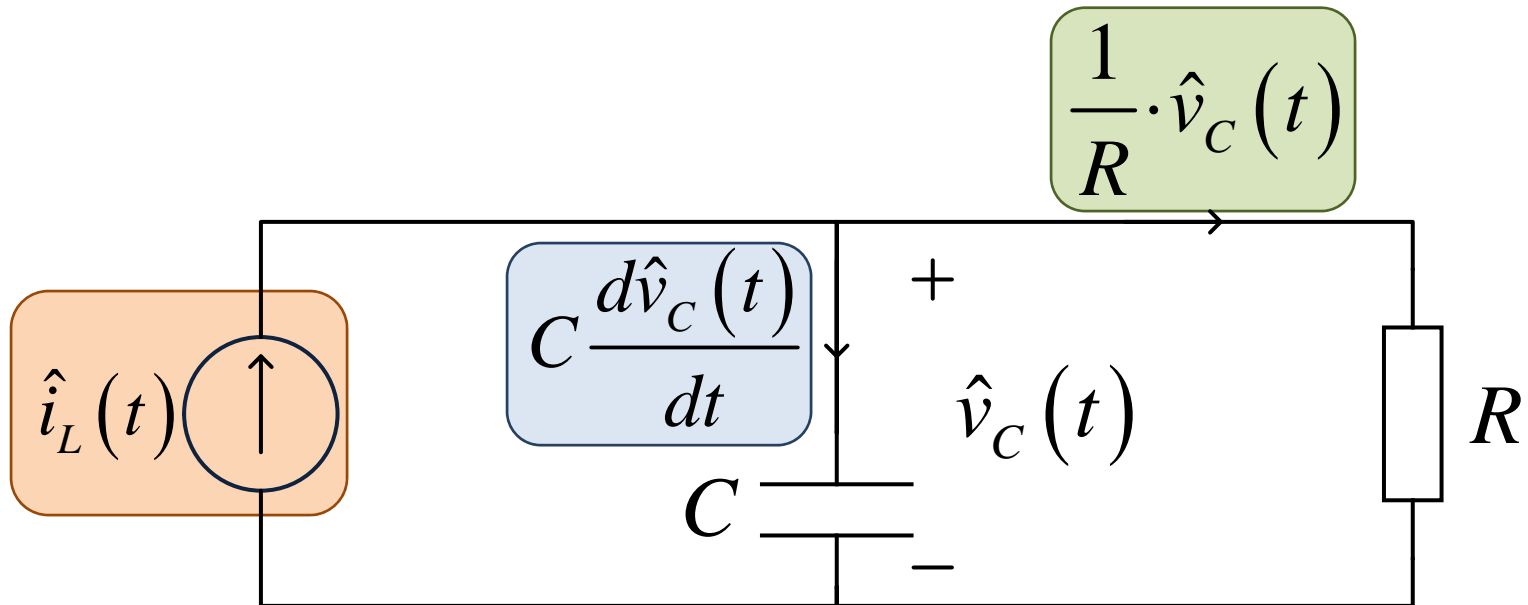
# Construct The Model

$$L \frac{d\hat{i}_L(t)}{dt} = + D \cdot \hat{v}_g(t) + V_g \cdot \hat{d}(t) - \hat{v}_C(t)$$



# Construct The Model

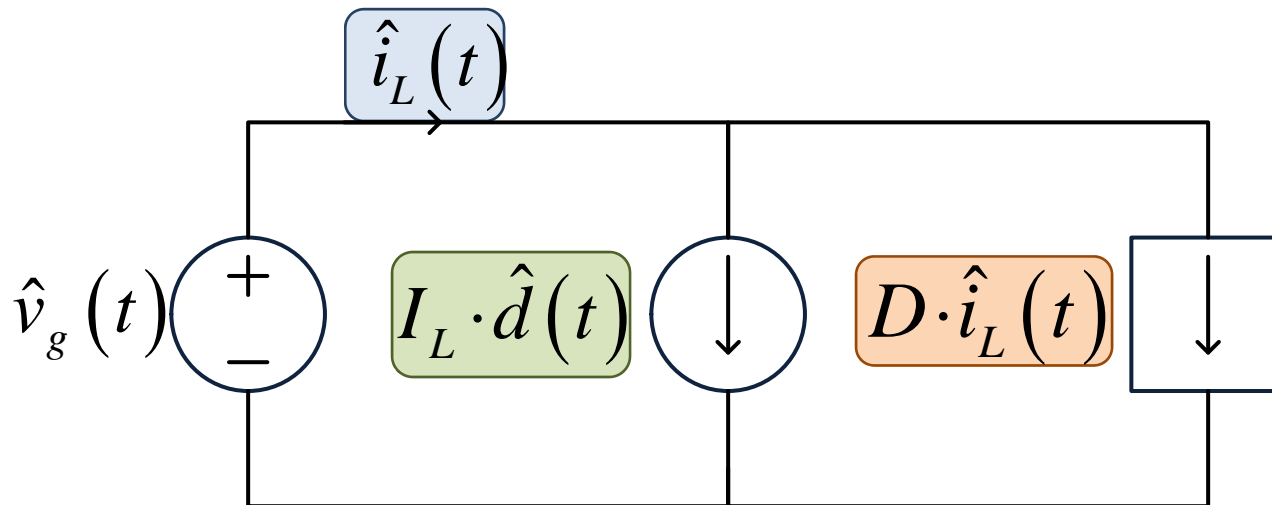
$$C \frac{d\hat{v}_C(t)}{dt} = \hat{i}_L(t) - \frac{1}{R} \cdot \hat{v}_C(t)$$



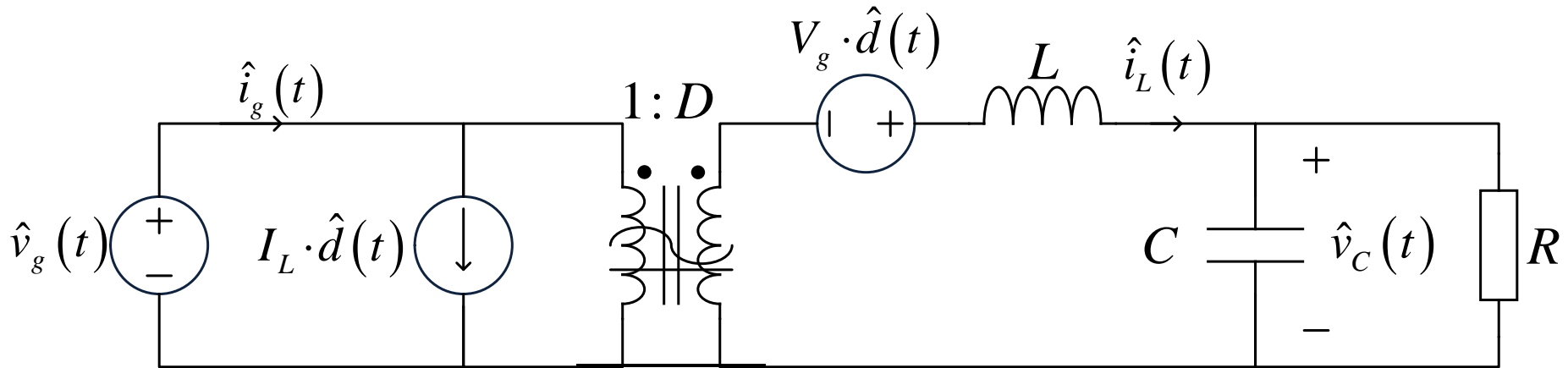
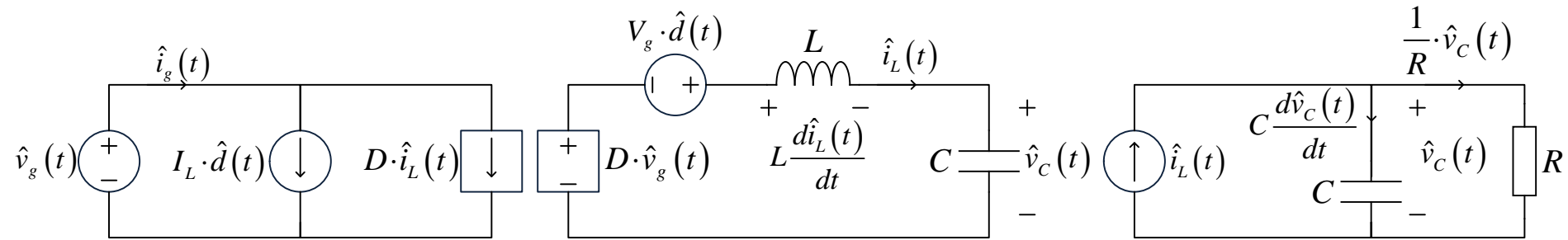


# Construct The Model

$$\hat{i}_g(t) = D \cdot \hat{i}_L(t) + I_L \cdot \hat{d}(t)$$

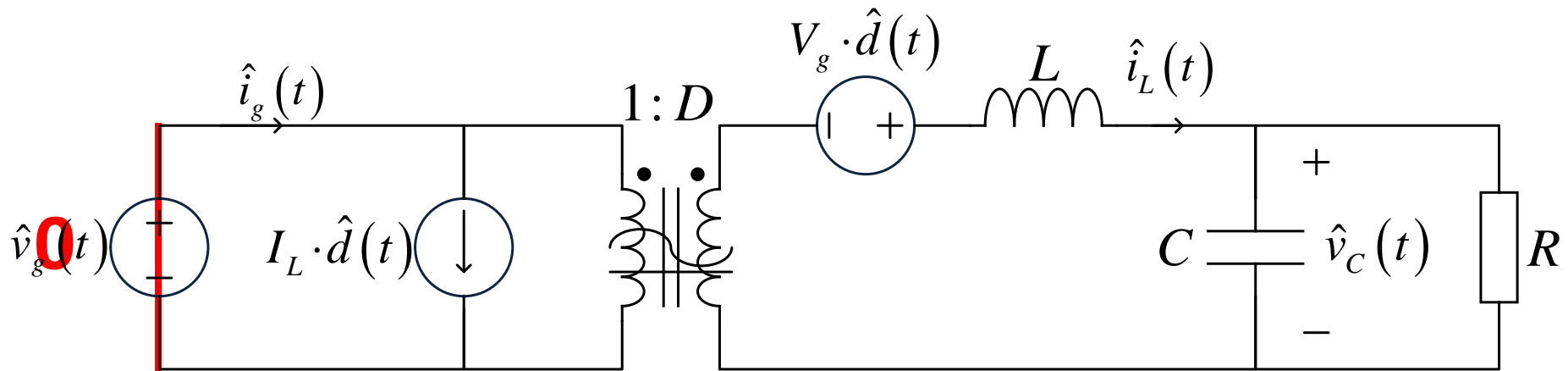


# Construct The Model

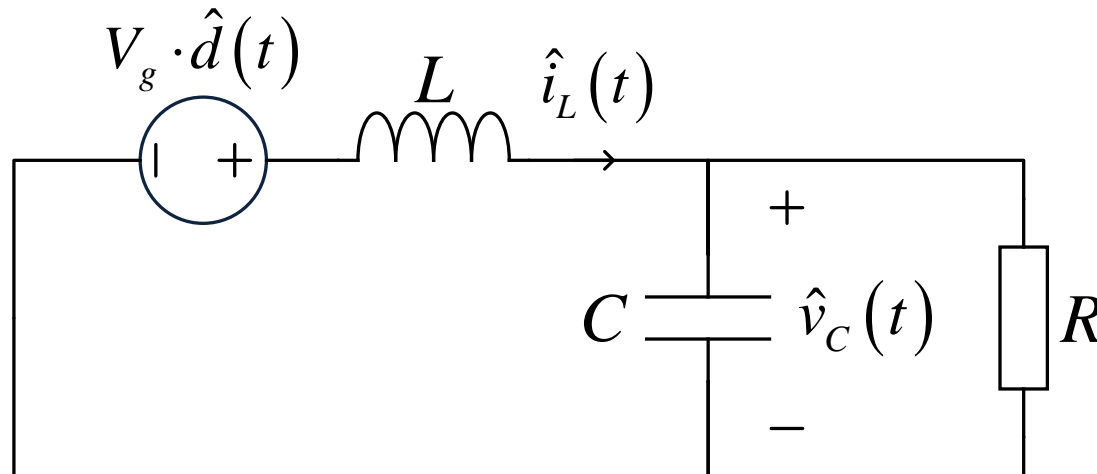
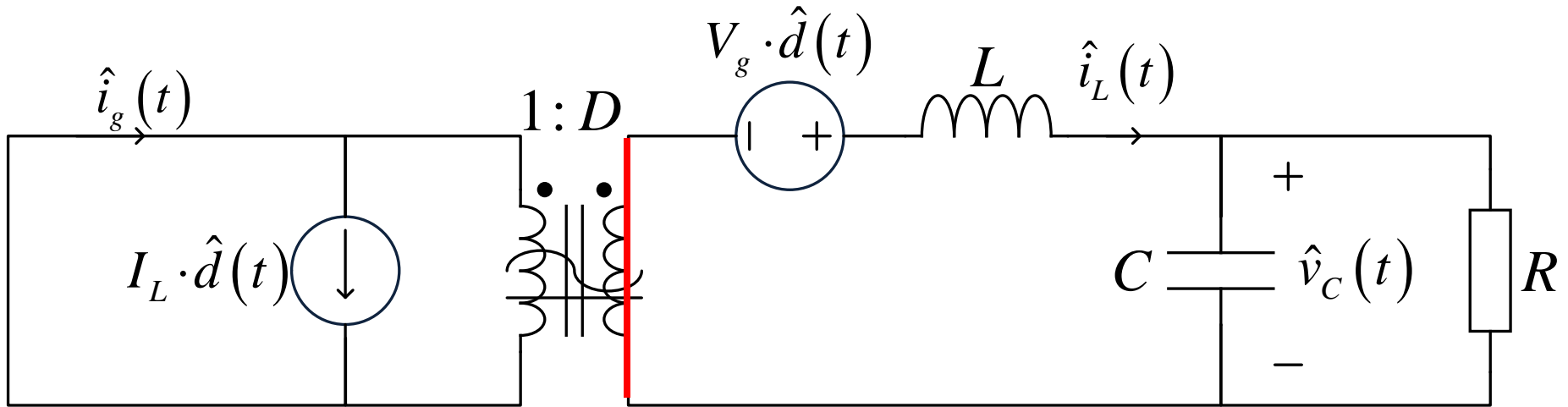


# Control-To-Output Transfer Function

$$G_{vd}(s) = \left. \frac{\hat{v}_C(s)}{\hat{d}(s)} \right|_{\hat{v}_g=0}$$

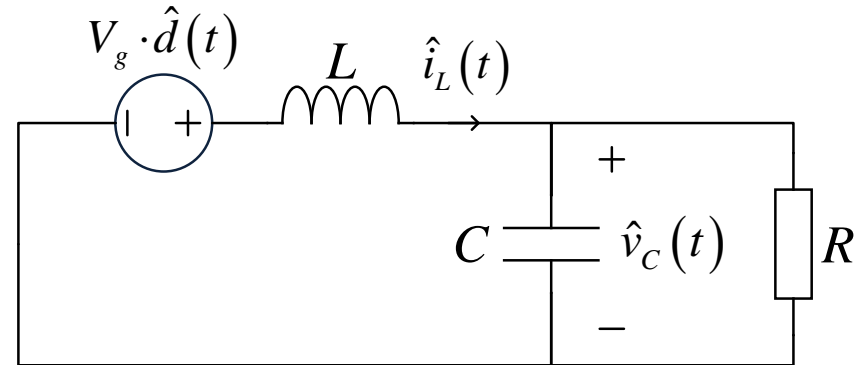


# Control-To-Output Transfer Function



# Control-To-Output Transfer Function

$$\hat{v}_C(s) = \frac{R \parallel \frac{1}{s \cdot C}}{s \cdot L + R \parallel \frac{1}{s \cdot C}} \cdot V_g \cdot \hat{d}(s)$$



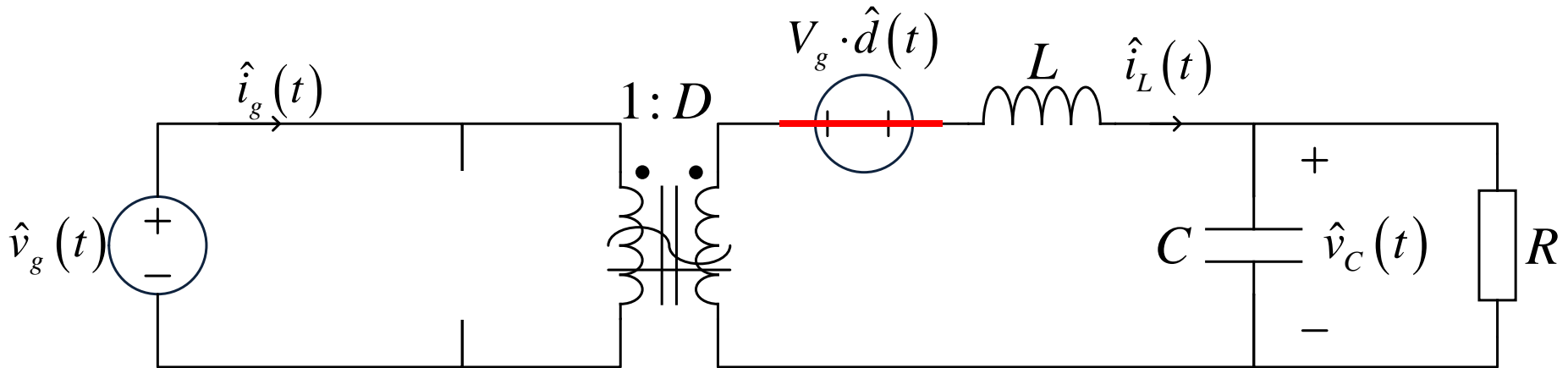
$$G_{vd}(s) = \frac{\hat{v}_C(s)}{\hat{d}(s)} = \frac{1}{1 + \frac{L}{R} \cdot s + L \cdot C \cdot s^2} \cdot V_g = \frac{1}{1 + \frac{1}{Q} \cdot \frac{s}{\omega_0} + \left(\frac{s}{\omega_0}\right)^2} \cdot V_g$$

$$\omega_0^2 = \frac{1}{L \cdot C} \quad Q = R \cdot \sqrt{\frac{C}{L}} = \frac{1}{2 \cdot \zeta}$$

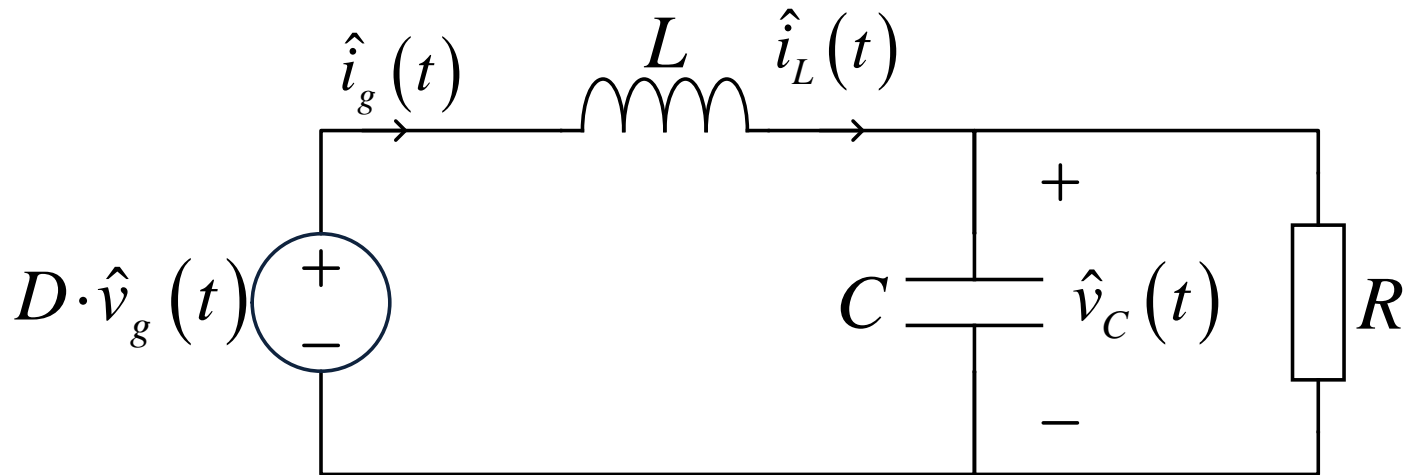
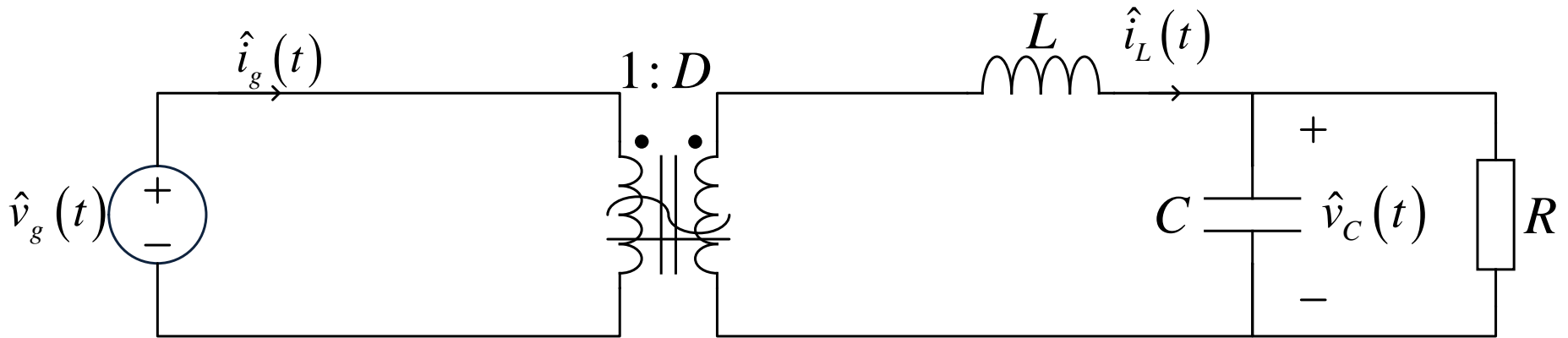
# Input To Output Transfer Function

$$G_{vg}(s) = \left. \frac{\hat{v}_C(s)}{\hat{v}_g(s)} \right|_{\hat{d}=0}$$

“Audiosusceptibility”

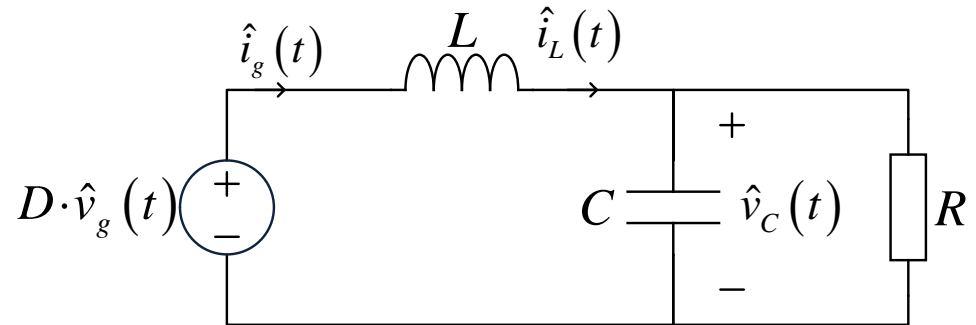


# Input To Output Transfer Function



# Input To Output Transfer Function

$$\hat{v}_C(s) = \frac{R \parallel \frac{1}{s \cdot C}}{s \cdot L + R \parallel \frac{1}{s \cdot C}} \cdot D \cdot \hat{v}_g$$

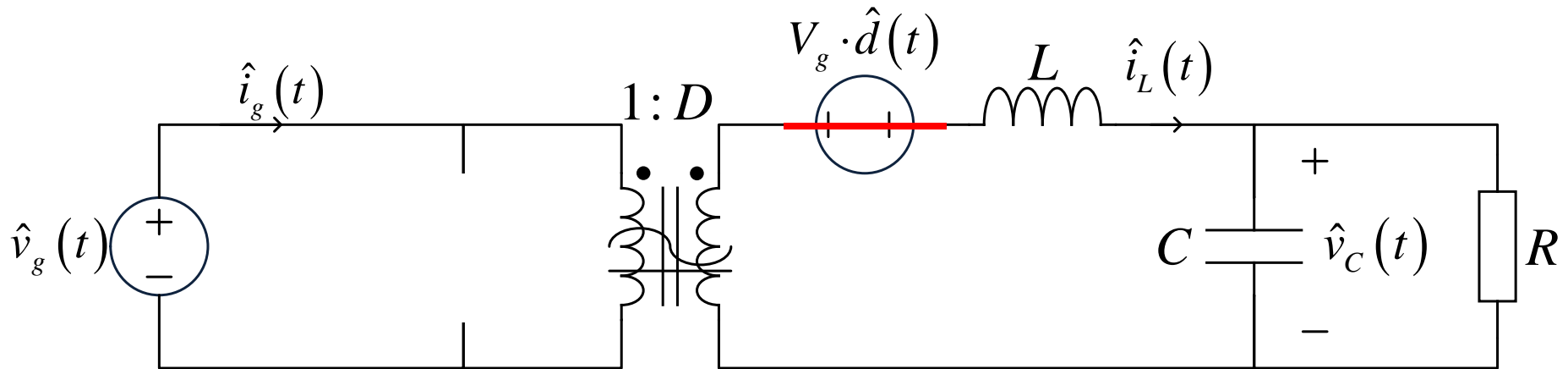


$$G_{vd}(s) = \frac{\hat{v}_C(s)}{\hat{v}_g} = \frac{D}{1 + \frac{L}{R} \cdot s + L \cdot C \cdot s^2} = \frac{D}{1 + \frac{1}{Q} \cdot \frac{s}{\omega_0} + \left(\frac{s}{\omega_0}\right)^2}$$

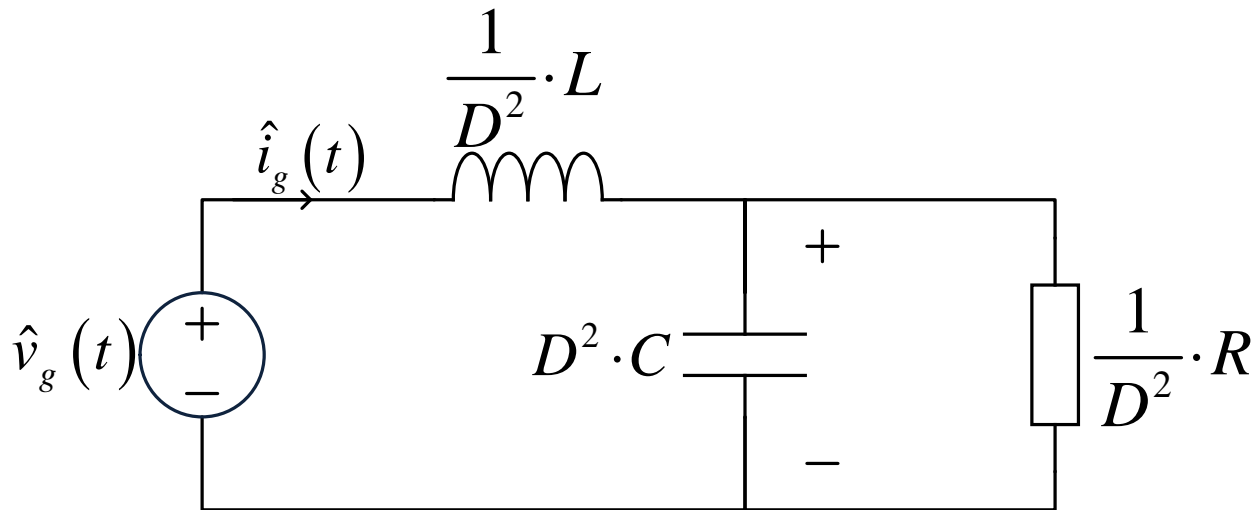
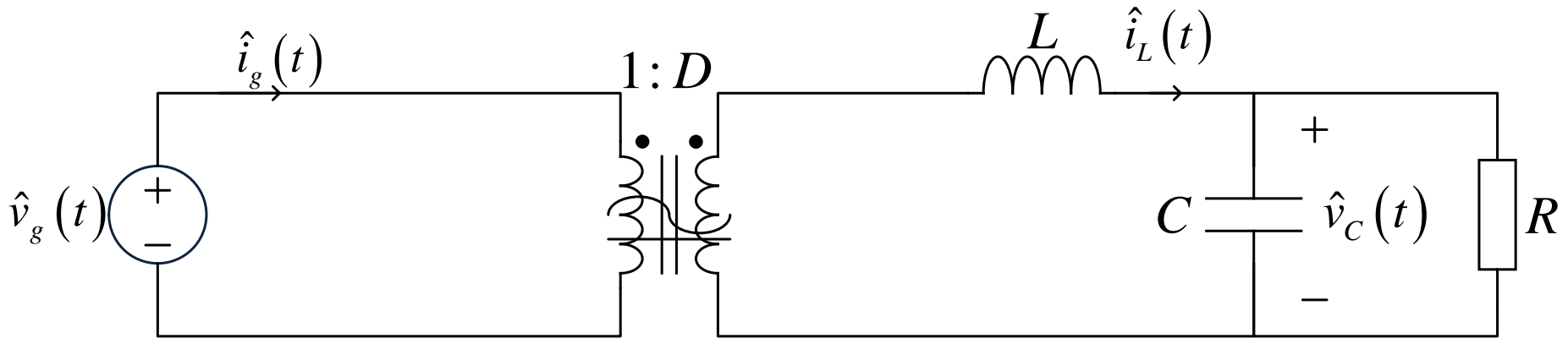


# Input Impedance

$$Z_i(s) = \left. \frac{\hat{v}_g(s)}{\hat{i}_g(s)} \right|_{\hat{d}=0}$$

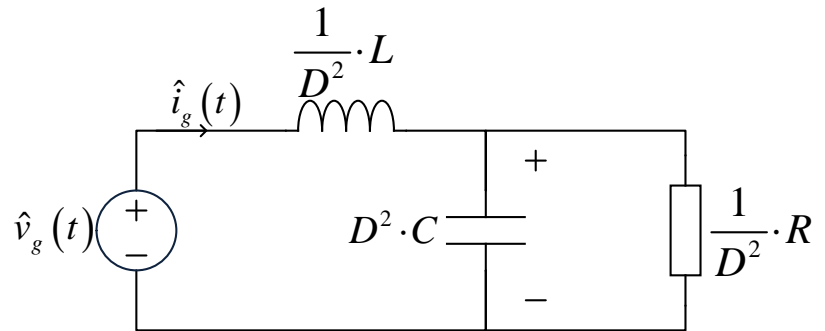


# Input Impedance



# Input Impedance

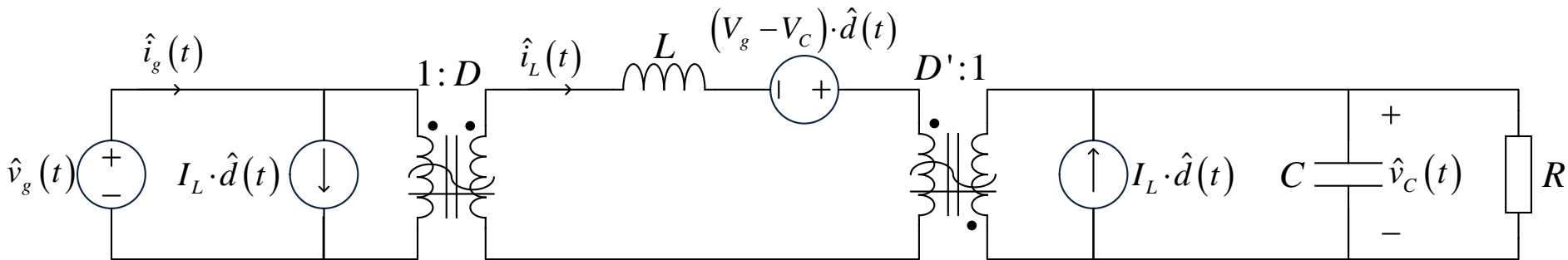
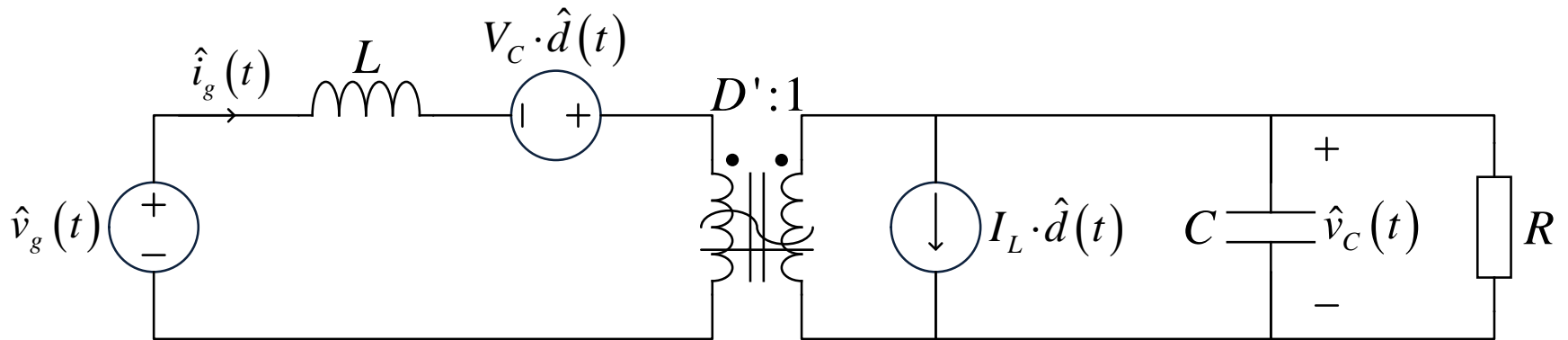
$$\hat{i}_g(s) = \frac{\hat{v}_g(s)}{s \cdot \frac{L}{D^2} + \frac{R}{D^2} \parallel \frac{1}{s \cdot D^2 \cdot C}}$$



$$Z_i(s) = \frac{\hat{v}_g(s)}{\hat{i}_g(s)} = s \cdot \frac{L}{D^2} + \frac{R}{D^2} \parallel \frac{1}{s \cdot D^2 \cdot C}$$

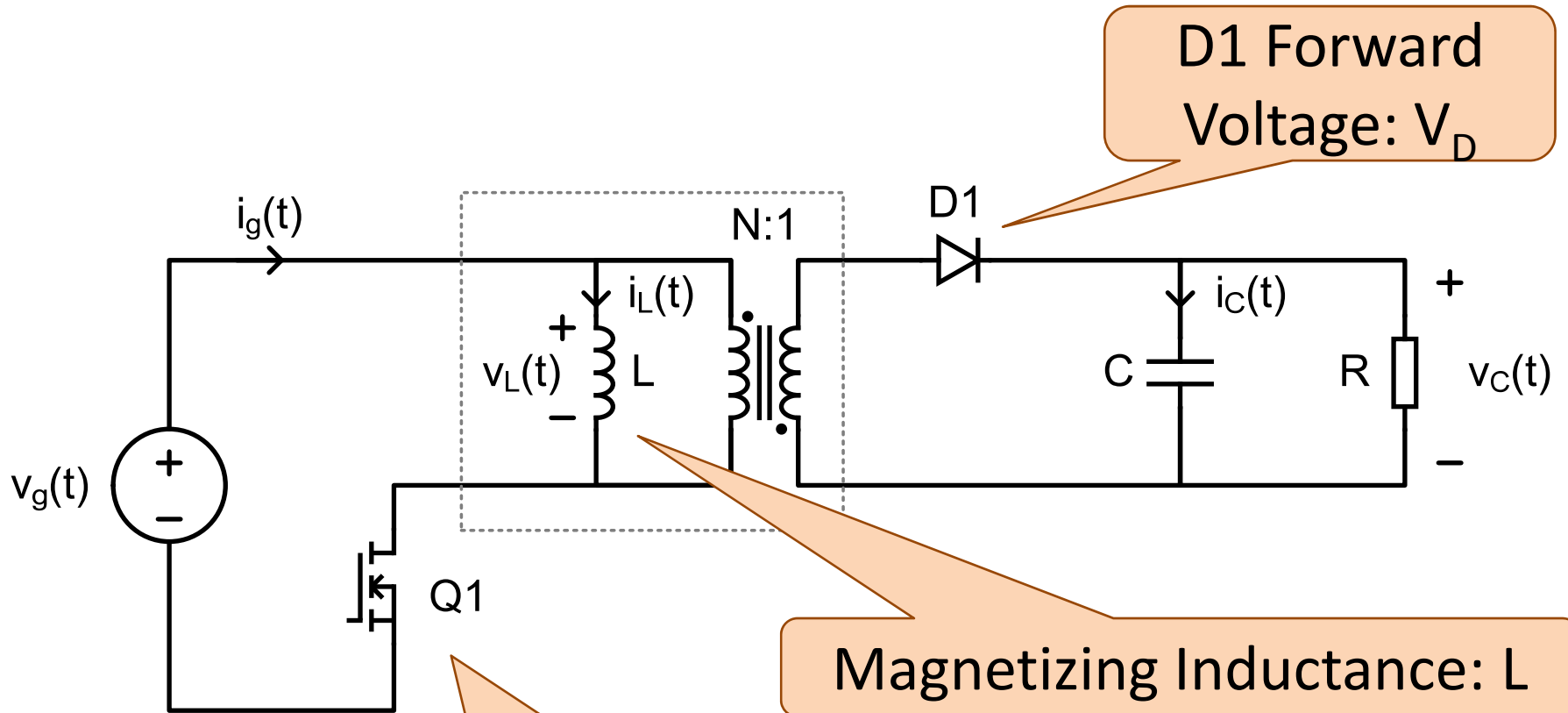
$$Z_i(s) = \frac{R}{D^2} \cdot \frac{1 + s \cdot \frac{L}{R} + s^2 \cdot L \cdot C}{1 + s \cdot R \cdot C} = \frac{R}{D^2} \cdot \frac{1 + \frac{1}{Q} \cdot \frac{s}{\omega_0} + \left(\frac{s}{\omega_0}\right)^2}{1 + s \cdot R \cdot C}$$

# Boost And Buck-Boost Models

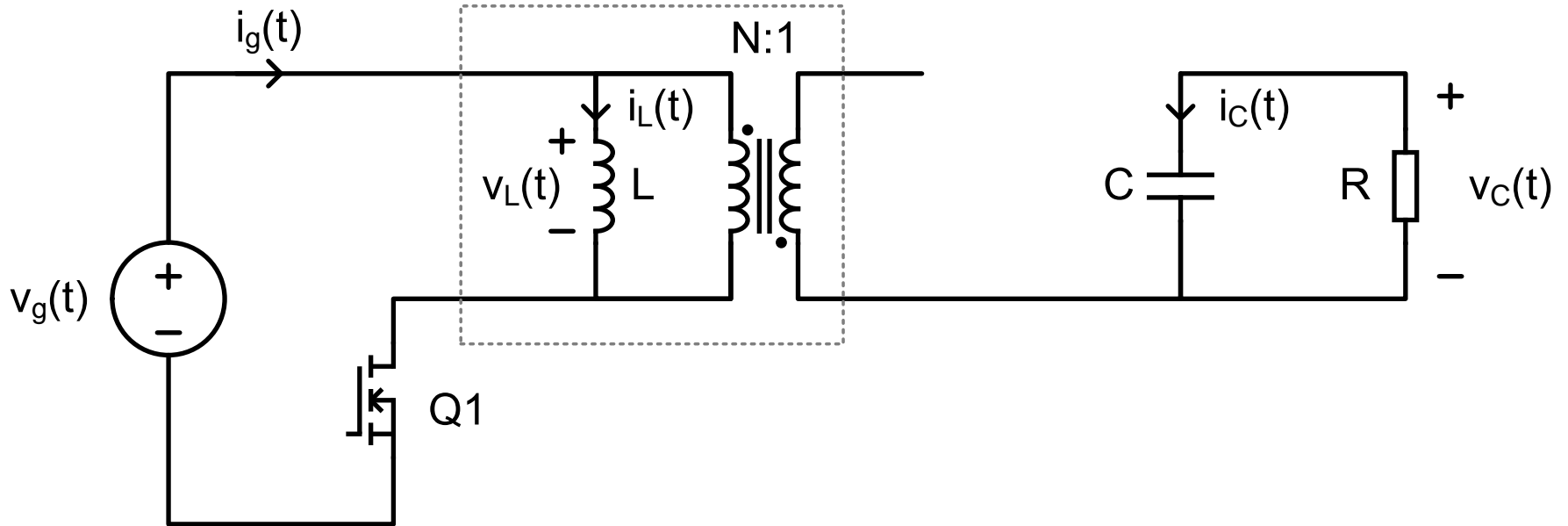


Re-drawn from "Fundamentals of Power Electronics", 2<sup>nd</sup> ed.,  
Erickson and Maksimovic, Figure 7.17

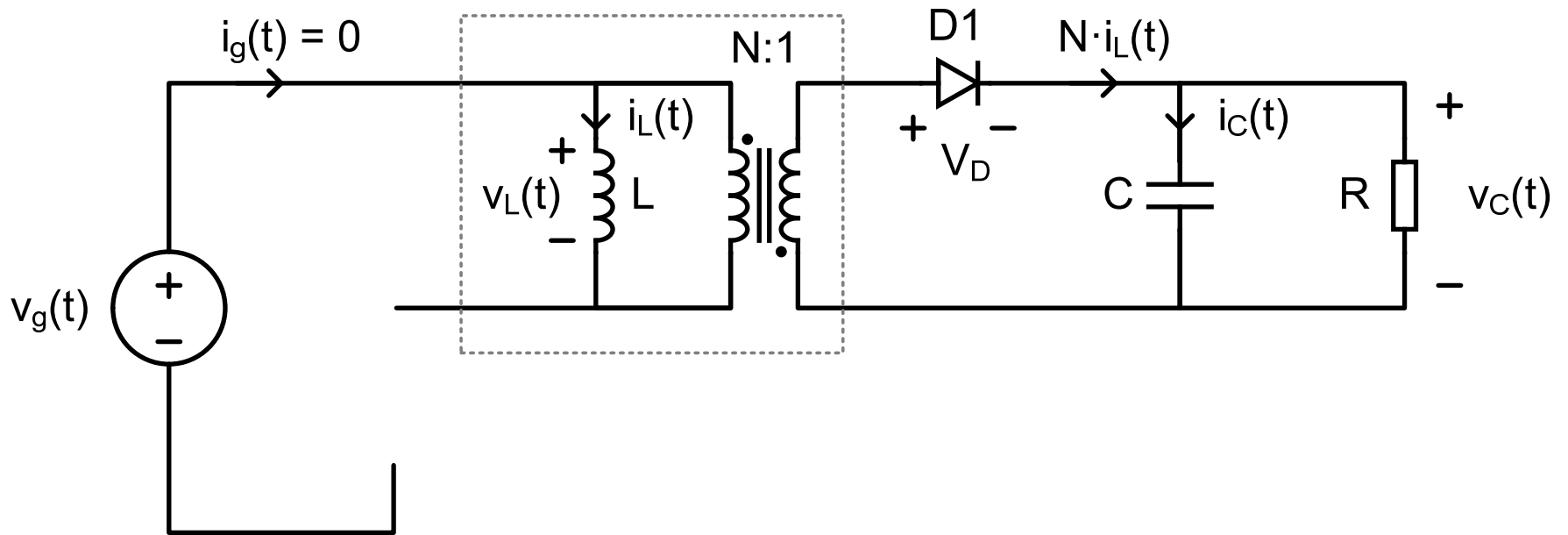
# Flyback Example



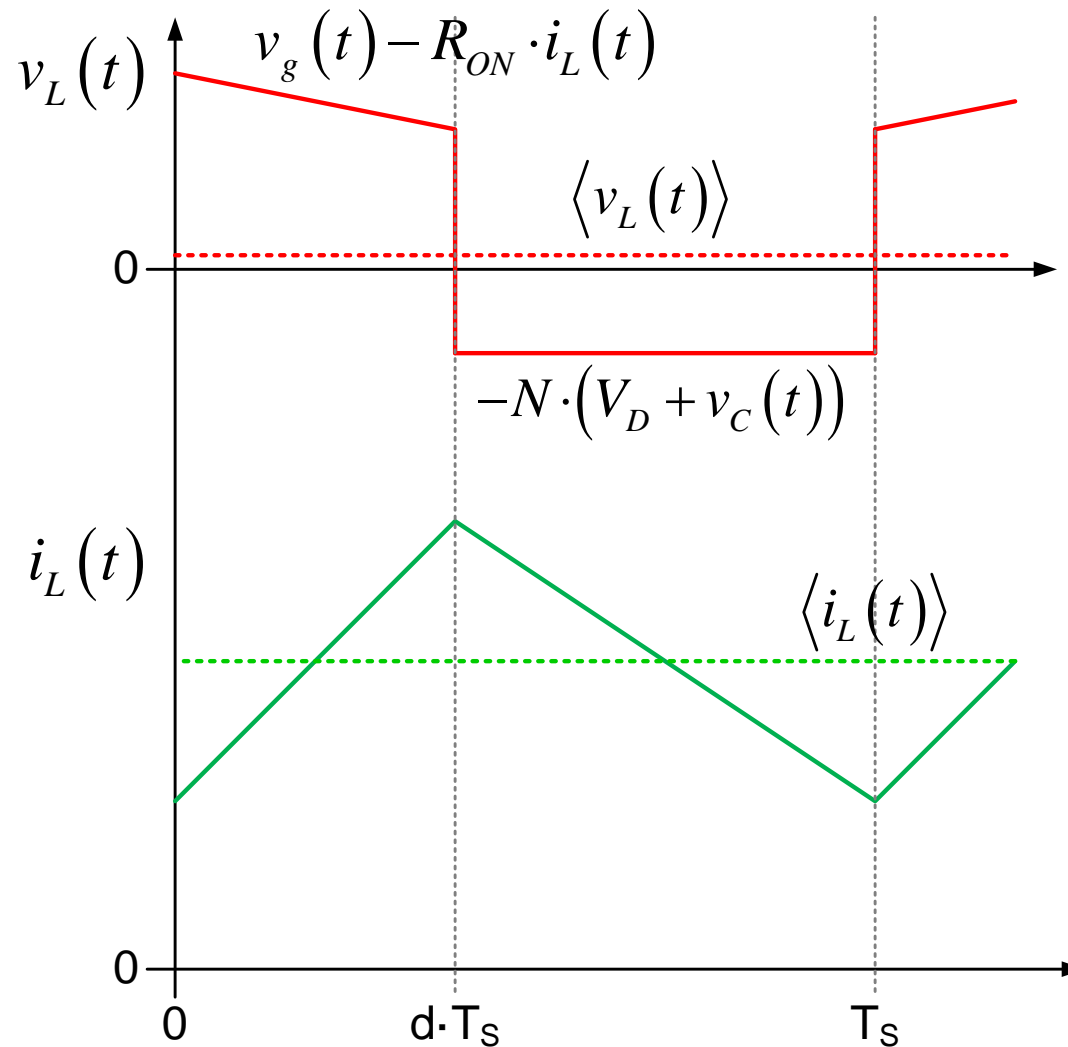
# On-Time Circuit



# Off Time Circuit

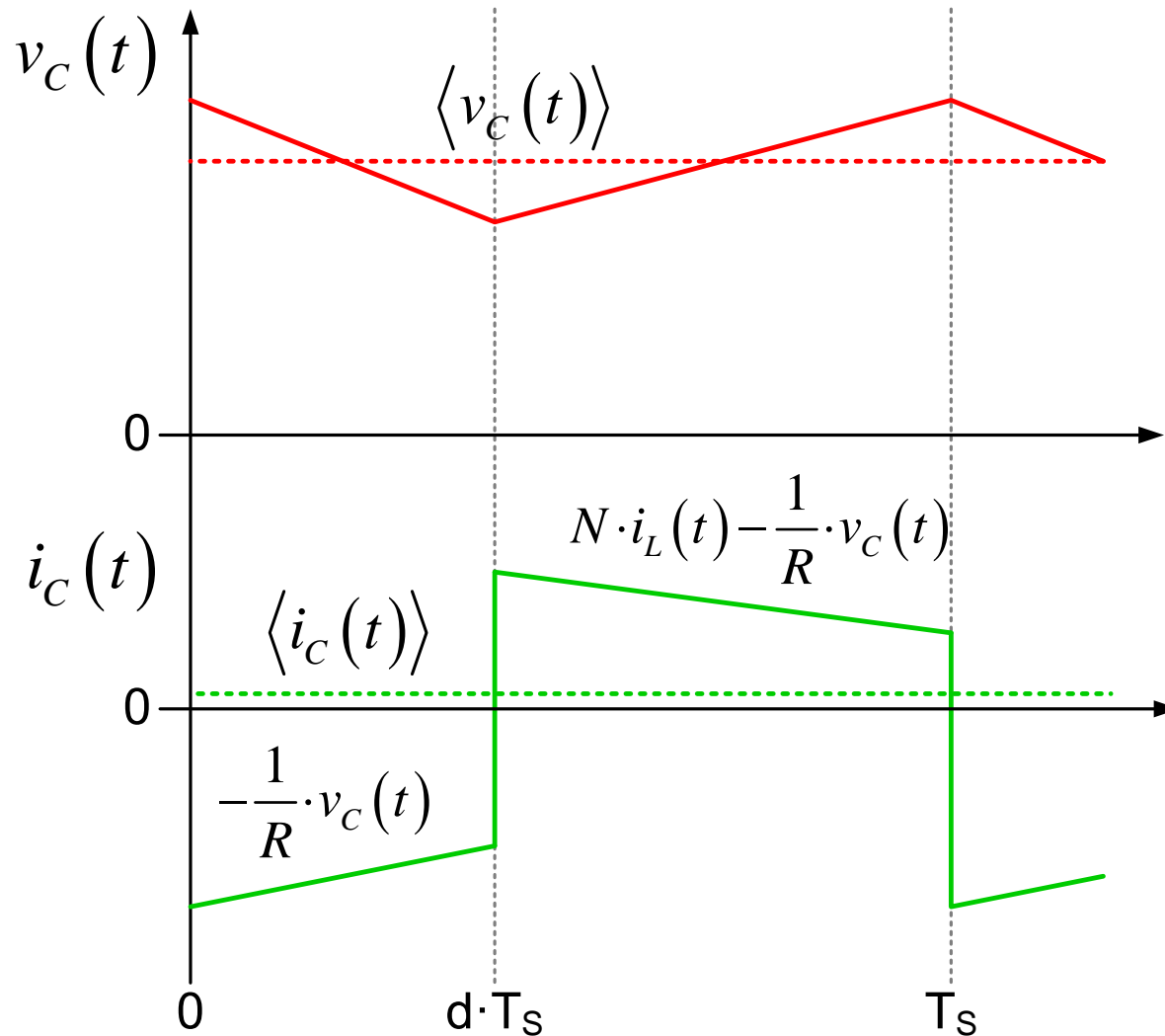


# Sketching The Inductor Waveforms





# Sketching The Capacitor Waveforms



# Averaging The Circuit Equations

## On Time

$$v_L(t) = v_g(t) - R_{ON} \cdot i_L(t)$$

$$i_C(t) = -\frac{1}{R} \cdot v_C(t)$$

$$i_g(t) = i_L(t)$$

## Off Time

$$v_L(t) = -N \cdot (V_D + v_c(t))$$

$$i_C(t) = N \cdot i_L(t) - \frac{1}{R} \cdot v_C(t)$$

$$i_g(t) = 0$$

---

$$v_L(t) = \langle v_g(t) \rangle - R_{ON} \cdot \langle i_L(t) \rangle$$

$$i_C(t) = -\frac{1}{R} \cdot \langle v_C(t) \rangle$$

$$i_g(t) = \langle i_L(t) \rangle$$

$$v_L(t) = -N \cdot (V_D + \langle v_c(t) \rangle)$$

$$i_C(t) = N \cdot \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle$$

$$i_g(t) = 0$$

# Averaging The Inductor Voltage

$$\begin{aligned}\langle v_L(t) \rangle &= d(t) \cdot \left( \langle v_g(t) \rangle - R_{ON} \cdot \langle i_L(t) \rangle \right) \\ &\quad + d'(t) \cdot \left( -N \cdot \left( V_D + \langle v_c(t) \rangle \right) \right) \\ &= d(t) \cdot \langle v_g(t) \rangle - d(t) \cdot R_{ON} \cdot \langle i_L(t) \rangle \\ &\quad - d'(t) \cdot N \cdot \langle v_c(t) \rangle - d'(t) \cdot N \cdot V_D\end{aligned}$$

$$\begin{aligned}L \cdot \frac{d \langle i_L(t) \rangle}{dt} &= \langle v_L(t) \rangle \\ &= d(t) \cdot \langle v_g(t) \rangle - d(t) \cdot R_{ON} \cdot \langle i_L(t) \rangle \\ &\quad - d'(t) \cdot N \cdot \langle v_c(t) \rangle - d'(t) \cdot N \cdot V_D\end{aligned}$$

# Averaging The Capacitor Current

$$\begin{aligned}\langle i_C(t) \rangle &= d(t) \cdot \left( -\frac{1}{R} \cdot \langle v_C(t) \rangle \right) \\ &\quad + d'(t) \cdot \left( N \cdot \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle \right) \\ &= d'(t) \cdot N \cdot \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle\end{aligned}$$

$$\begin{aligned}C \cdot \frac{d \langle v_C(t) \rangle}{dt} &= \langle i_C(t) \rangle \\ &= d'(t) \cdot N \cdot \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_C(t) \rangle\end{aligned}$$

# Averaging The Input Current/ Perturbation

$$\begin{aligned}\langle i_g(t) \rangle &= d(t) \cdot \langle i_L(t) \rangle + d'(t) \cdot 0 \\ &= d(t) \cdot \langle i_L(t) \rangle\end{aligned}$$

## Perturbing The Inputs

$$d(t) = D + \hat{d}(t)$$

$$d'(t) = 1 - d(t) = 1 - D - \hat{d}(t)$$

$$\langle V_g(t) \rangle = V_g + \hat{v}_g(t)$$

## Perturbed Circuit Variables

$$\langle i_L(t) \rangle = I_L + \hat{i}_L(t)$$

$$\langle v_C(t) \rangle = V_C + \hat{v}_C(t)$$

$$\langle i_g(t) \rangle = I_g + \hat{i}_g(t)$$

Substitute Expressions Into Averaged Differential Equations

# Averaging The Inductor Voltage



$$\begin{aligned}L \cdot \frac{d\langle i_L(t) \rangle}{dt} &= \langle v_L(t) \rangle \\ &= d(t) \cdot \langle v_g(t) \rangle - d(t) \cdot R_{ON} \cdot \langle i_L(t) \rangle \\ &\quad - d'(t) \cdot N \cdot \langle v_c(t) \rangle - d'(t) \cdot N \cdot V_D\end{aligned}$$

$$\begin{aligned}L \cdot \frac{d(I_L + \hat{i}_L(t))}{dt} &= (D + \hat{d}(t)) \cdot (V_g + \hat{v}_g(t)) - (D + \hat{d}(t)) \cdot R_{ON} \cdot (I_L + \hat{i}_L(t)) \\ &\quad - (1 - D - \hat{d}(t)) \cdot N \cdot (V_C + \hat{v}_C(t)) - (1 - D - \hat{d}(t)) \cdot N \cdot V_D\end{aligned}$$

# Averaging The Inductor Voltage



$$L \cdot \frac{d(I_L)}{dt} + L \cdot \frac{d(\hat{i}_L(t))}{dt} = D \cdot V_g + D \cdot \hat{v}_g(t) + V_g \cdot \hat{d}(t) + \hat{d}(t) \cdot \hat{v}_g(t)$$

$$-D \cdot R_{ON} \cdot I_L - D \cdot R_{ON} \cdot \hat{i}_L(t) - R_{ON} \nu I_L \cdot \hat{d}(t) - R_{ON} \cdot \hat{d}(t) \cdot \hat{i}_L(t)$$

$$-N \cdot V_C - N \cdot \hat{v}_C(t) + D \cdot N \cdot V_C + D \cdot N \cdot \hat{v}_C(t) + N \cdot V_C \cdot \hat{d}(t) + N \cdot \hat{v}_C(t) \cdot \hat{d}(t)$$

$$-N \cdot V_D + D \cdot N \cdot V_D + N \cdot V_D \cdot \hat{d}(t)$$

# Averaging The Inductor Voltage



$$\begin{aligned}
 L \cdot \frac{d(I_L)}{dt} + L \cdot \frac{d(\hat{i}_L(t))}{dt} &= D \cdot V_g - D \cdot R_{ON} \cdot I_L - N \cdot V_C + D \cdot N \cdot V_C - N \cdot V_D + D \cdot N \cdot V_D \\
 &+ D \cdot \hat{v}_g(t) \\
 &+ V_g \cdot \hat{d}(t) - R_{ON} \cdot I_L \cdot \hat{d}(t) + N \cdot V_C \cdot \hat{d}(t) + N \cdot V_D \cdot \hat{d}(t) \\
 &- D \cdot R_{ON} \cdot \hat{i}_L(t) \\
 &- N \cdot \hat{v}_C(t) + D \cdot N \cdot \hat{v}_C(t) \\
 &+ \hat{d}(t) \cdot \hat{v}_g(t) - R_{ON} \cdot \hat{d}(t) \cdot \hat{i}_L(t) + N \cdot \hat{v}_C(t) \cdot \hat{d}(t)
 \end{aligned}$$



# Averaging The Inductor Voltage



$$L \cdot \frac{d(I_L)}{dt} = 0$$

$$= D \cdot V_g - D \cdot R_{ON} \cdot I_L - N \cdot V_C + D \cdot N \cdot V_C - N \cdot V_D + D \cdot N \cdot V_D$$

$$= D \cdot (V_g - R_{ON} \cdot I_L) - (1 - D) \cdot N \cdot V_C - (1 - D) \cdot N \cdot V_D$$

$$D' \cdot N \cdot V_C = D \cdot (V_g - R_{ON} \cdot I_L) - D' \cdot N \cdot V_D$$

$$V_C = \frac{D}{D'} \cdot \frac{1}{N} \cdot (V_g - R_{ON} \cdot I_L) - V_D$$

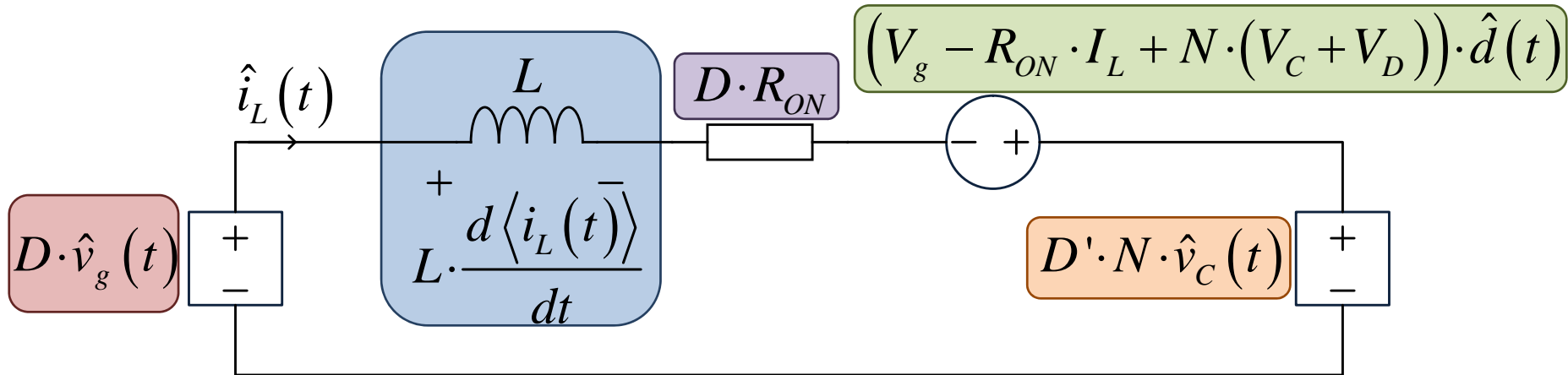
Get The Same Result By Inductor  
Volt-Second Balance Calculation

# Averaging The Inductor Voltage

$$\begin{aligned}L \frac{d \langle i_L(t) \rangle}{dt} &= D \cdot \hat{v}_g(t) \\ &+ V_g \cdot \hat{d}(t) - R_{ON} \cdot I_L \cdot \hat{d}(t) + N \cdot V_C \cdot \hat{d}(t) + N \cdot V_D \cdot \hat{d}(t) \\ &- D \cdot R_{ON} \cdot \hat{i}_L(t) \\ &- N \cdot \hat{v}_C(t) + D \cdot N \cdot \hat{v}_C(t) \\ &= D \cdot \hat{v}_g(t) \\ &+ (V_g - R_{ON} \cdot I_L + N \cdot (V_C + V_D)) \cdot \hat{d}(t) \\ &- D \cdot R_{ON} \cdot \hat{i}_L(t) \\ &- (1 - D) \cdot N \cdot \hat{v}_C(t)\end{aligned}$$

# Construct The Model

$$L \cdot \frac{d\langle i_L(t) \rangle}{dt} = D \cdot \hat{v}_g(t) + (V_g - R_{ON} \cdot I_L + N \cdot (V_C + V_D)) \cdot \hat{d}(t) - D \cdot R_{ON} \cdot \hat{i}_L(t) - D' \cdot N \cdot \hat{v}_C(t)$$



# Averaging The Capacitor Current



$$C \frac{d\langle v_c(t) \rangle}{dt} = d'(t) \cdot N \cdot \langle i_L(t) \rangle - \frac{1}{R} \cdot \langle v_c(t) \rangle$$

$$C \frac{d(V_C + \hat{v}_c(t))}{dt} = (1 - D - \hat{d}(t)) \cdot N \cdot (I_L + \hat{i}_L(t)) - \frac{1}{R} \cdot (V_C + \hat{v}_c(t))$$

$$\begin{aligned} C \frac{d(V_C)}{dt} + C \frac{d(\hat{v}_c(t))}{dt} &= N \cdot I_L + N \cdot \hat{i}_L(t) - D \cdot N \cdot I_L - D \cdot N \cdot \hat{i}_L(t) \\ &\quad - N \cdot I_L \cdot \hat{d}(t) - \cancel{N \cdot \hat{i}_L(t) \cdot \hat{d}(t)} \\ &\quad - \frac{1}{R} \cdot V_C - \frac{1}{R} \cdot \hat{v}_c(t) \end{aligned}$$

# Averaging The Capacitor Current



$$C \frac{d(V_C)}{dt} + C \frac{d(\hat{v}_C(t))}{dt} = N \cdot I_L - D \cdot N \cdot I_L - \frac{1}{R} \cdot V_C$$
$$+ N \cdot \hat{i}_L(t) - D \cdot N \cdot \hat{i}_L(t)$$
$$- N \cdot I_L \cdot \hat{d}(t)$$
$$- \frac{1}{R} \cdot \hat{v}_C(t)$$

$$C \frac{d(\hat{v}_C(t))}{dt} = D' \cdot N \cdot \hat{i}_L(t) - N \cdot I_L \cdot \hat{d}(t) - \frac{1}{R} \cdot \hat{v}_C(t)$$

# Averaging The Capacitor Current



$$C \frac{d(V_C)}{dt} = D' \cdot N \cdot I_L - \frac{1}{R} \cdot V = 0$$

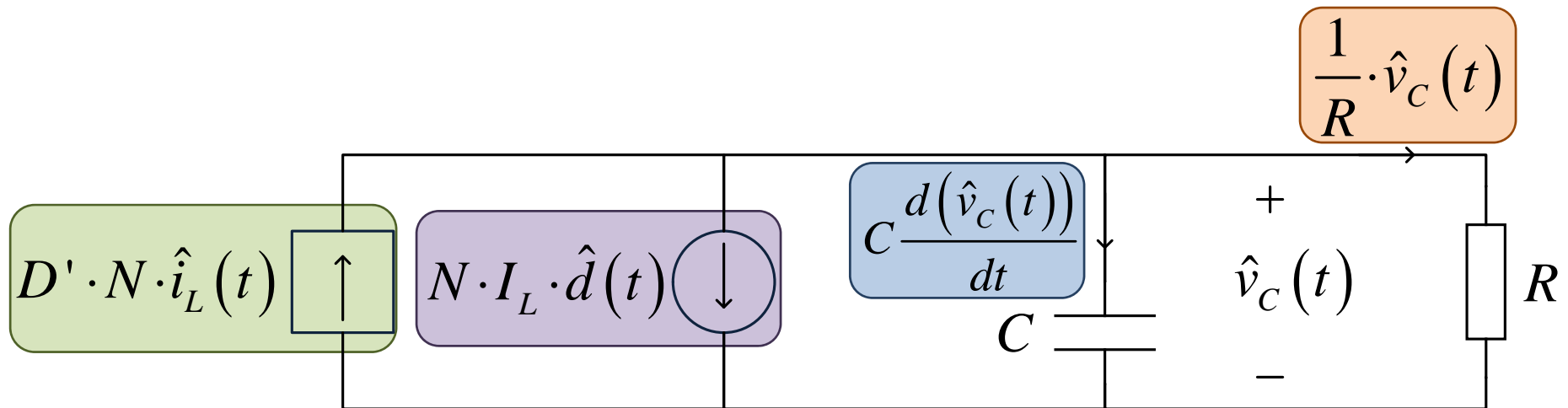
$$D' \cdot N \cdot I_L = \frac{1}{R} \cdot V_C$$

$$I_L = \frac{1}{D'} \cdot \frac{1}{N \cdot R} \cdot V_C$$

Get The Same Result By Capacitor  
Charge Balance Calculation

# Constructing The Model

$$C \frac{d(\hat{v}_C(t))}{dt} = D' \cdot N \cdot \hat{i}_L(t) - N \cdot I_L \cdot \hat{d}(t) - \frac{1}{R} \cdot \hat{v}_C(t)$$



# Averaging The Input Current

$$\langle i_g(t) \rangle = d(t) \cdot \langle i_L(t) \rangle$$

$$I_g + \hat{i}_g(t) = (D + \hat{d}(t)) \cdot (I_L + \hat{i}_L(t))$$

$$= D \cdot I_L + D \cdot \hat{i}_L(t) + I_L \cdot \hat{d}(t) + \hat{d}(t) \cdot \hat{i}_L(t)$$

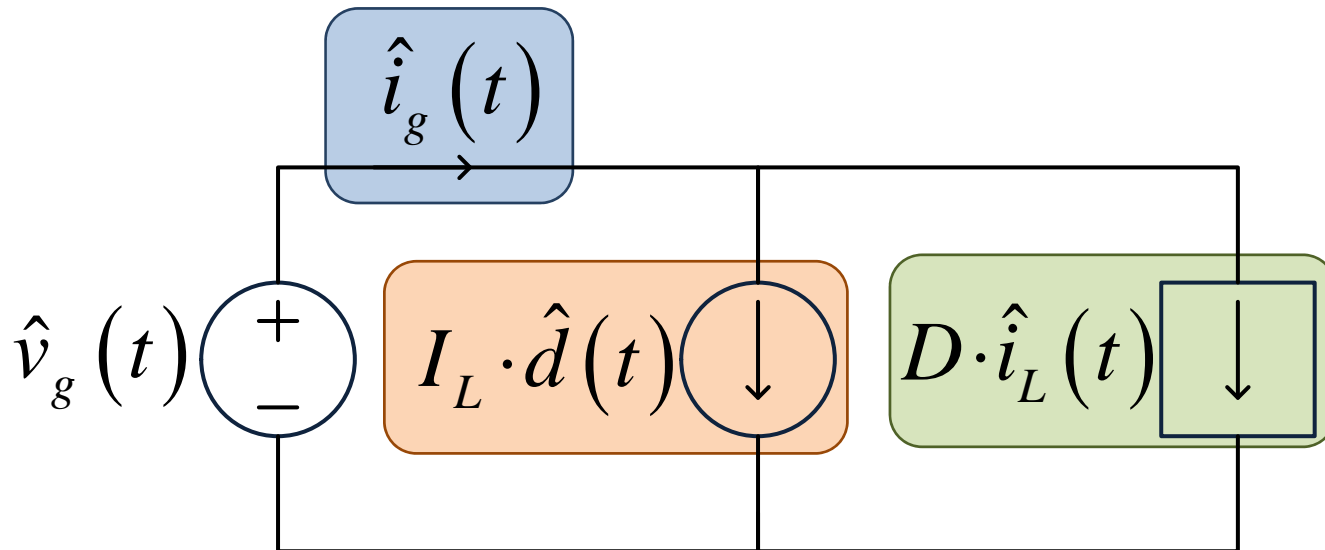
$$I_g = D \cdot I_L$$

$$\hat{i}_g(t) = D \cdot \hat{i}_L(t) + I_L \cdot \hat{d}(t)$$

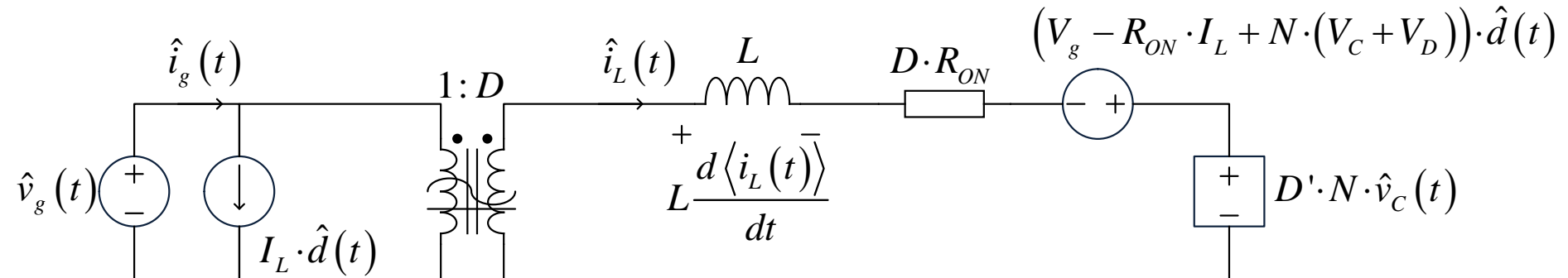
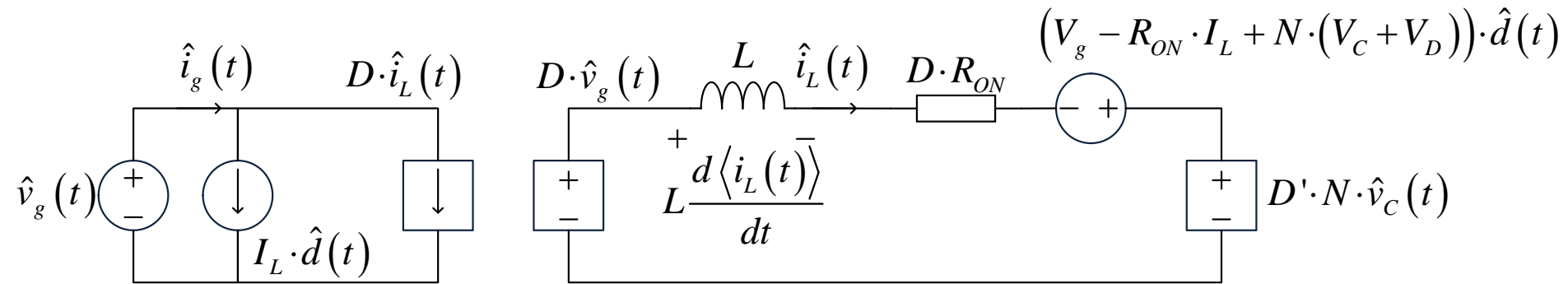


# Constructing The Model

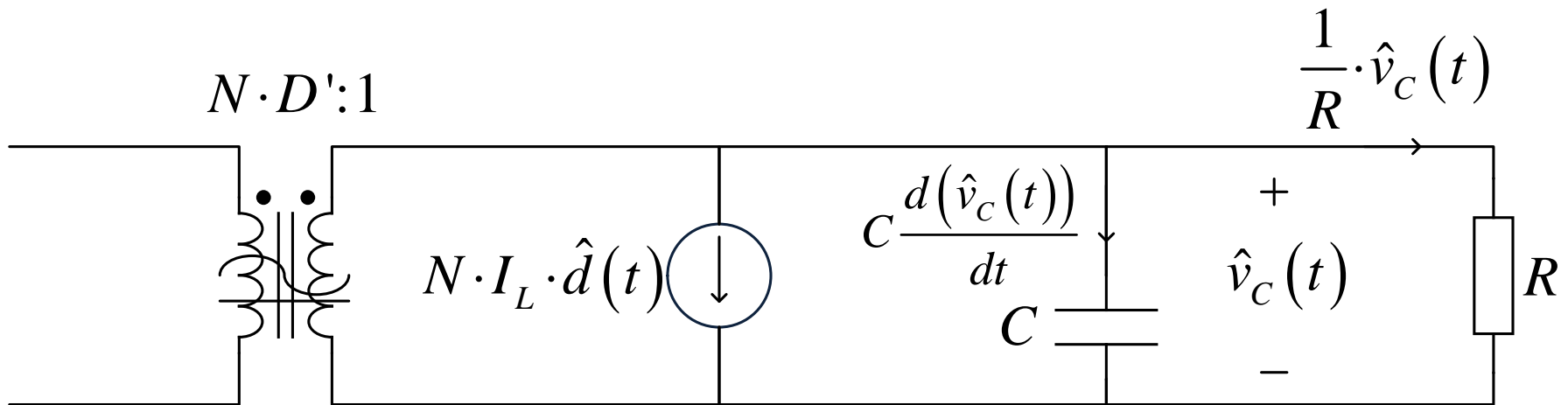
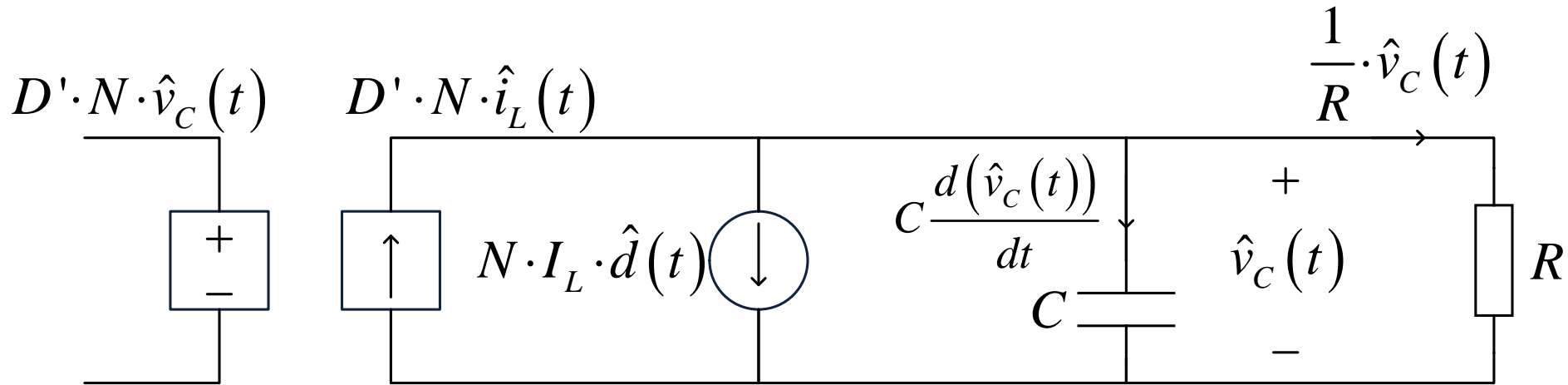
$$\hat{i}_g(t) = D \cdot \hat{i}_L(t) + I_L \cdot \hat{d}(t)$$



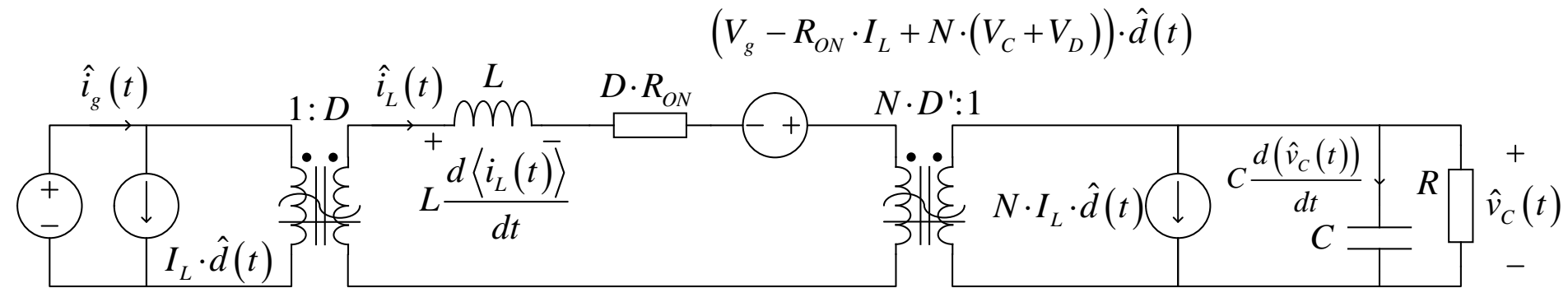
# Completing The Flyback Model



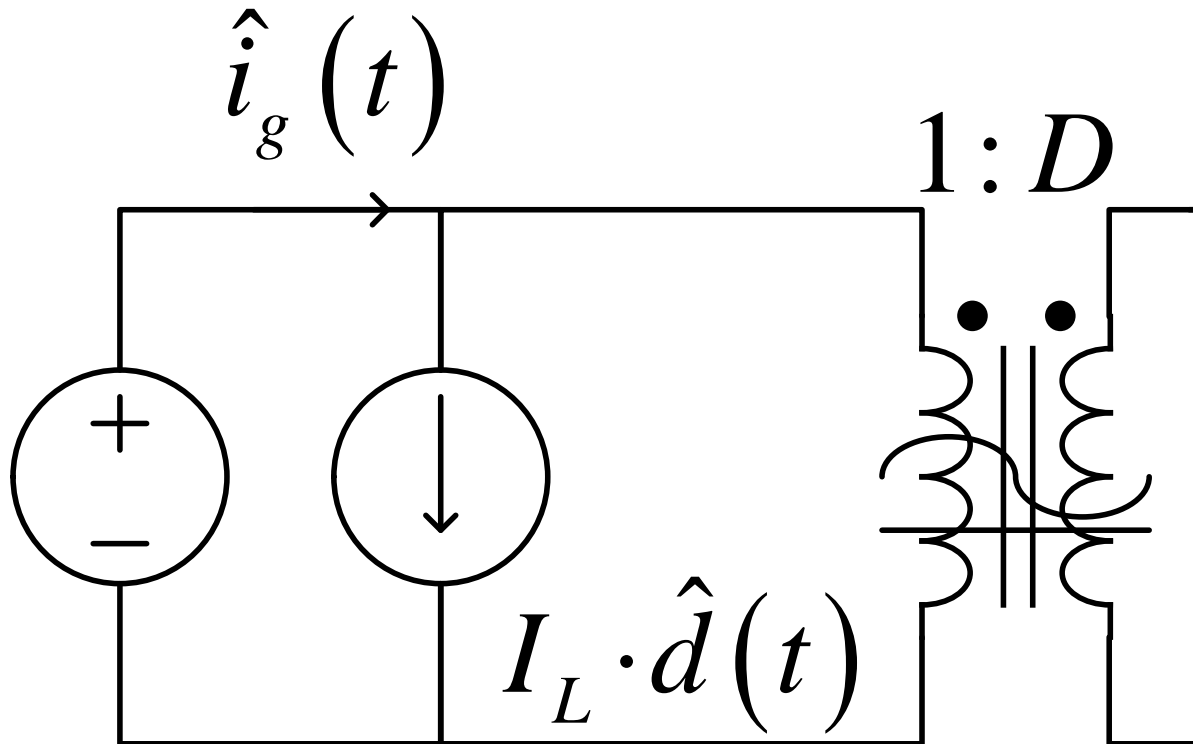
# Completing The Flyback Model



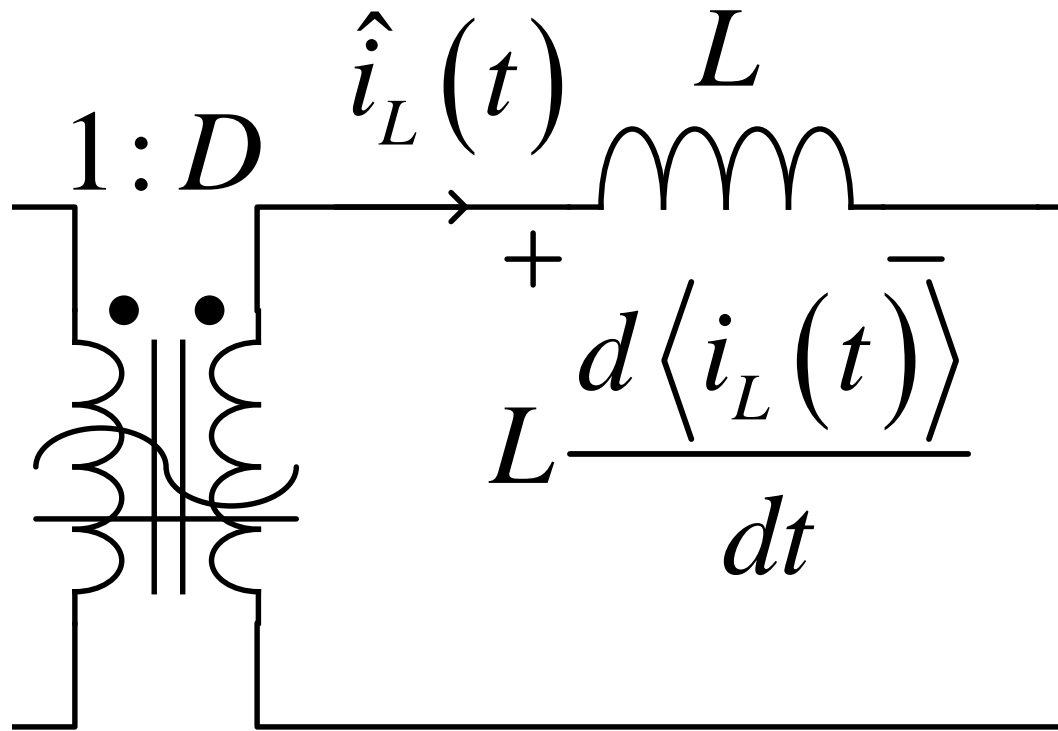
# Complete Flyback Model



# Complete Flyback Model



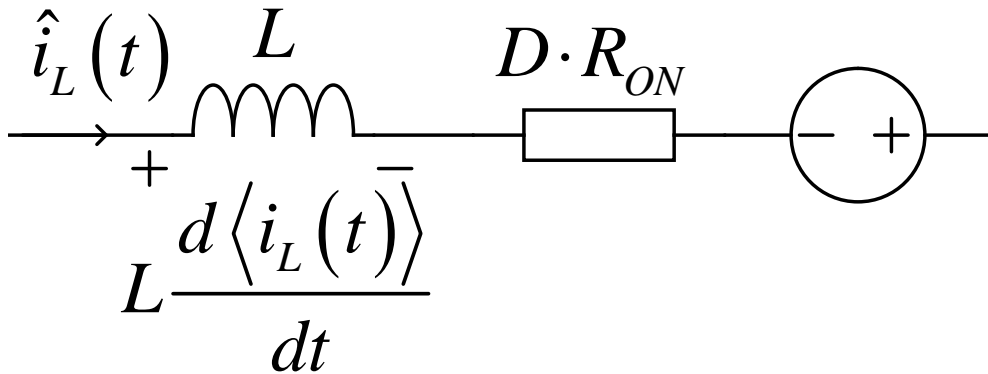
# Complete Flyback Model



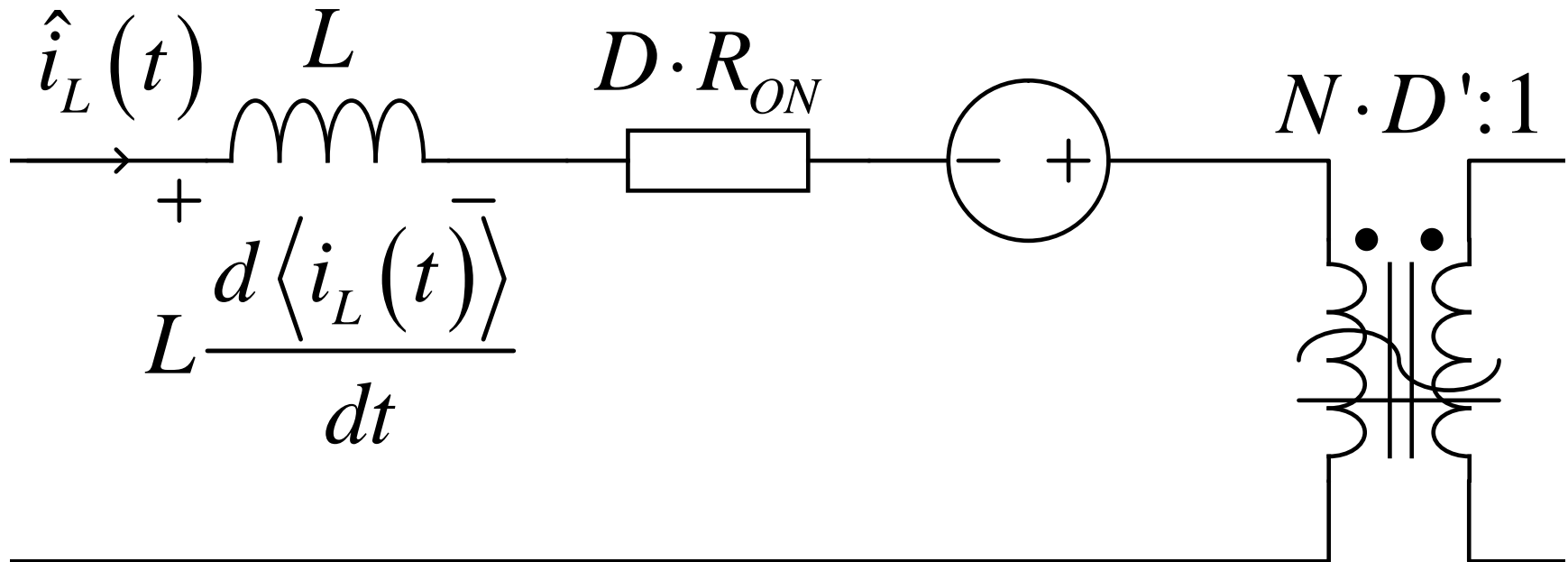
# Complete Flyback Model



$$\left( V_g - R_{ON} \cdot I_L + N \cdot (V_C + V_D) \right) \cdot \hat{d}(t)$$

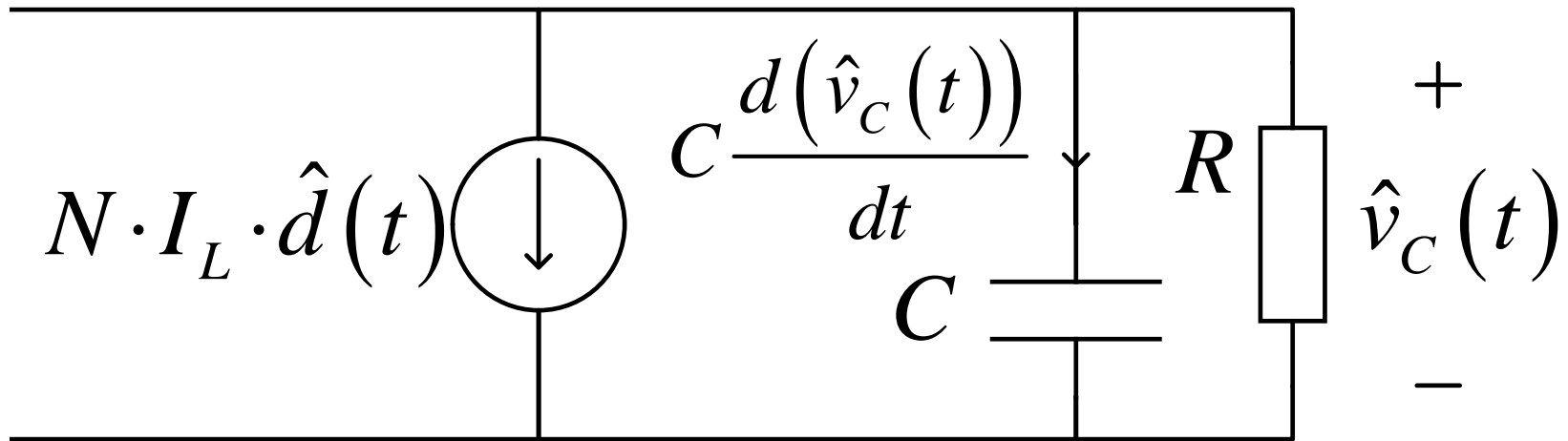


# Complete Flyback Model



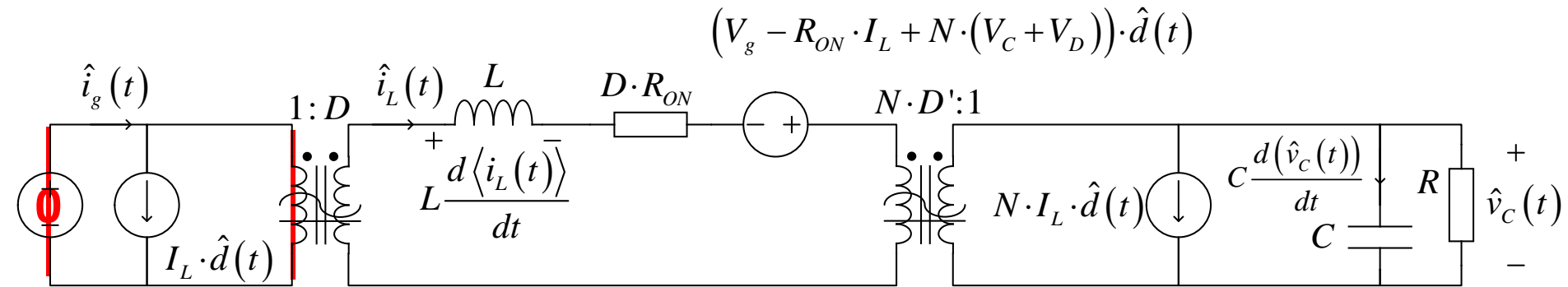


# Complete Flyback Model

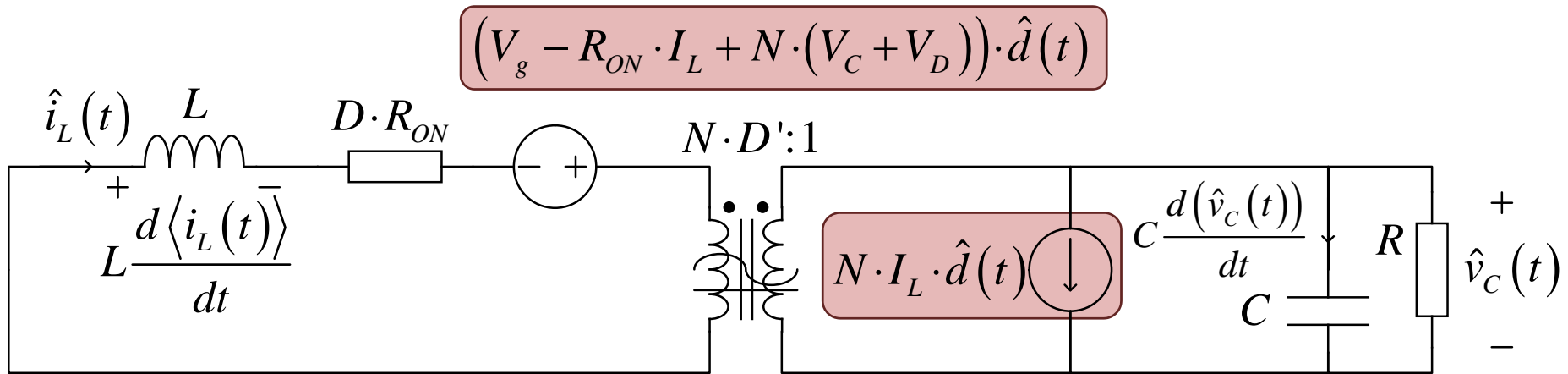


# Control-To-Output Transfer Function

$$G_{vd}(s) = \left. \frac{\hat{v}_C(s)}{\hat{d}(s)} \right|_{\hat{v}_g=0}$$



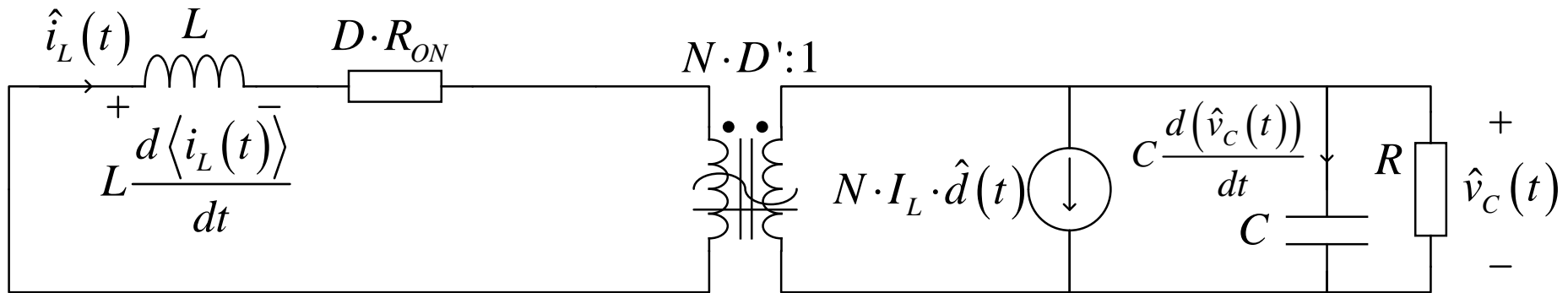
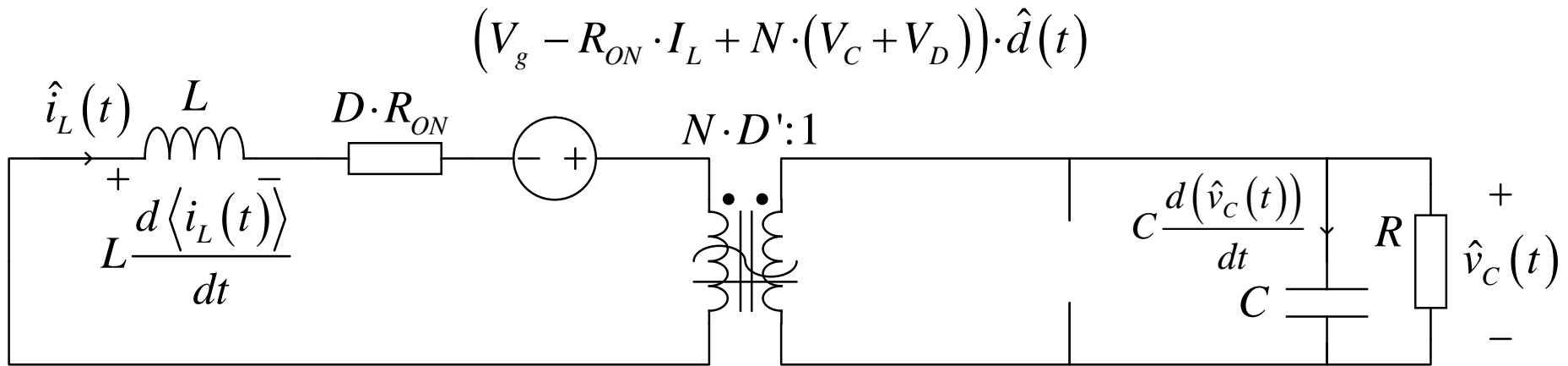
# Control-To-Output Transfer Function



Still Have Two dhat Terms

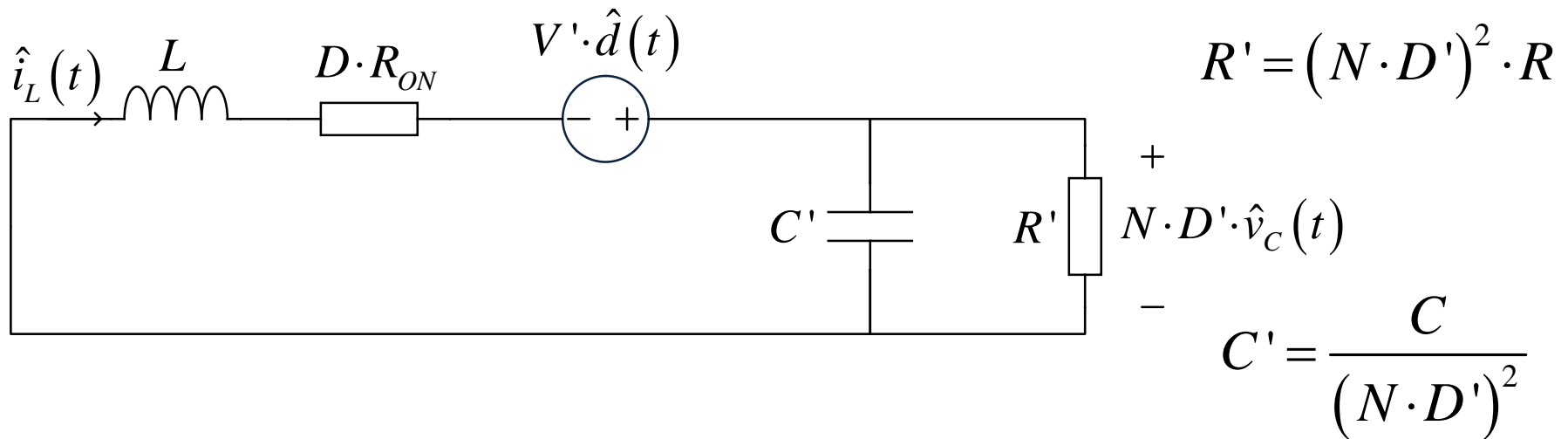
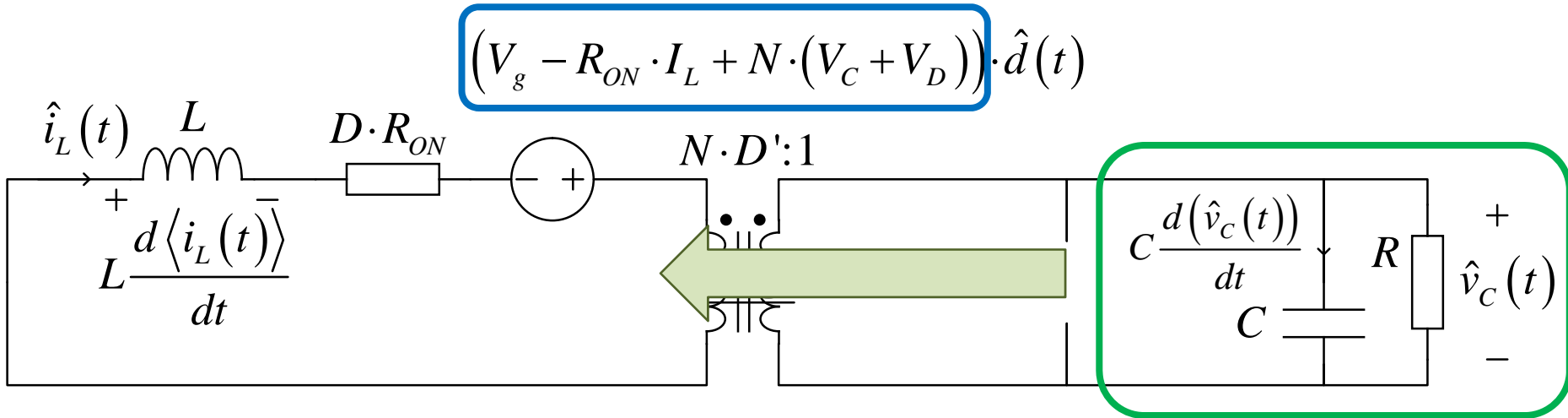
Solve By Using Superposition

# Control-To-Output Transfer Function



# Control-To-Output Transfer Function

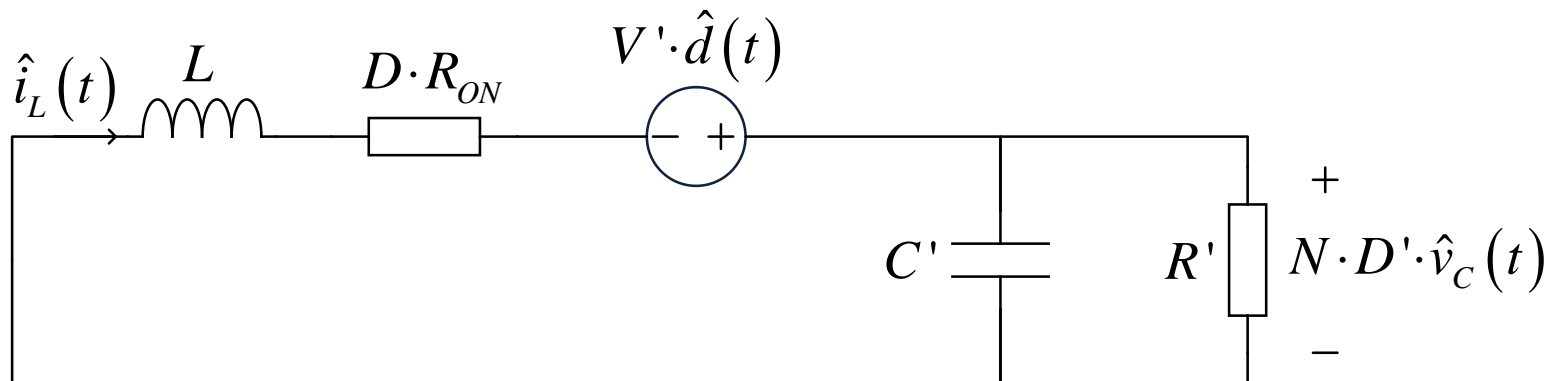

 $V' = V_g - R_{ON} \cdot I_L + N \cdot (V_C + V_D)$



# Control-To-Output Transfer Function

$$N \cdot D' \cdot \hat{v}_C(s) = \frac{R' \parallel \frac{1}{s \cdot C'}}{s \cdot L + D \cdot R_{ON} + R' \parallel \frac{1}{s \cdot C'}} \cdot V' \cdot \hat{d}(t)$$

$$G_{vd1}(s) = \frac{\hat{v}_C(s)}{\hat{d}(t)} = \frac{V'}{N \cdot D'} \cdot \frac{R' \parallel \frac{1}{s \cdot C'}}{s \cdot L + D \cdot R_{ON} + R' \parallel \frac{1}{s \cdot C'}}$$



# Control-To-Output Transfer Function

$$\begin{aligned}
 R' \parallel \frac{1}{s \cdot C'} &= \frac{R' \cdot \frac{1}{s \cdot C'}}{R' + \frac{1}{s \cdot C'}} \cdot \frac{s \cdot C'}{s \cdot C'} = \frac{R'}{1 + s \cdot R' \cdot C'} \\
 \frac{R' \parallel \frac{1}{s \cdot C'}}{s \cdot L + D \cdot R_{ON} + R' \parallel \frac{1}{s \cdot C'}} &= \frac{\frac{R'}{1 + s \cdot R' \cdot C'}}{s \cdot L + D \cdot R_{ON} + \frac{R'}{1 + s \cdot R' \cdot C'}} \cdot \frac{1 + s \cdot R' \cdot C'}{1 + s \cdot R' \cdot C'} \\
 &= \frac{R'}{s \cdot L + s^2 \cdot R' \cdot C' \cdot L + D \cdot R_{ON} + s \cdot D \cdot R_{ON} \cdot R' \cdot C' + R'} \\
 &= \frac{R'}{R' + D \cdot R_{ON} + s \cdot L + s \cdot D \cdot R_{ON} \cdot R' \cdot C' + s^2 \cdot R' \cdot C' \cdot L} \cdot \frac{1}{\frac{R'}{R'}} \\
 &= \frac{1}{1 + \frac{D \cdot R_{ON}}{R'} + s \cdot \left( \frac{L}{R'} + D \cdot R_{ON} \cdot C' \right) + s^2 \cdot C' \cdot L}
 \end{aligned}$$

# Control-To-Output Transfer Function

$$\frac{R' \parallel \frac{1}{s \cdot C'}}{s \cdot L + D \cdot R_{ON} + R' \parallel \frac{1}{s \cdot C'}} = \frac{1}{1 + \frac{D \cdot R_{ON}}{R'} + s \cdot \left( \frac{L}{R'} + D \cdot R_{ON} \cdot C' \right) + s^2 \cdot C' \cdot L}$$

$$R' = (N \cdot D')^2 \cdot R$$

$$C' = \frac{C}{(N \cdot D')^2}$$

$$= \frac{1}{1 + \frac{D \cdot R_{ON}}{(N \cdot D')^2 \cdot R} + s \cdot \left( \frac{L}{(N \cdot D')^2 \cdot R} + D \cdot R_{ON} \cdot \frac{C}{(N \cdot D')^2} \right) + s^2 \cdot \frac{C}{(N \cdot D')^2} \cdot L}$$

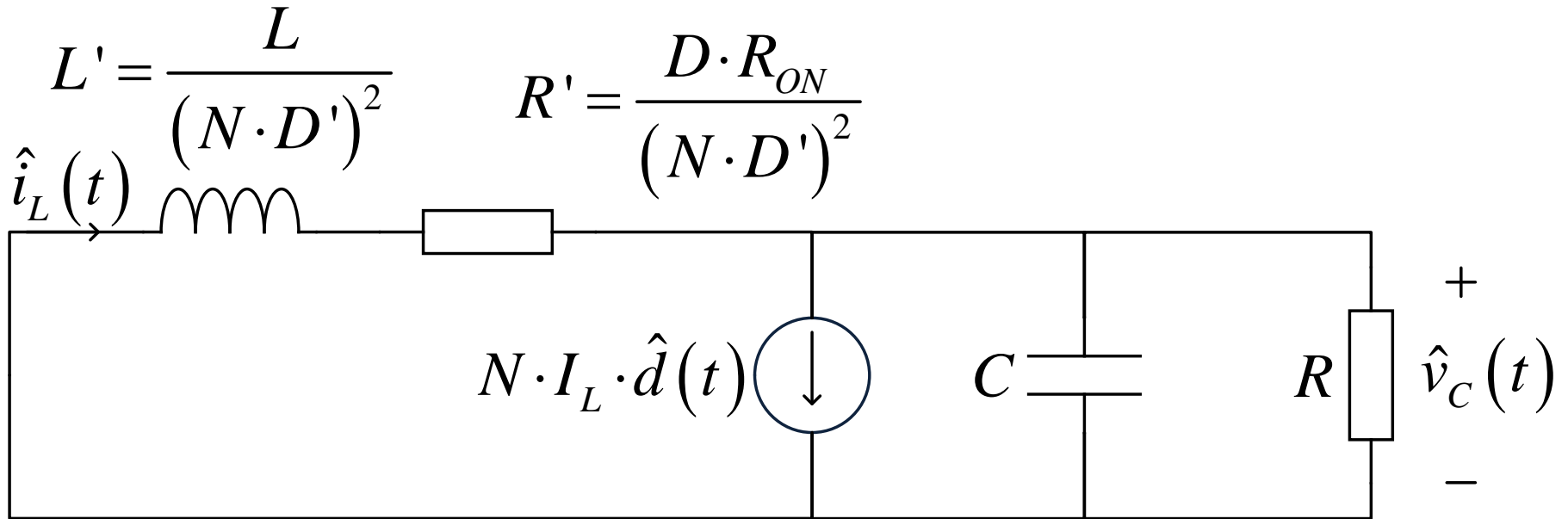
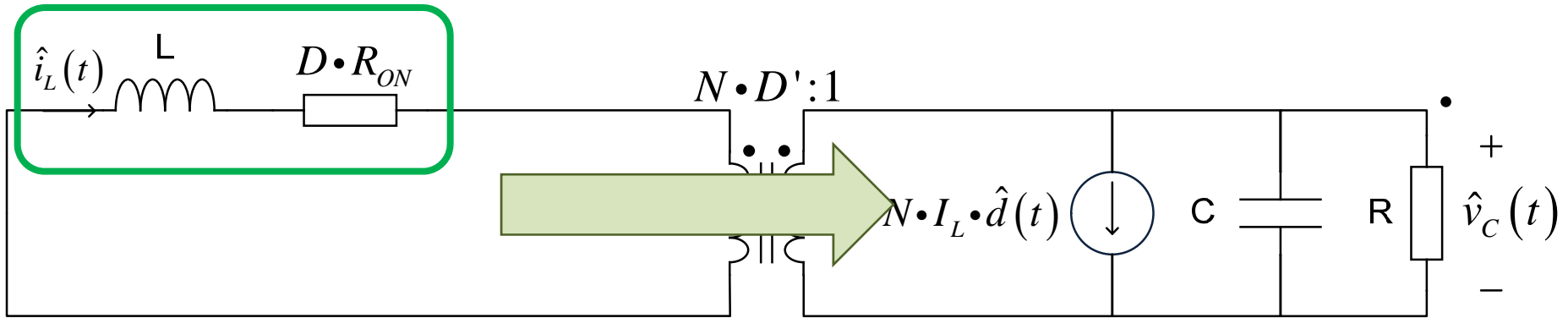


# Control-To-Output Transfer Function

$$G_{vd1}(s) = \frac{V'}{N \cdot D'} \cdot \frac{1}{1 + \frac{D \cdot R_{ON}}{(N \cdot D')^2 \cdot R} + s \cdot \left( \frac{L}{(N \cdot D')^2 \cdot R} + \frac{D \cdot R_{ON} \cdot C}{(N \cdot D')^2} \right) + s^2 \cdot \frac{L \cdot C}{(N \cdot D')^2}}$$

$$V' = V_g - R_{ON} \cdot I_L + N \cdot (V_C + V_D)$$

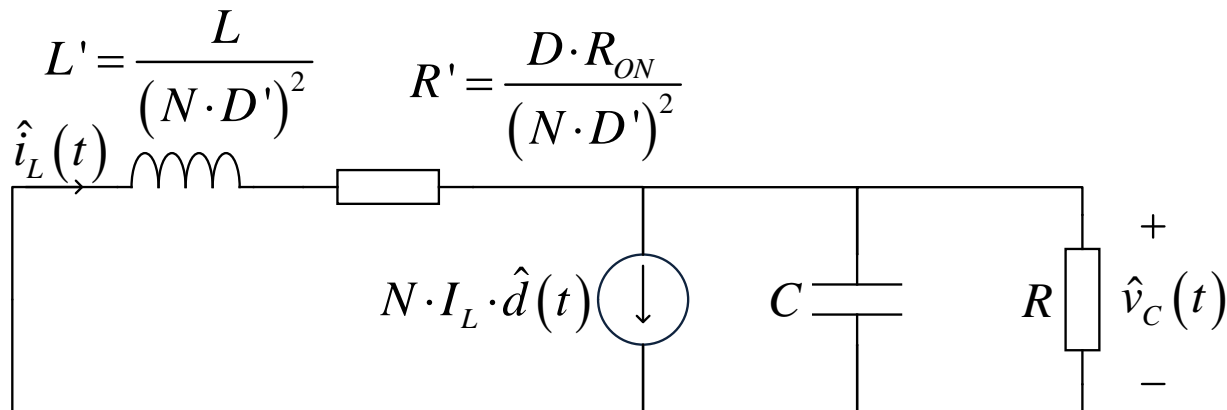
# Control-To-Output Transfer Function



# Control-To-Output Transfer Function

$$\hat{v}_C(t) = -N \cdot I_L \cdot \hat{d}(t) \cdot \left[ (s \cdot L' + R') \parallel \left( \frac{1}{s \cdot C} \right) \parallel R \right]$$

$$= -N \cdot I_L \cdot \hat{d}(t) \cdot \frac{1}{\frac{1}{s \cdot L' + R'} + \frac{1}{\frac{1}{s \cdot C}} + \frac{1}{R}}$$



# Control-To-Output Transfer Function

$$\begin{aligned} \frac{1}{\frac{1}{s \cdot L' + R'} + \frac{1}{s \cdot C} + \frac{1}{R}} &= \frac{1}{\frac{1}{s \cdot L' + R'} + s \cdot C + \frac{1}{R}} \\ &= \frac{1}{\frac{1}{s \cdot L' + R'} + \frac{1 + s \cdot R \cdot C}{R}} \\ &= \frac{1}{\frac{R + (s \cdot L' + R') \cdot (1 + s \cdot R \cdot C)}{R \cdot (s \cdot L' + R')}} \\ &= \frac{R \cdot (s \cdot L' + R')}{R + s \cdot L' + R' + s \cdot R \cdot C \cdot R' + s^2 \cdot R \cdot L' \cdot C} \end{aligned}$$

# Control-To-Output Transfer Function

$$\frac{1}{\frac{1}{s \cdot L' + R'} + \frac{1}{s \cdot C} + \frac{1}{R}} = \frac{R \cdot (s \cdot L' + R')}{R + R' + s \cdot L' + s \cdot R \cdot C \cdot R' + s^2 \cdot R \cdot L' \cdot C} \cdot \frac{1}{R}$$

$$= \frac{s \cdot L' + R'}{1 + \frac{R'}{R} + s \cdot \left( \frac{L'}{R} + R' \cdot C \right) + s^2 \cdot L' \cdot C}$$

$$L' = \frac{L}{(N \cdot D')^2}$$

$$R' = \frac{D \cdot R_{ON}}{(N \cdot D')^2}$$

# Control-To-Output Transfer Function

$$\begin{aligned}
 &= \frac{s \cdot \frac{L}{(N \cdot D')^2} + \frac{D \cdot R_{ON}}{(N \cdot D')^2}}{1 + \frac{D \cdot R_{ON}}{(N \cdot D')^2} + \frac{D \cdot R_{ON}}{R} + s \cdot \left( \frac{L}{(N \cdot D')^2} + \frac{D \cdot R_{ON}}{(N \cdot D')^2} \cdot C \right) + s^2 \cdot \frac{L}{(N \cdot D')^2} \cdot C} \\
 &= \frac{1}{(N \cdot D')^2} \cdot (s \cdot L + D \cdot R_{ON})}{1 + \frac{D \cdot R_{ON}}{(N \cdot D')^2} \cdot R + s \cdot \left( \frac{L}{(N \cdot D')^2} \cdot R + \frac{D \cdot R_{ON} \cdot C}{(N \cdot D')^2} \right) + s^2 \cdot \frac{L \cdot C}{(N \cdot D')^2}}
 \end{aligned}$$

# Control-To-Output Transfer Function

$$G_{vd2}(s) = \frac{\hat{v}_c(t)}{\hat{d}(t)}$$

$$= -N \cdot I_L \cdot \frac{\frac{1}{(N \cdot D')^2} \cdot (s \cdot L + D \cdot R_{ON})}{1 + \frac{D \cdot R_{ON}}{(N \cdot D')^2 \cdot R} + s \cdot \left( \frac{L}{(N \cdot D')^2 \cdot R} + \frac{D \cdot R_{ON} \cdot C}{(N \cdot D')^2} \right) + s^2 \cdot \frac{L \cdot C}{(N \cdot D')^2}}$$

# Control-To-Output Transfer Function

$$G_{vd}(s) = G_{vd1}(s) + G_{vd2}(s)$$

$$G_{vd}(s) = \frac{\text{num}(G_{vd}(s))}{\text{den}(G_{vd}(s))} = \frac{\text{num}(G_{vd1}(s))}{\text{den}(G_{vd1}(s))} + \frac{\text{num}(G_{vd2}(s))}{\text{den}(G_{vd2}(s))}$$

$$\text{den}(G_{vd1}(s)) = \text{den}(G_{vd2}(s)) = \text{den}(G_{vd}(s))$$

$$G_{vd}(s) = \frac{\text{num}(G_{vd}(s))}{\text{den}(G_{vd}(s))} = \frac{\text{num}(G_{vd1}(s)) + \text{num}(G_{vd2}(s))}{\text{den}(G_{vd}(s))}$$



# Control-To-Output Transfer Function

$$\text{num}(G_{vd1}(s)) = \frac{V'}{N \cdot D'}$$

$$\text{num}(G_{vd2}(s)) = -N \cdot I_L \cdot \frac{1}{(N \cdot D')^2} \cdot (s \cdot L + D \cdot R_{ON})$$

$$\text{num}(G_{vd1}(s)) + \text{num}(G_{vd2}(s)) = \frac{V'}{N \cdot D'} - N \cdot I_L \cdot \frac{1}{(N \cdot D')^2} \cdot (s \cdot L + D \cdot R_{ON})$$

# Control-To-Output Transfer Function



$$\begin{aligned} num(G_{vd1}(s)) + num(G_{vd2}(s)) &= \frac{V' \cdot N \cdot D'}{(N \cdot D')^2} - \frac{N \cdot I_L \cdot (s \cdot L + D \cdot R_{ON})}{(N \cdot D')^2} \\ &= \frac{V' \cdot N \cdot D' - N \cdot D \cdot R_{ON} \cdot I_L - s \cdot N \cdot I_L \cdot L}{(N \cdot D')^2} \\ &= \frac{V' \cdot N \cdot D' - N \cdot D \cdot R_{ON} \cdot I_L}{(N \cdot D')^2} \cdot \left( 1 - s \cdot \frac{N \cdot I_L \cdot L}{V' \cdot N \cdot D' - N \cdot D \cdot R_{ON} \cdot I_L} \right) \\ &= \frac{V' \cdot D' - D \cdot R_{ON} \cdot I_L}{N \cdot D'^2} \cdot \left( 1 - s \cdot \frac{N \cdot I_L \cdot L}{V' \cdot N \cdot D' - N \cdot D \cdot R_{ON} \cdot I_L} \right) \end{aligned}$$

# Control To Output Transfer Function



Quick check on the algebra: Are the units correct?

$$1 - s \cdot \frac{N \cdot I_L \cdot L}{V' \cdot N \cdot D' - N \cdot D \cdot R_{ON} \cdot I_L}$$
$$\Rightarrow \frac{1}{s} \cdot A \cdot \frac{v \cdot s}{A} \Rightarrow \frac{v}{v} \Rightarrow \text{Dimensionless}$$

# Control-To-Output Transfer Function



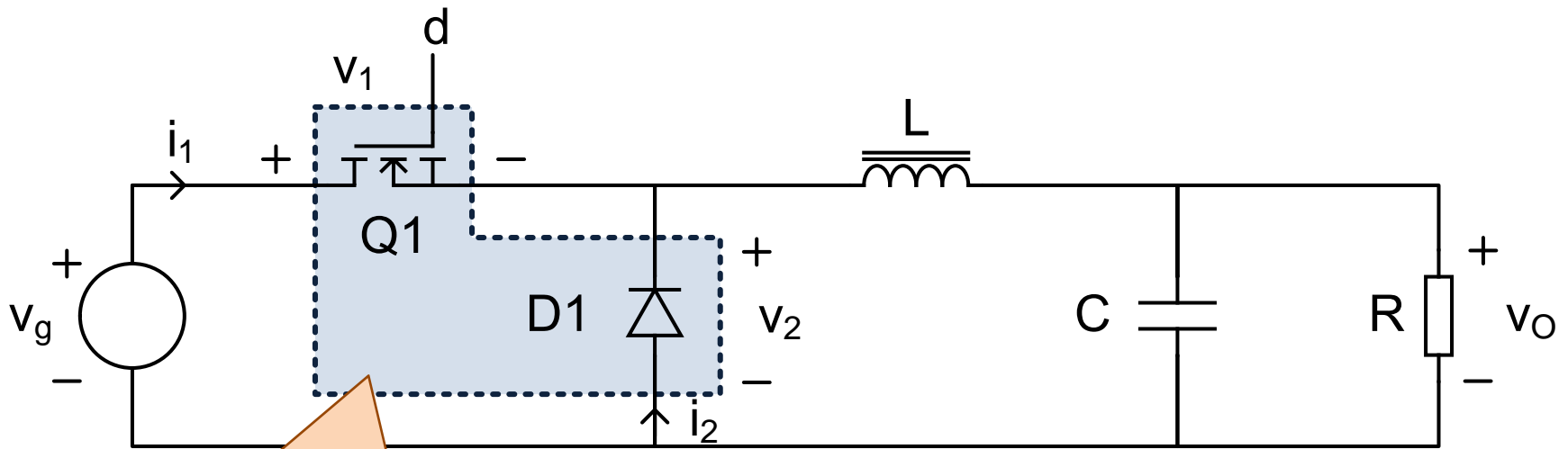
$$G_{vd}(s) = \frac{\frac{V' \cdot D' - D \cdot R_{ON} \cdot I_L}{N \cdot D'^2} \cdot \left( 1 - s \cdot \frac{N \cdot I_L \cdot L}{V' \cdot N \cdot D' - N \cdot D \cdot R_{ON} \cdot I_L} \right)}{1 + \frac{D \cdot R_{ON}}{(N \cdot D')^2 \cdot R} + s \cdot \left( \frac{L}{(N \cdot D')^2 \cdot R} + \frac{D \cdot R_{ON} \cdot C}{(N \cdot D')^2} \right) + s^2 \cdot \frac{L \cdot C}{(N \cdot D')^2}}$$

$$V' = V_g - R_{ON} \cdot I_L + N \cdot (V_C + V_D)$$

# Averaging Summary

- Write Circuit Differential Equations For Each State In Terms Of Averaged Values
- Average Over One Switching Cycle
  - Inductor Current
  - Capacitor Voltages
- Perturb And Linearize
  - DC Terms Are Zero
  - Discard 2<sup>nd</sup> And Higher Order Terms
- Construct The Circuit Model

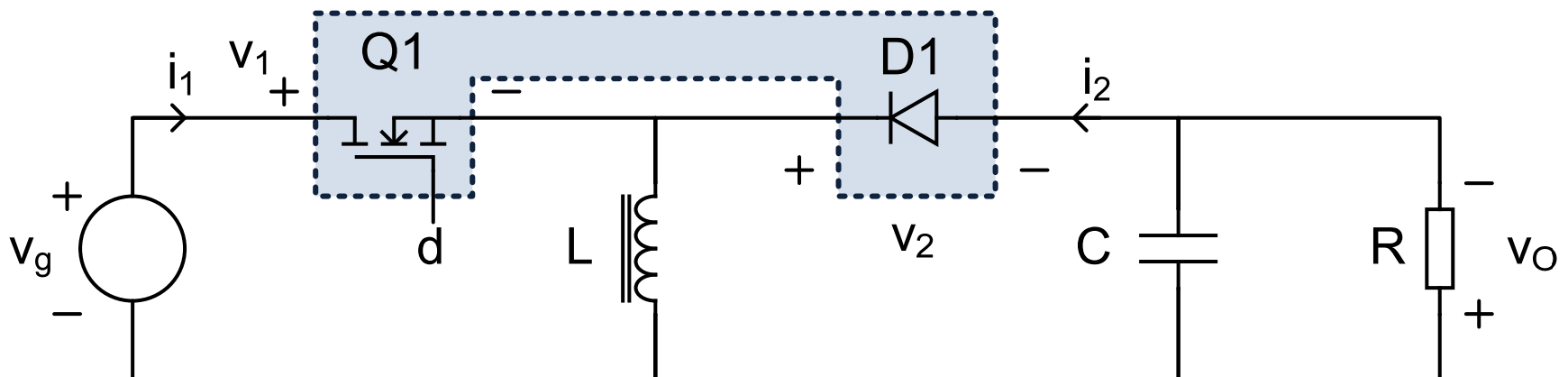
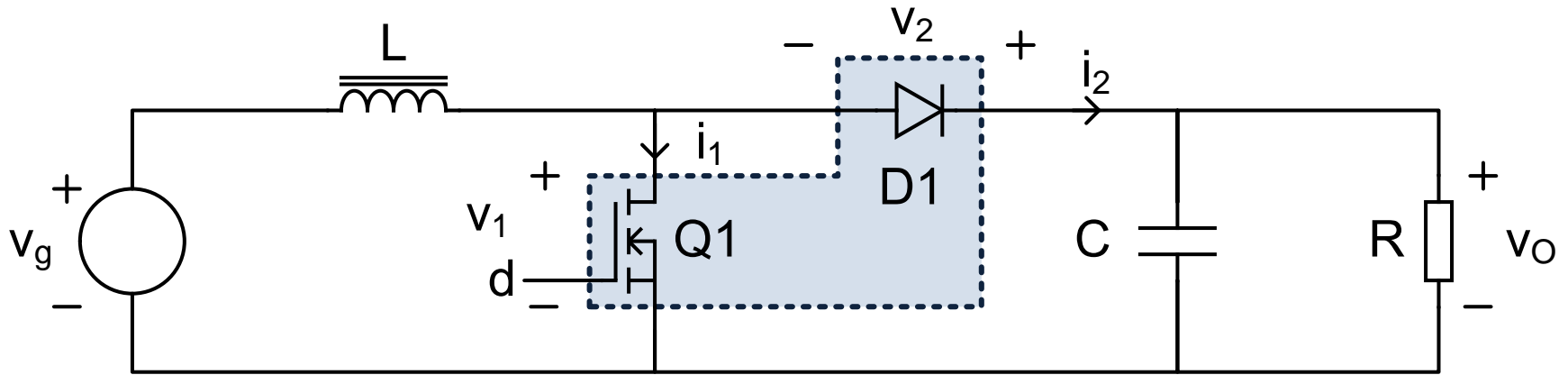
# Averaged Switch Modeling



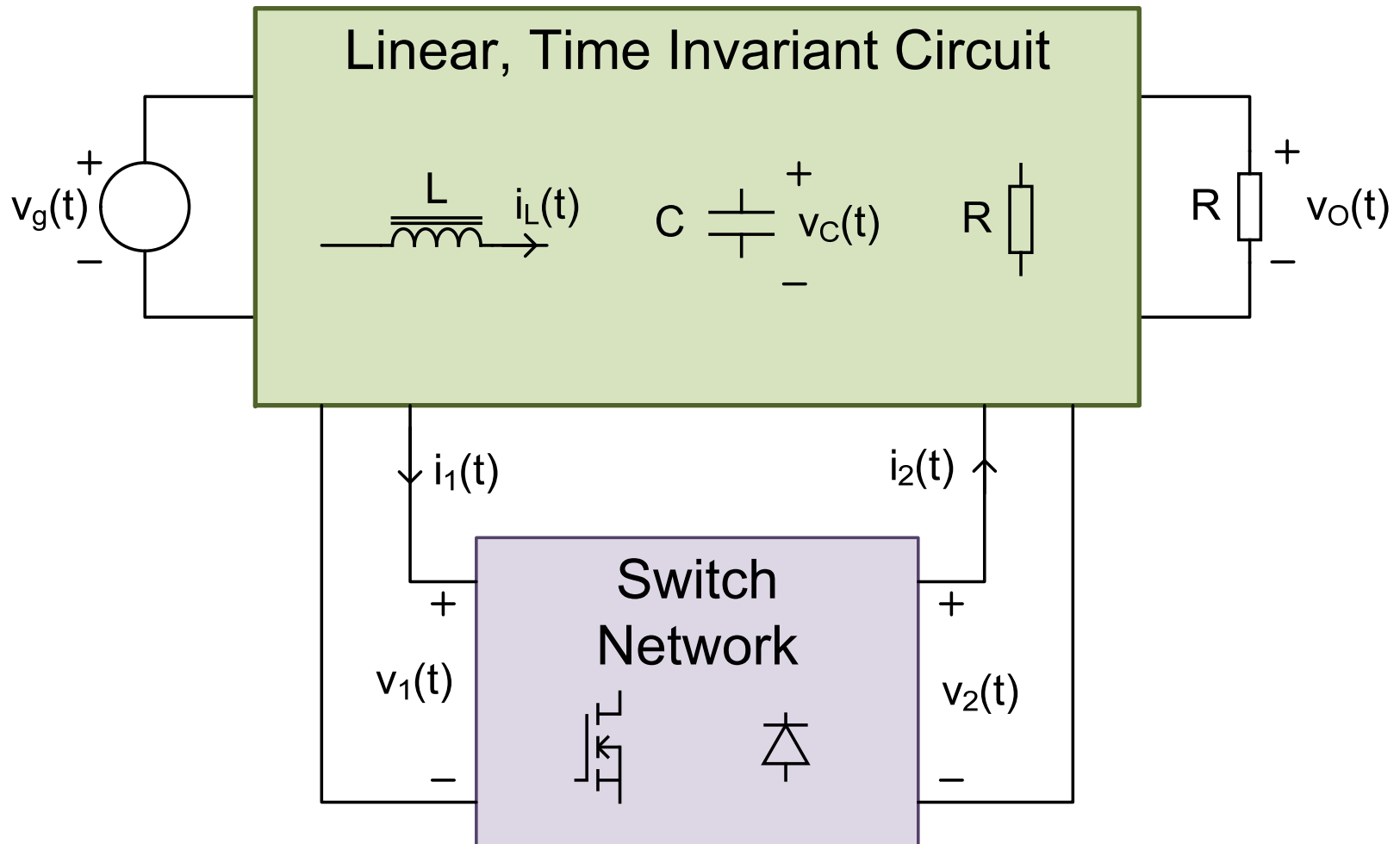
Two Port Switch Network  
Includes All Nonlinear  
And Time Varying Elements

Everything  
Else Is  
LTI

# Boost And Buck-Boost Switch Networks

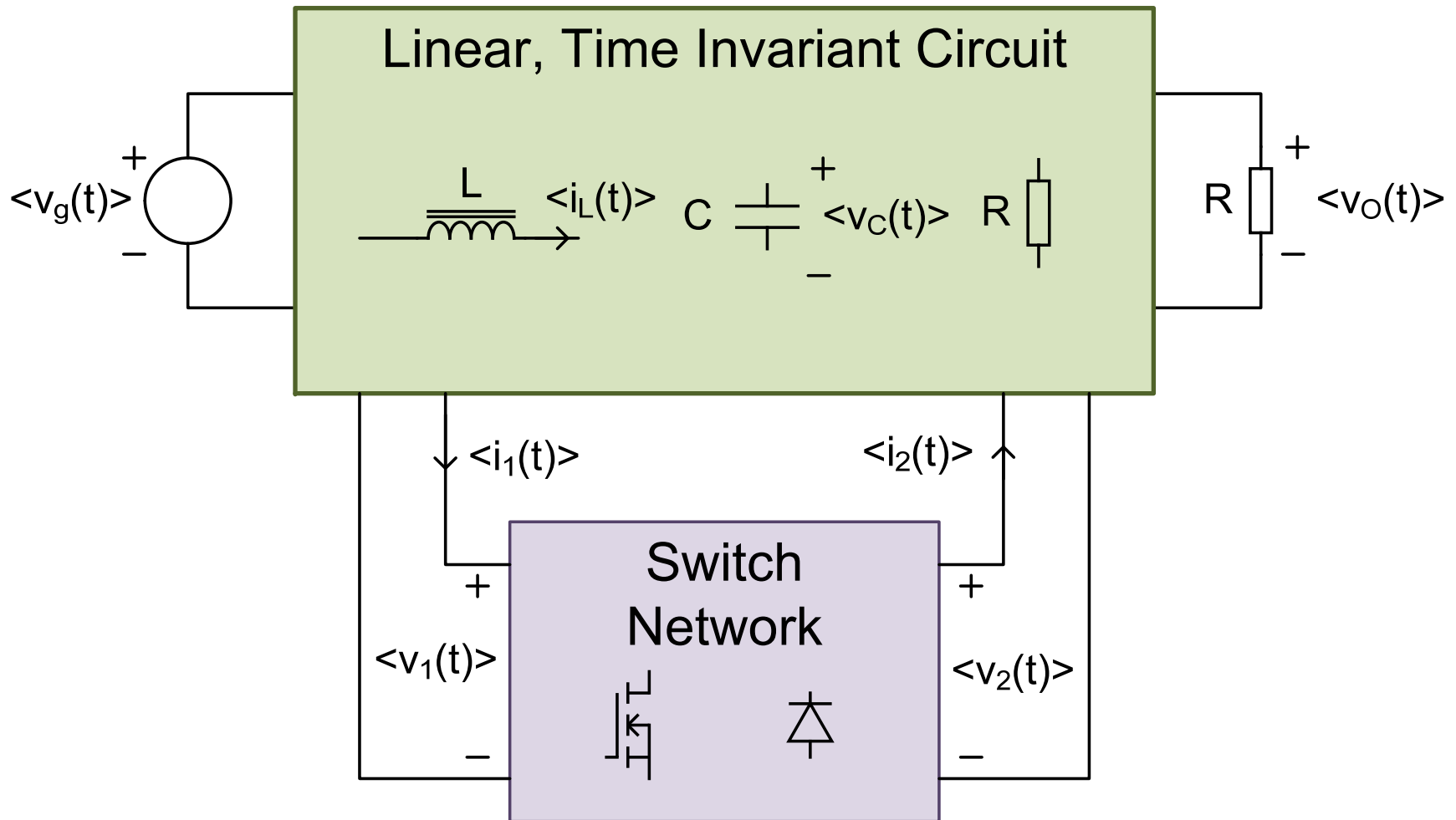


# Averaged Switch Modeling

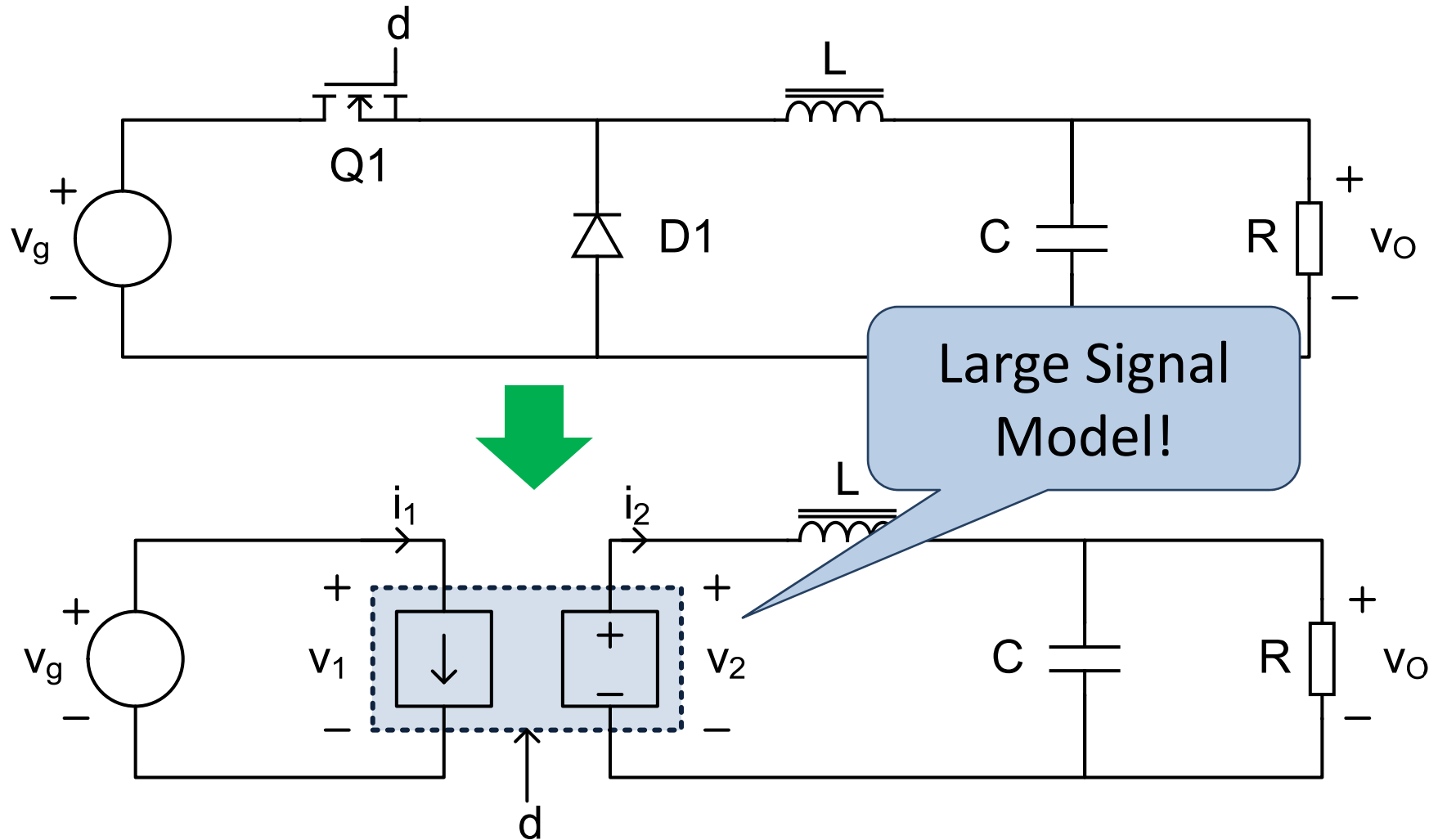




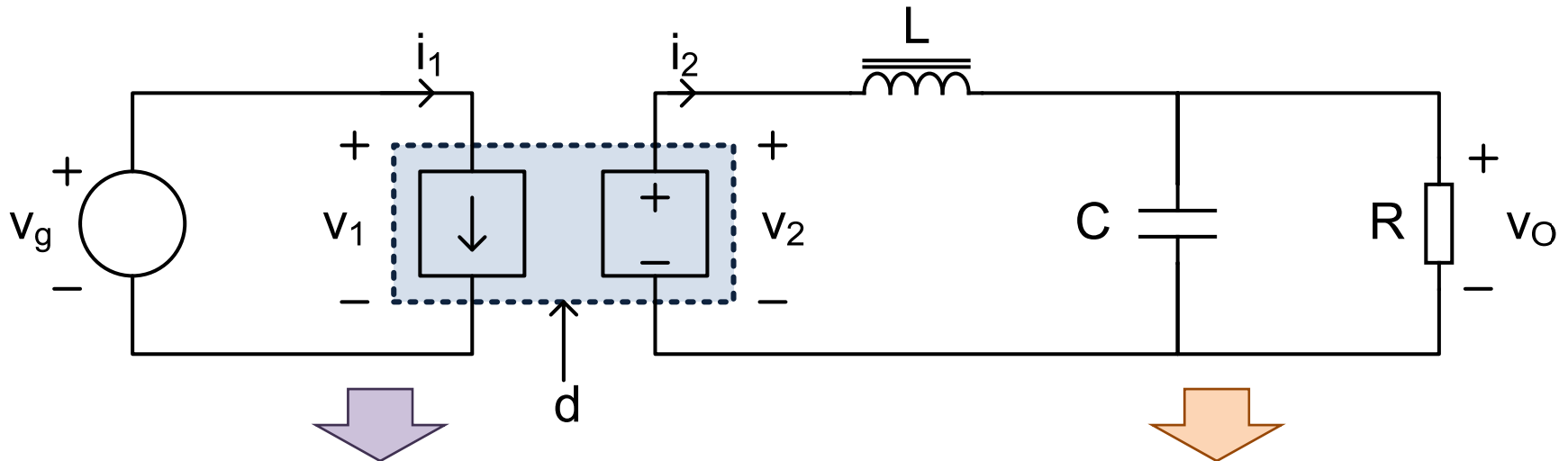
# Averaged Switch Modeling



# Averaged Switch Modeling



# Averaged Switch Modeling



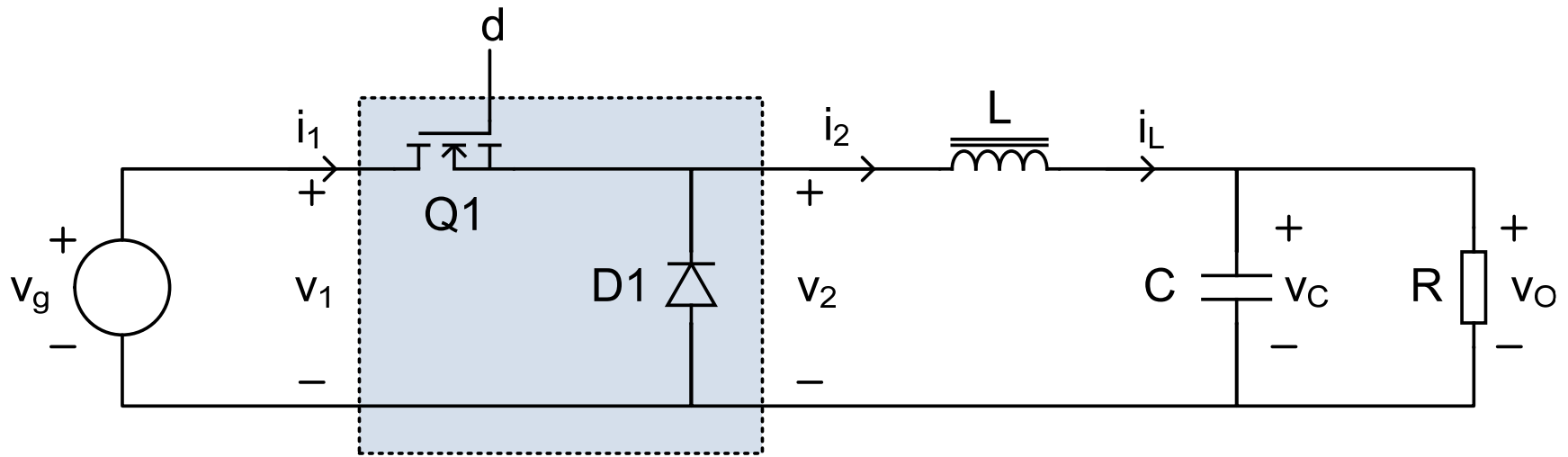
## Circuit Simulation

Time Domain  
(e.g. Transient Response)  
Frequency Domain  
(e.g. Bode Plots)

## Linearization

Small Signal  
Analytical Models  
 $\Rightarrow$  Transfer Functions

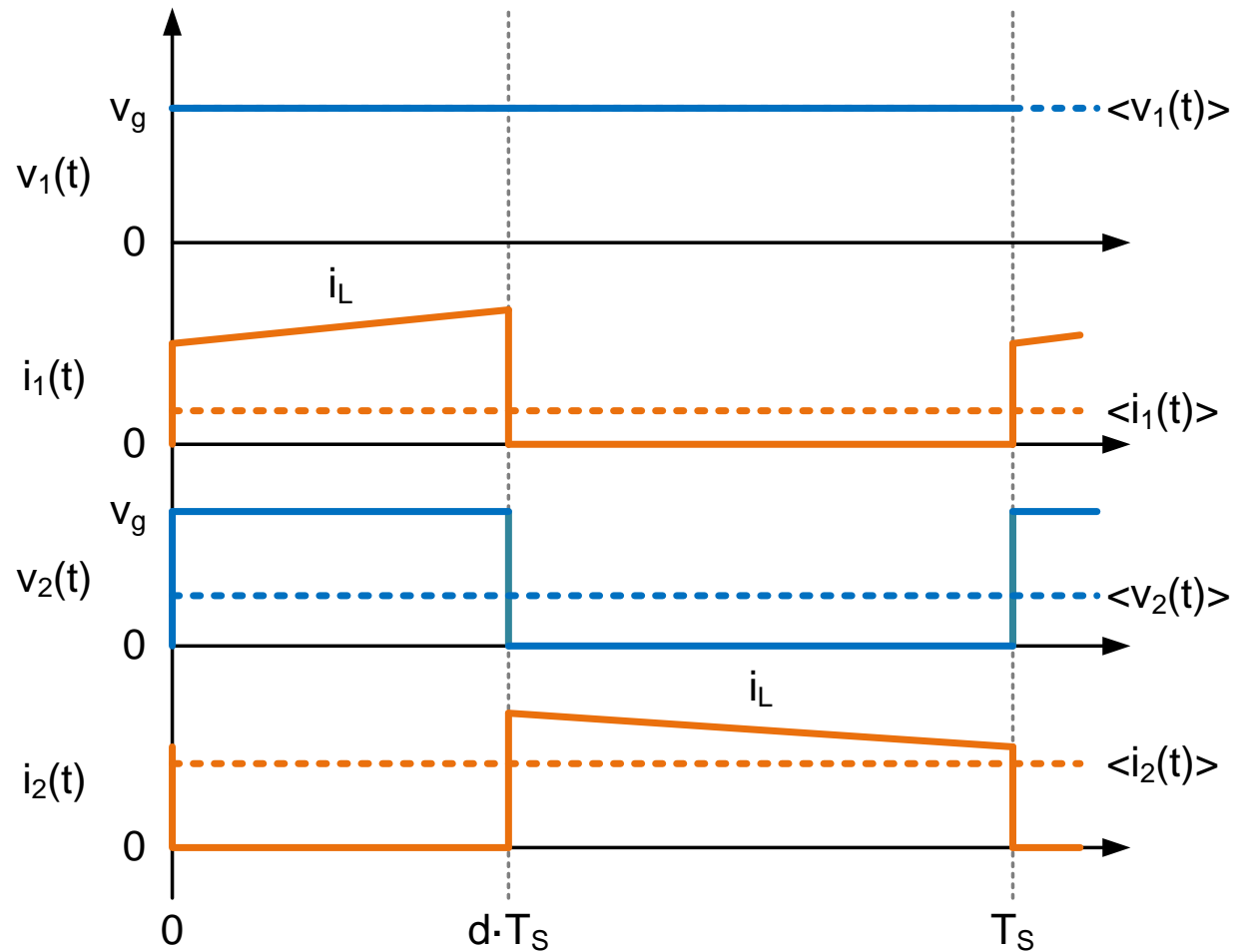
# Buck Converter Model: Define Switch Network And Ports



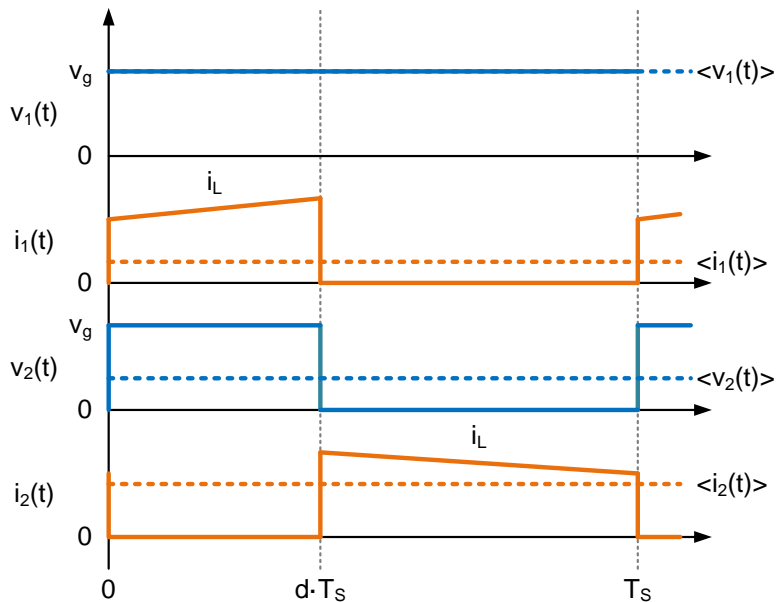
Port 1:  $v_1, i_1$

Port 2:  $v_2, i_2$

# Buck Converter Model: Sketch Waveforms



# Buck Converter Model: Average Switch Network Variables



$$\begin{aligned} \langle v_1(t) \rangle &= d \cdot \langle v_g(t) \rangle + d' \cdot \langle v_g(t) \rangle \\ &= \langle v_g(t) \rangle \end{aligned}$$

$$\begin{aligned} \langle i_1(t) \rangle &= d \cdot \langle i_L(t) \rangle + d' \cdot 0 \\ &= d \cdot \langle i_L(t) \rangle \end{aligned}$$

$$\begin{aligned} \langle v_2(t) \rangle &= d \cdot \langle v_g(t) \rangle + d' \cdot 0 \\ &= d \cdot \langle v_g(t) \rangle \end{aligned}$$

$$\begin{aligned} \langle i_2(t) \rangle &= d \cdot \langle i_L(t) \rangle + d' \cdot \langle i_L(t) \rangle \\ &= \langle i_L(t) \rangle \end{aligned}$$

# Buck Converter Model: Eliminate Non-Switch Variables

$$\begin{aligned}\langle v_1(t) \rangle &= d \cdot \langle v_g(t) \rangle + d' \cdot \langle v_g(t) \rangle \\ &= \langle v_g(t) \rangle\end{aligned}$$

$$\begin{aligned}\langle i_1(t) \rangle &= d \cdot \langle i_L(t) \rangle + d' \cdot 0 \\ &= d \cdot \langle i_L(t) \rangle\end{aligned}$$

$$\begin{aligned}\langle v_2(t) \rangle &= d \cdot \langle v_g(t) \rangle + d' \cdot 0 \\ &= d \cdot \langle v_g(t) \rangle\end{aligned}$$

$$\begin{aligned}\langle i_2(t) \rangle &= d \cdot \langle i_L(t) \rangle + d' \cdot \langle i_L(t) \rangle \\ &= \langle i_L(t) \rangle\end{aligned}$$

$$\langle v_2(t) \rangle = d \cdot \langle v_g(t) \rangle = d \cdot \langle v_1(t) \rangle$$

# Buck Converter Model: Eliminate Non-Switch Variables

$$\begin{aligned}\langle v_1(t) \rangle &= d \cdot \langle v_g(t) \rangle + d' \cdot \langle v_g(t) \rangle \\ &= \langle v_g(t) \rangle\end{aligned}$$

$$\begin{aligned}\langle i_1(t) \rangle &= d \cdot \langle i_L(t) \rangle + d' \cdot 0 \\ &= d \cdot \langle i_L(t) \rangle\end{aligned}$$

$$\langle v_2(t) \rangle = d \cdot \langle v_g(t) \rangle = d \cdot \langle v_1(t) \rangle$$

$$\begin{aligned}\langle v_2(t) \rangle &= d \cdot \langle v_g(t) \rangle + d' \cdot 0 \\ &= d \cdot \langle v_g(t) \rangle\end{aligned}$$

$$\langle i_1(t) \rangle = d \cdot \langle i_L(t) \rangle = d \cdot \langle i_2(t) \rangle$$

$$\begin{aligned}\langle i_2(t) \rangle &= d \cdot \langle i_L(t) \rangle + d' \cdot \langle i_L(t) \rangle \\ &= \langle i_L(t) \rangle\end{aligned}$$

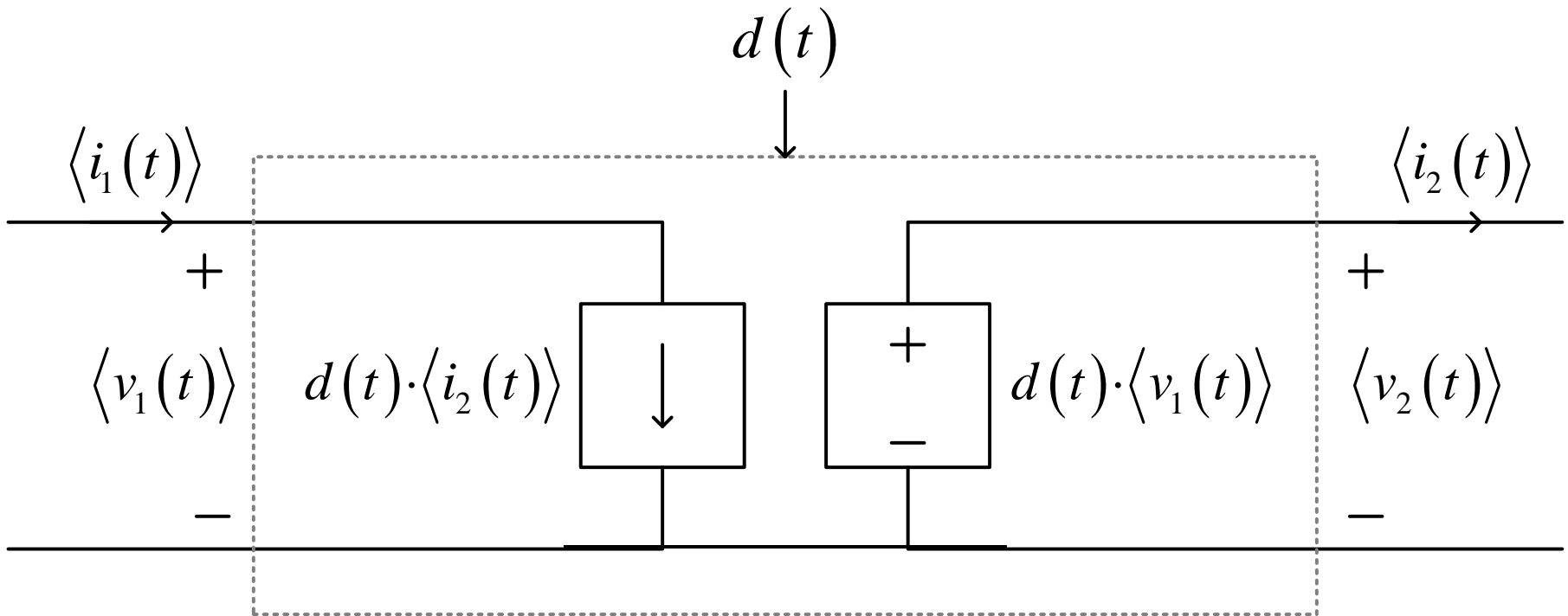


# Buck Converter Model: Create Switch Network Model

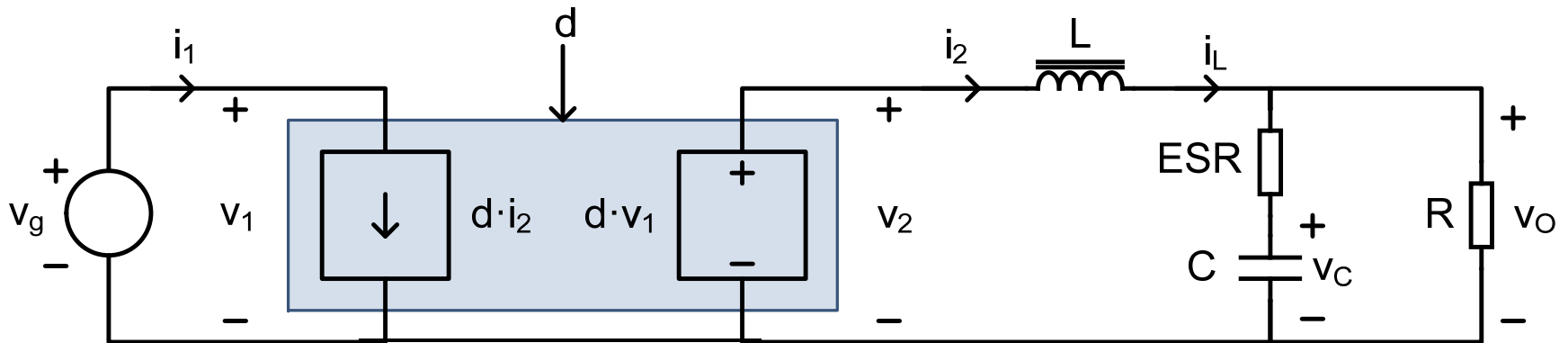


$$\langle i_1(t) \rangle = d(t) \cdot \langle i_2(t) \rangle$$

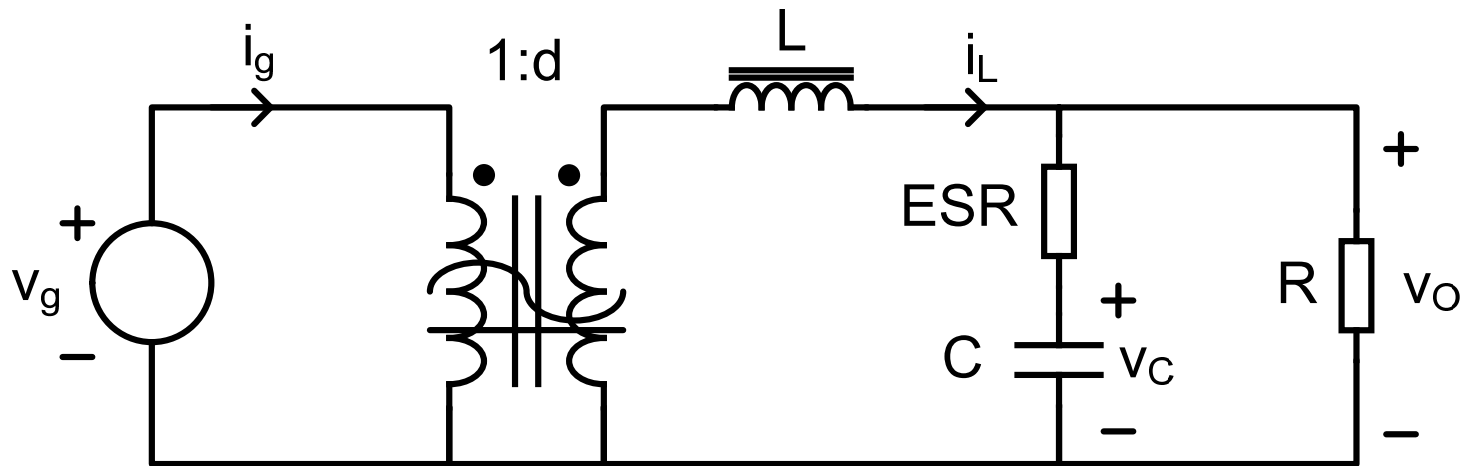
$$\langle v_2(t) \rangle = d(t) \cdot \langle v_1(t) \rangle$$



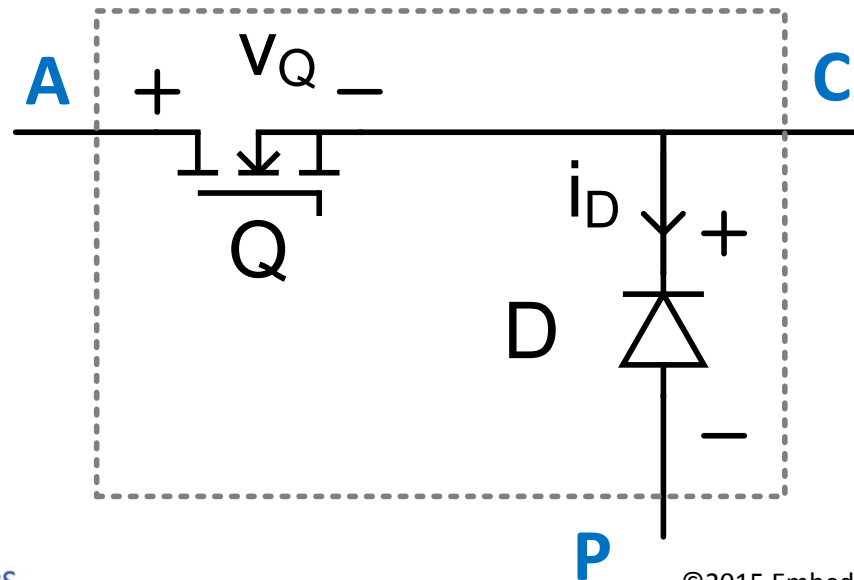
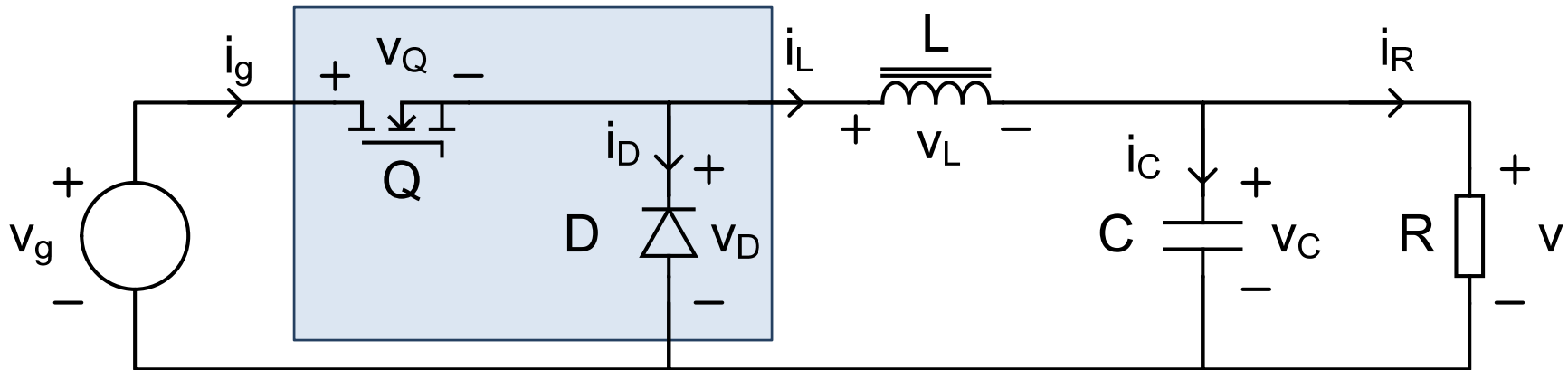
# Buck Converter Model: Complete The Converter Model



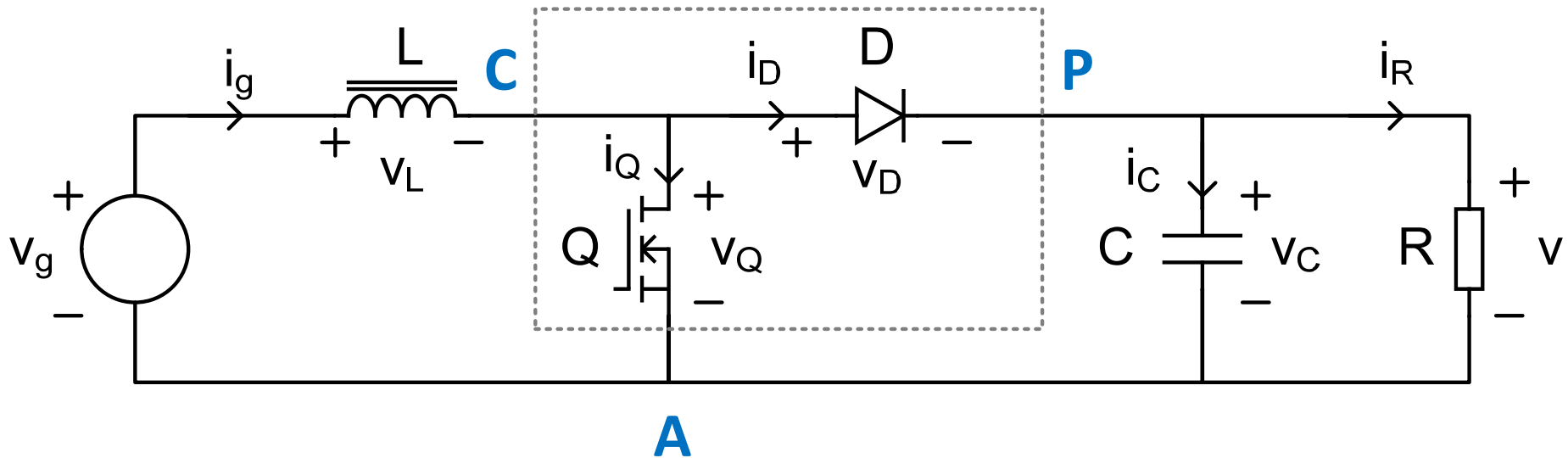
# Buck Converter Model: Complete The Converter Model



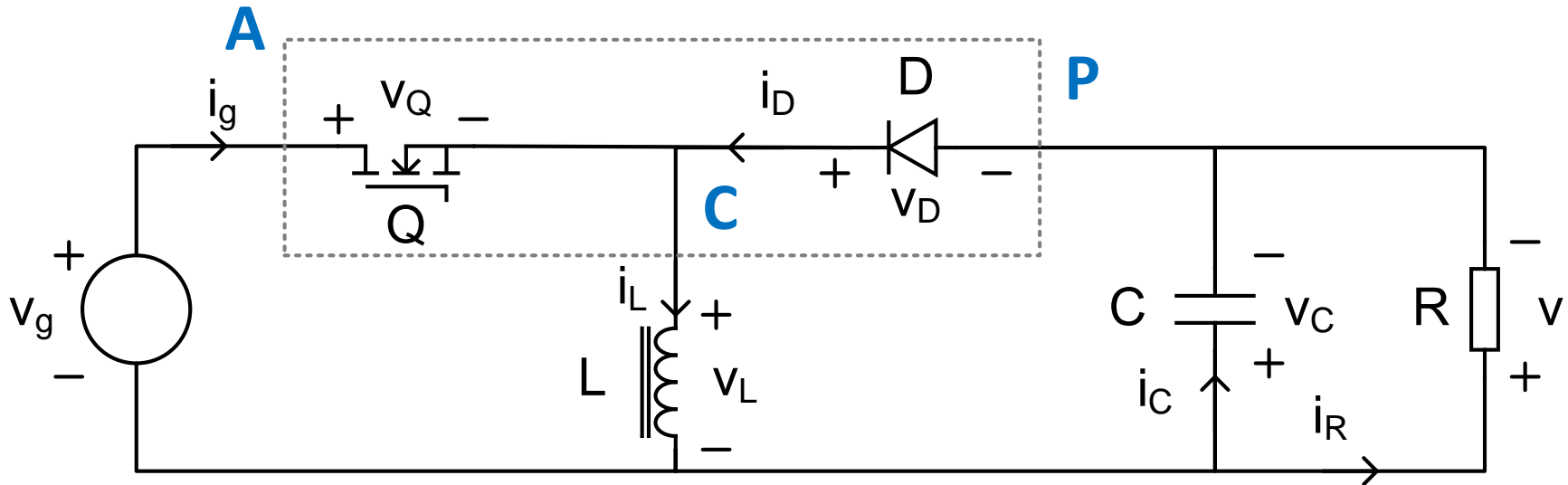
# Another View Of The Average Switch Model



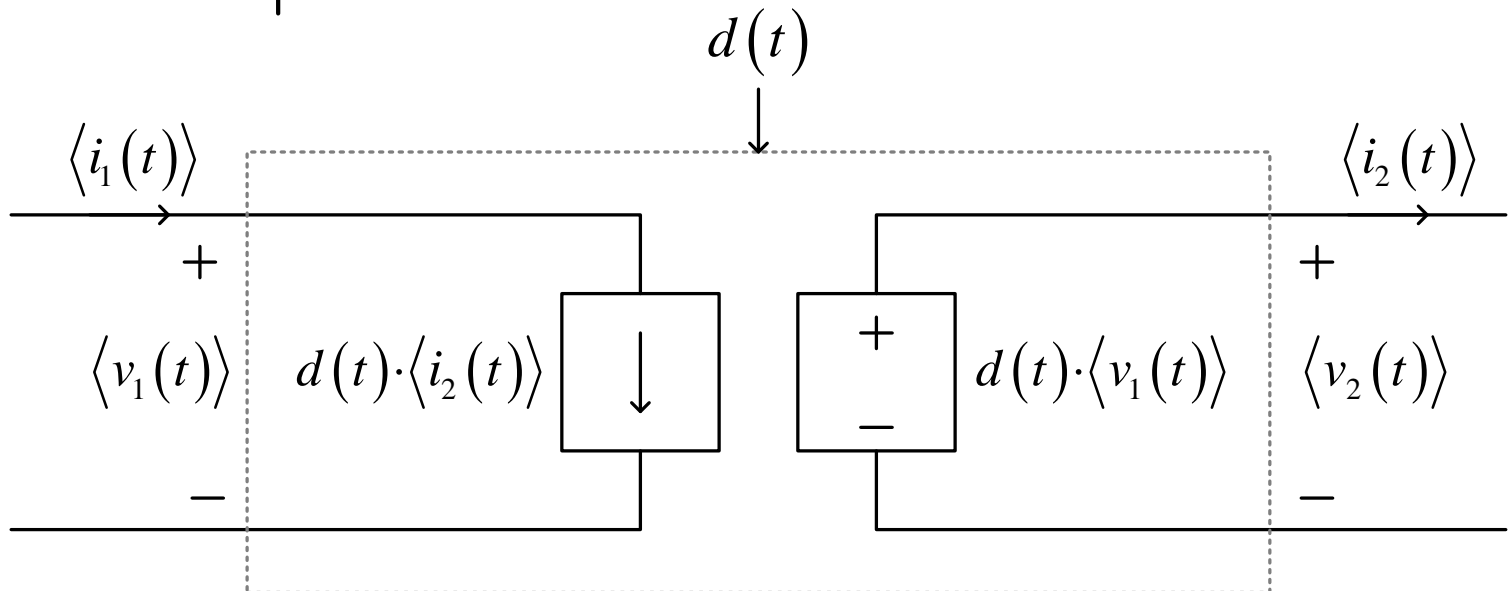
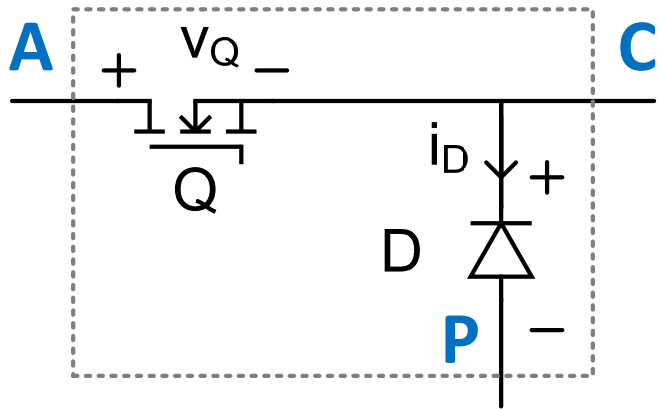
# Another View Of The Average Switch Model



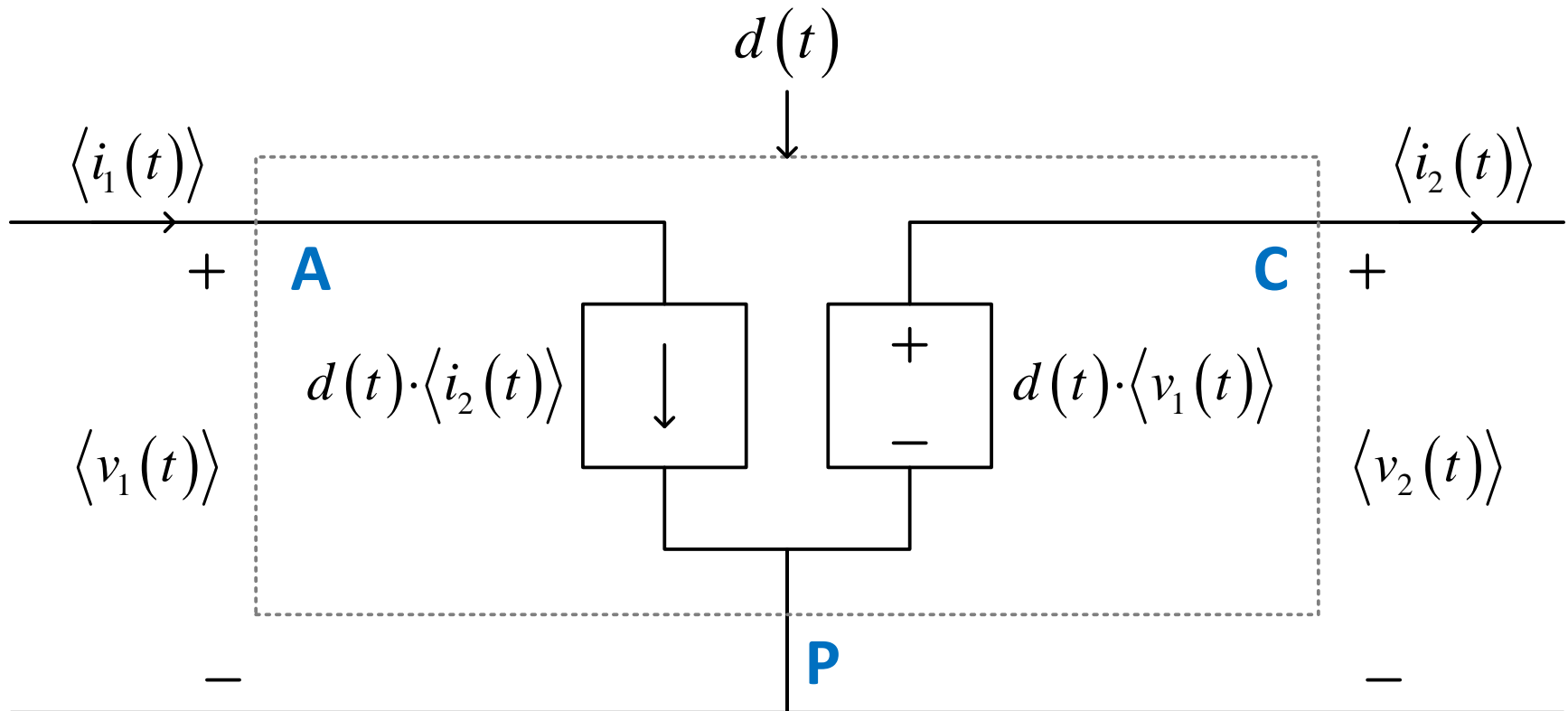
# Another View Of The Average Switch Model



# Another View Of The Average Switch Model

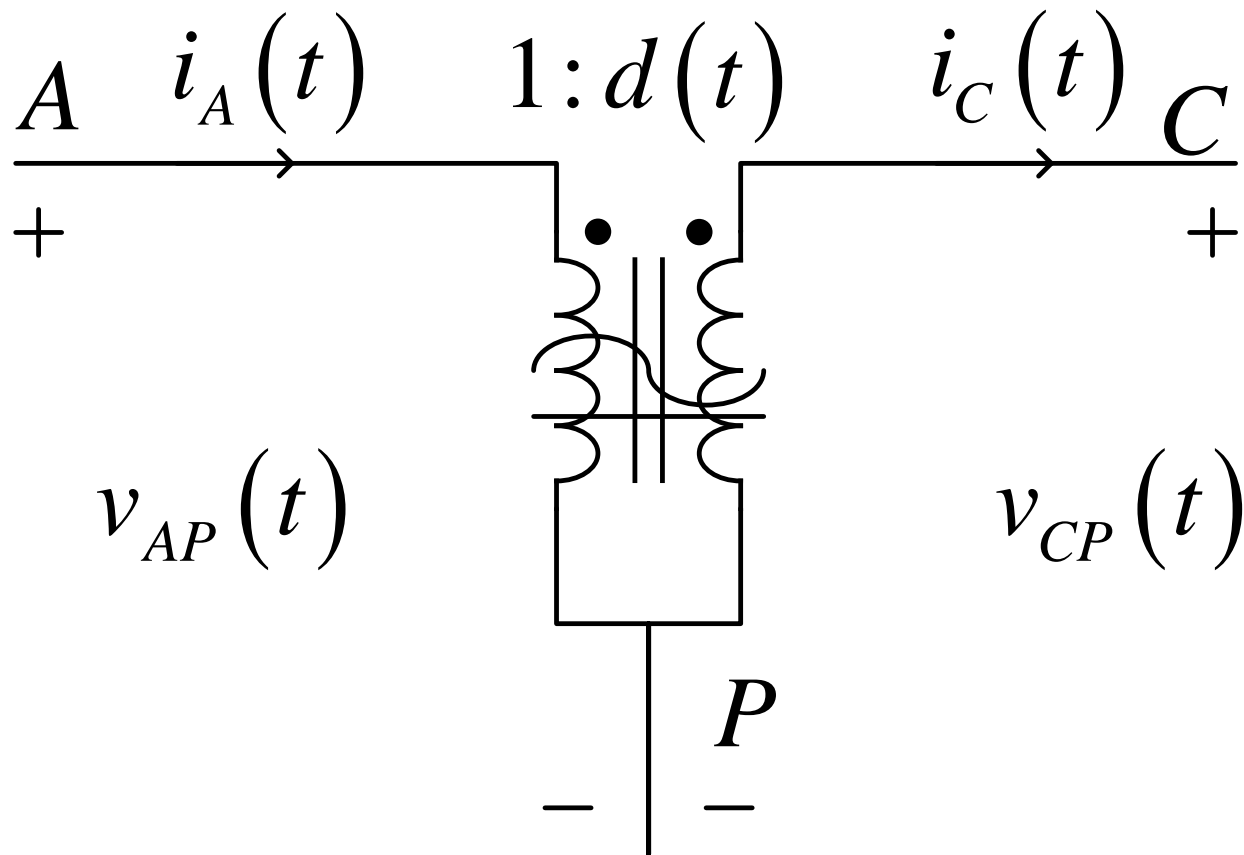


# Another View Of The Average Switch Model





# Another View Of The Average Switch Model



# Simulating Buck Converter With Averaged Switch Model

- $F_{\text{SWITCH}} = 500 \text{ kHz}$
- $V_g = 12 \text{ Vdc}$
- $V_o = 3 \text{ Vdc}$
- $D = 0.25$
- $I_o = 3 \text{ A}$
- $R_o = 1 \Omega$
- $\Delta I_L = 20\% I_o = 0.6 \text{ A} \Rightarrow$   
 $L = 7.5 \mu\text{H}$
- $C = 33 \mu\text{F}$ 
  - $\text{ESR} = 50 \text{ m}\Omega$
  - $F_{\text{ZERO}} = 96.5 \text{ kHz}$
  - $\Delta V_C = 9.1 \text{ mV}$   
(capacitor only)
- $F_o = 10.1 \text{ kHz}$
- $Q = 2.1 = 6.4 \text{ dB}$

# LTspice Model: DC Sweep

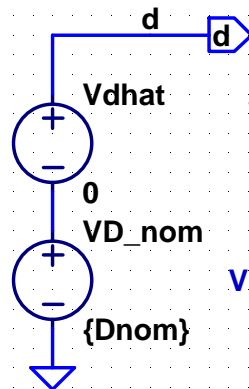
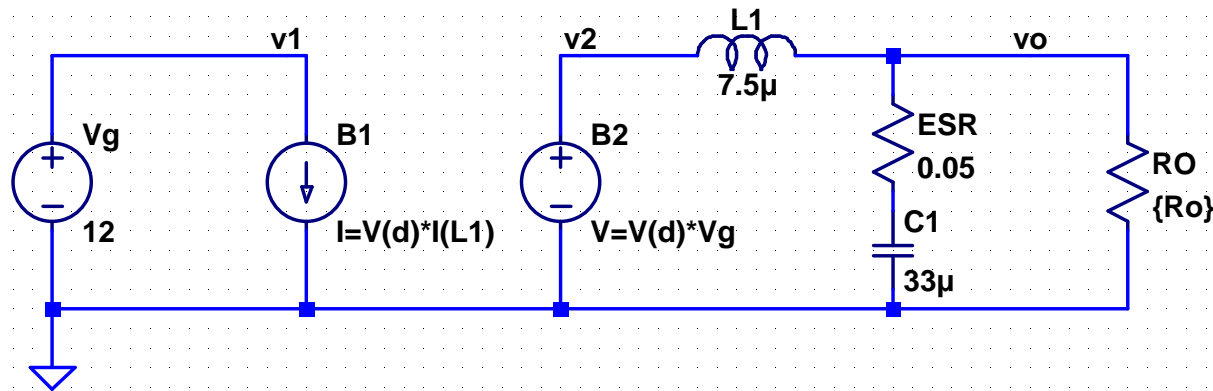


Input Parameters (Vg, Vo\_nom, Ro) Calculated Parameters (Io\_nom, Dnom)

```
.param Vg = 12  
.param Vo_nom = 3  
.param Ro = 1
```

```
.param Dnom = (Vo_nom/Vg)  
.param Io_nom = Vo_nom/Ro
```

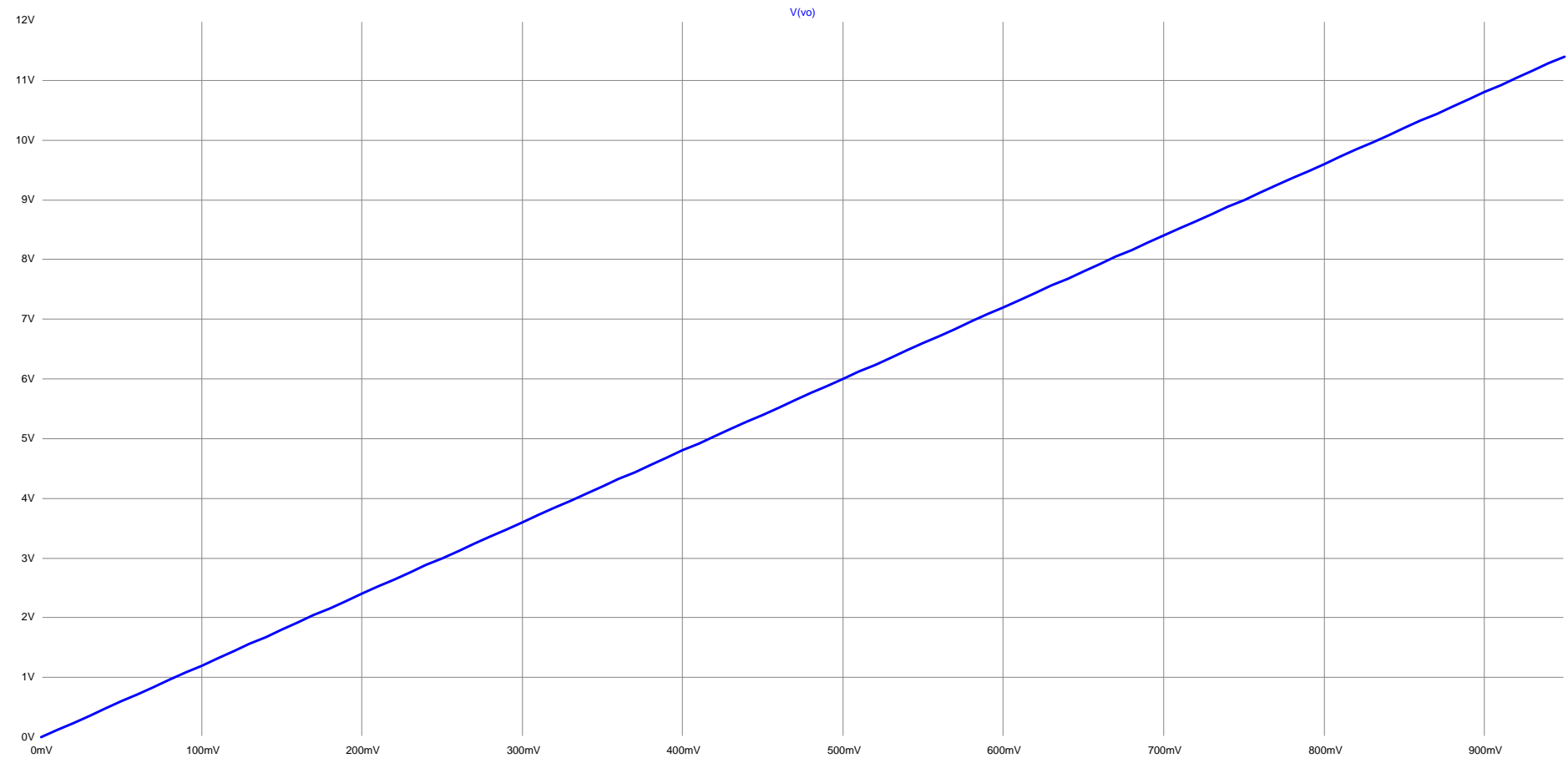
```
.dc VD_nom 0 0.95 0.01
```



Vdhat sets the variation around the dc operating point  
Set to zero for dc sweep analysis

VD\_nom sets the dc duty cycle operating point

# LTspice Model: DC Sweep



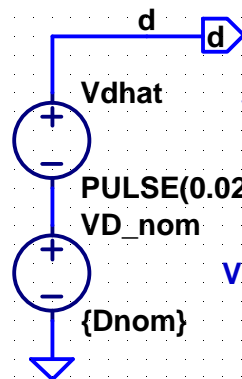
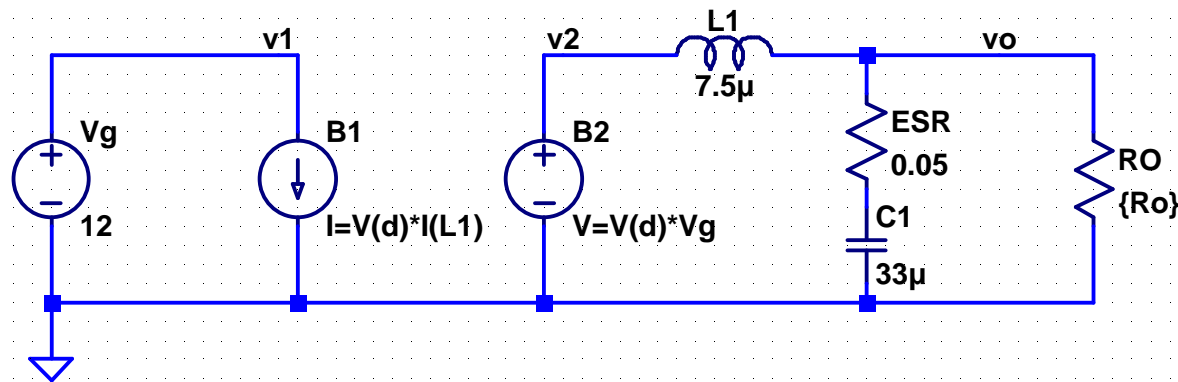
# LTspice Model: Transient Response

Input Parameters ( $V_g$ ,  $V_o\_nom$ ,  $R_o$ ) Calculated Parameters ( $I_o\_nom$ ,  $D_{nom}$ )

```
.param Vg = 12
.param Vo_nom = 3
.param Ro = 1
```

```
.param Dnom = (Vo_nom/Vg)
.param Io_nom = Vo_nom/Ro
```

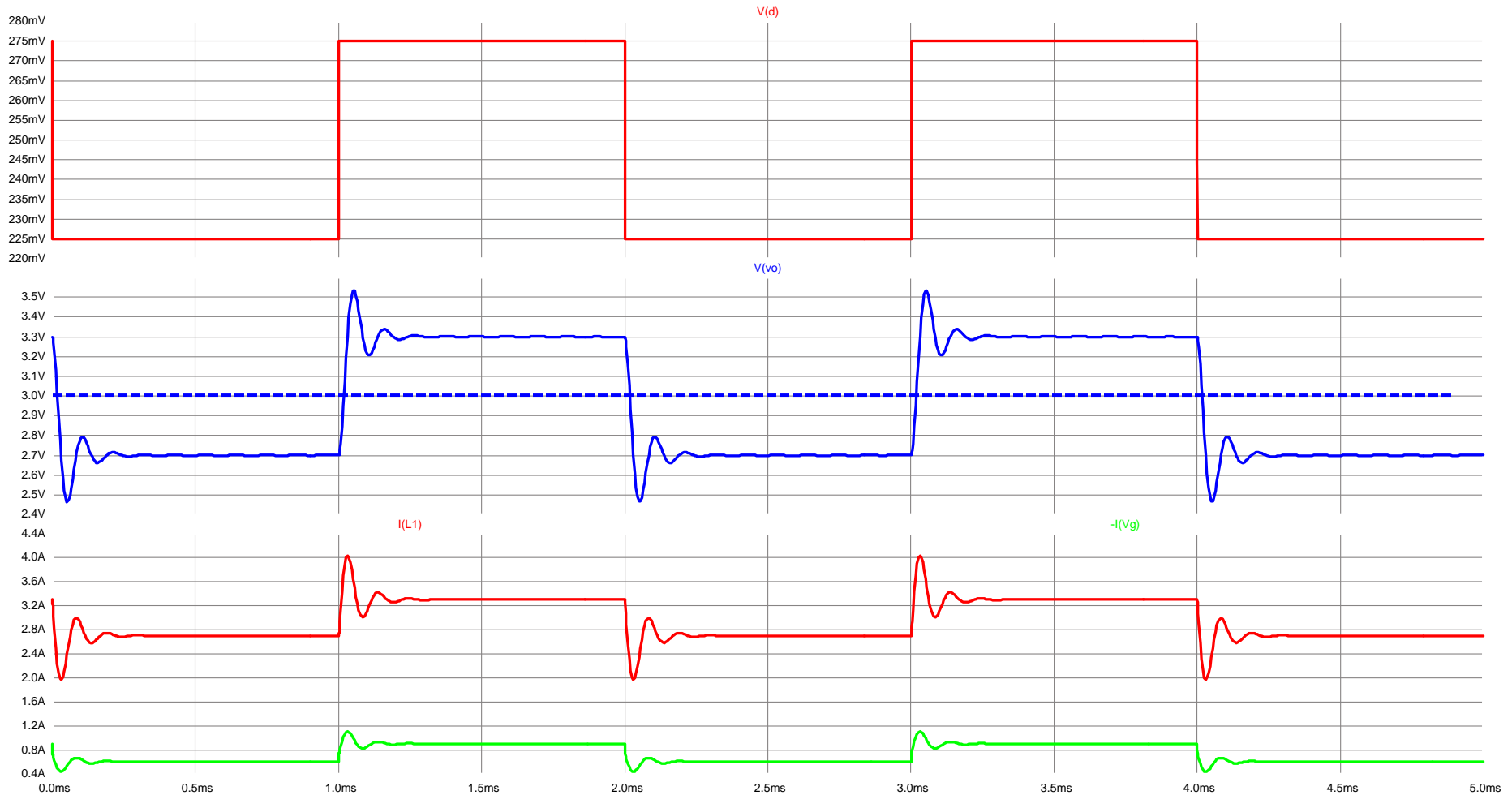
```
.tran 5m
```



$V_{dhat}$  sets the variation around the dc operating point

$V_{D\_nom}$  sets the dc duty cycle operating point

# LTspice Transient Simulation



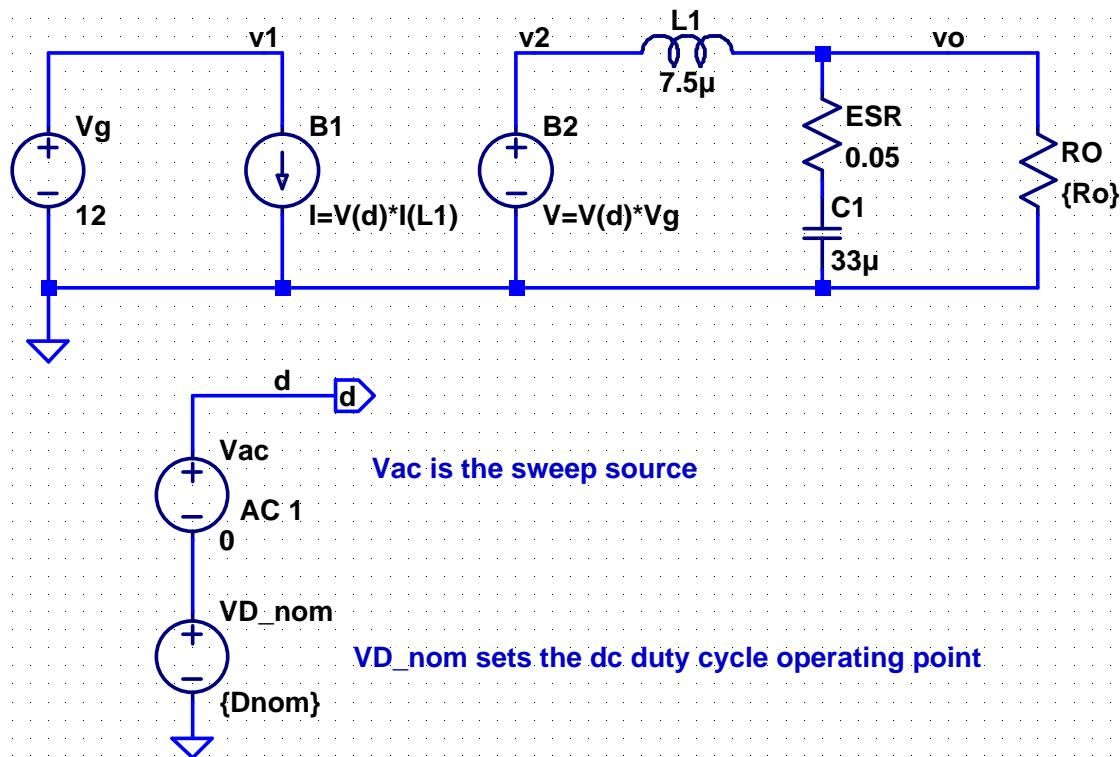
# LTspice Model: Plotting $G_{vd}$

Input Parameters ( $V_g$ ,  $V_o\_nom$ ,  $R_o$ ) Calculated Parameters ( $I_o\_nom$ ,  $D_{nom}$ )

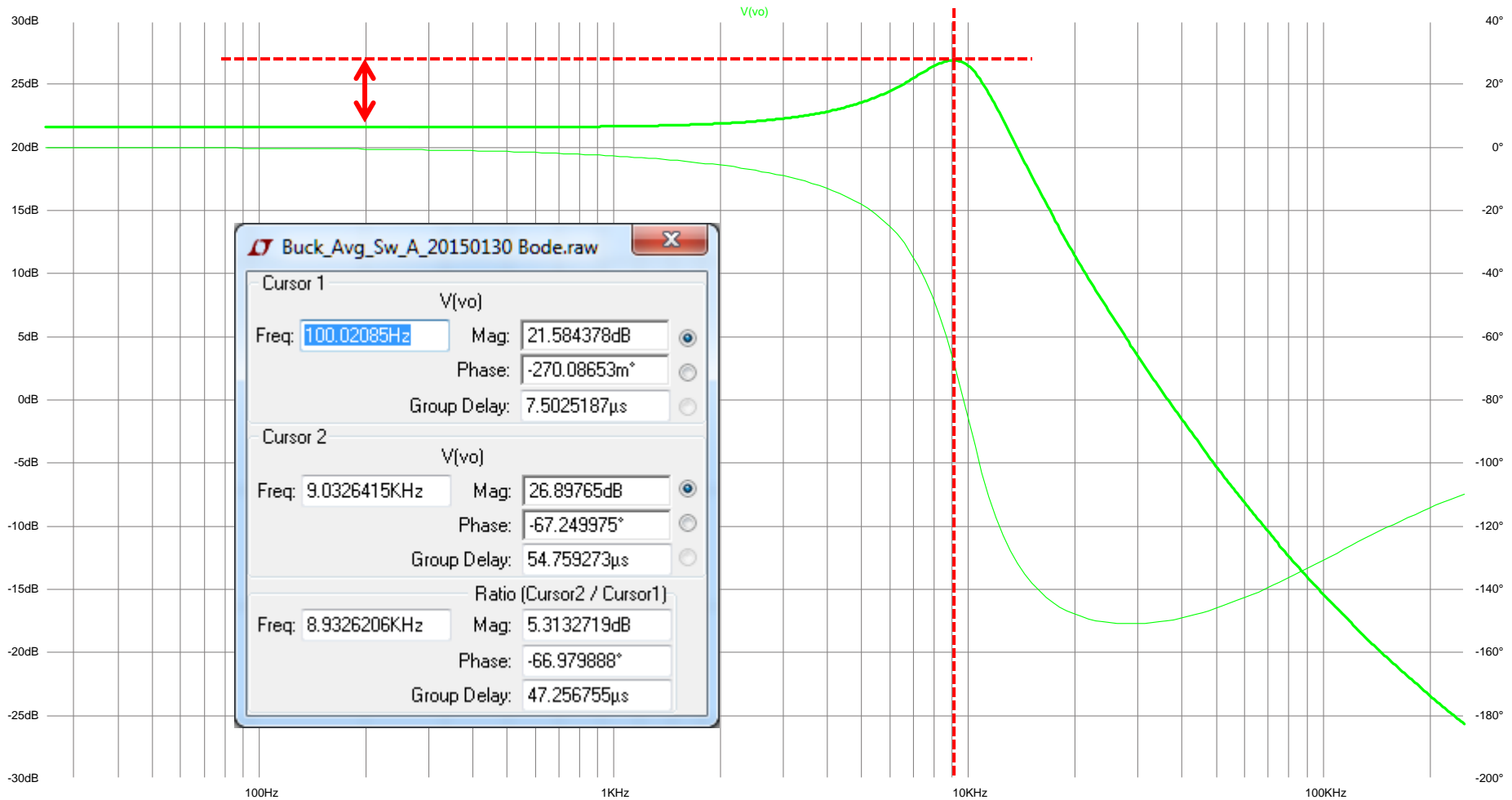
```
.param Vg = 12  
.param Vo_nom = 3  
.param Ro = 1
```

```
.param Dnom = (Vo_nom/Vg)  
.param Io_nom = Vo_nom/Ro
```

```
.ac dec 50 25 250k
```

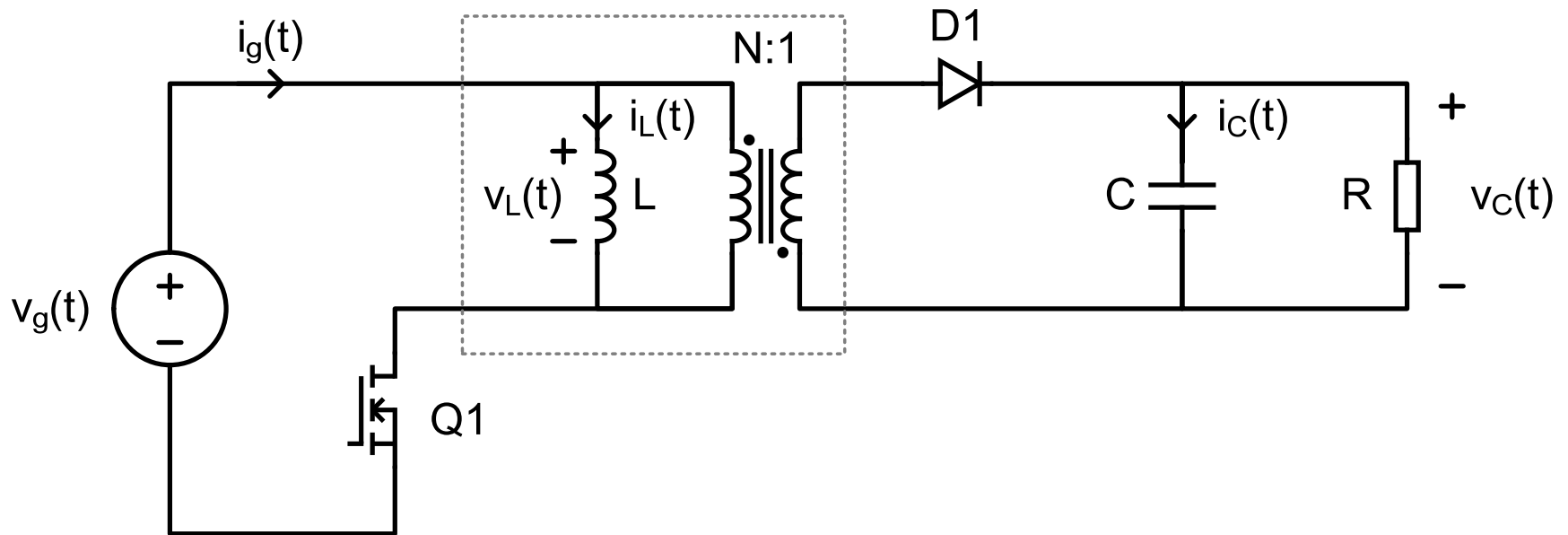


# LTspice Model

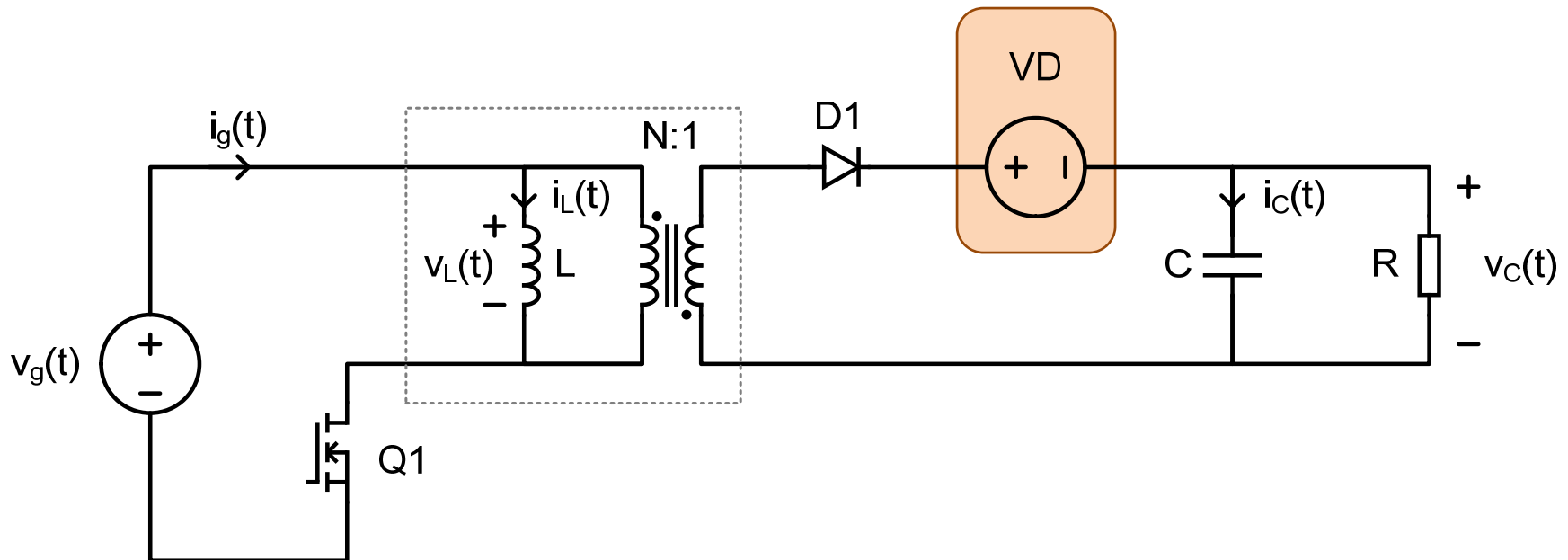




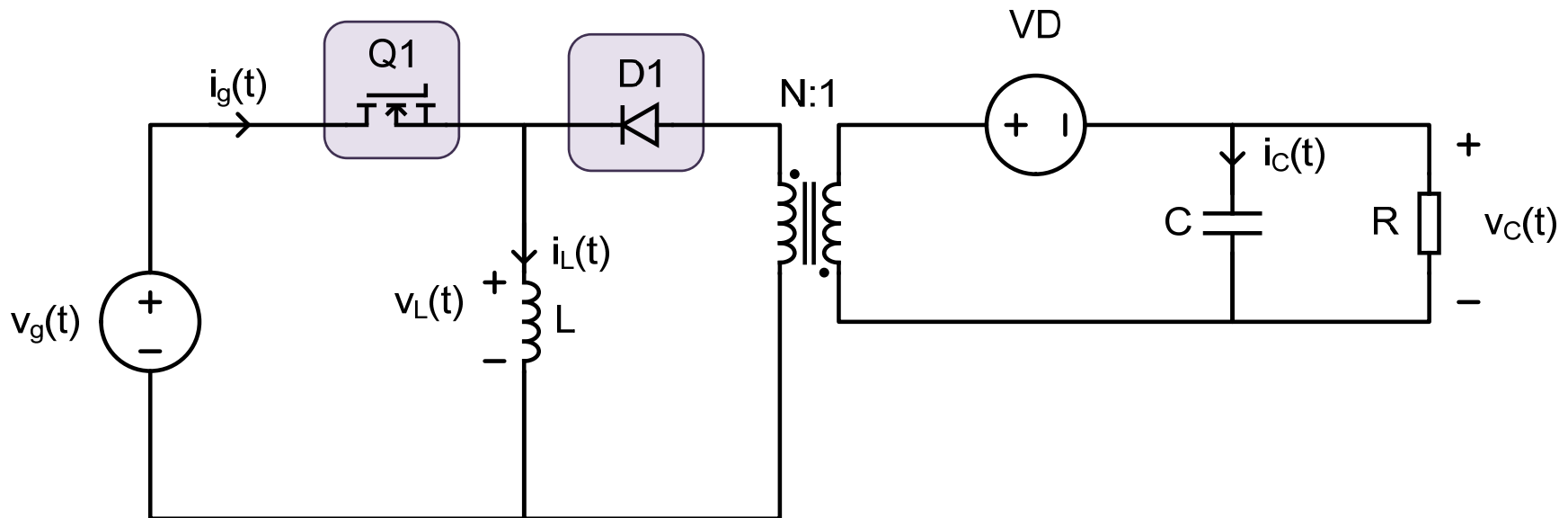
# Flyback Simulation With Average Switch Model



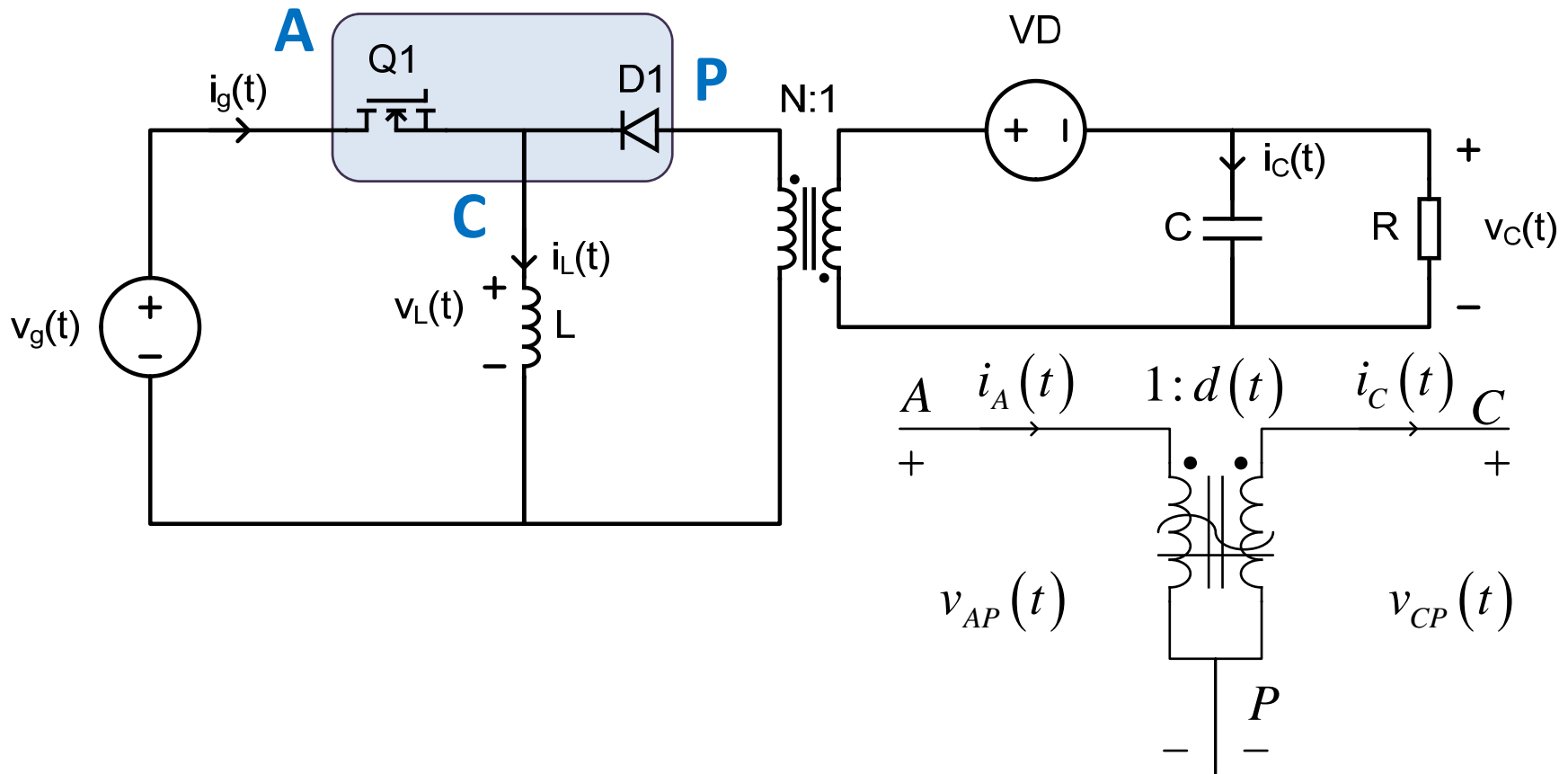
# Flyback Simulation With Average Switch Model



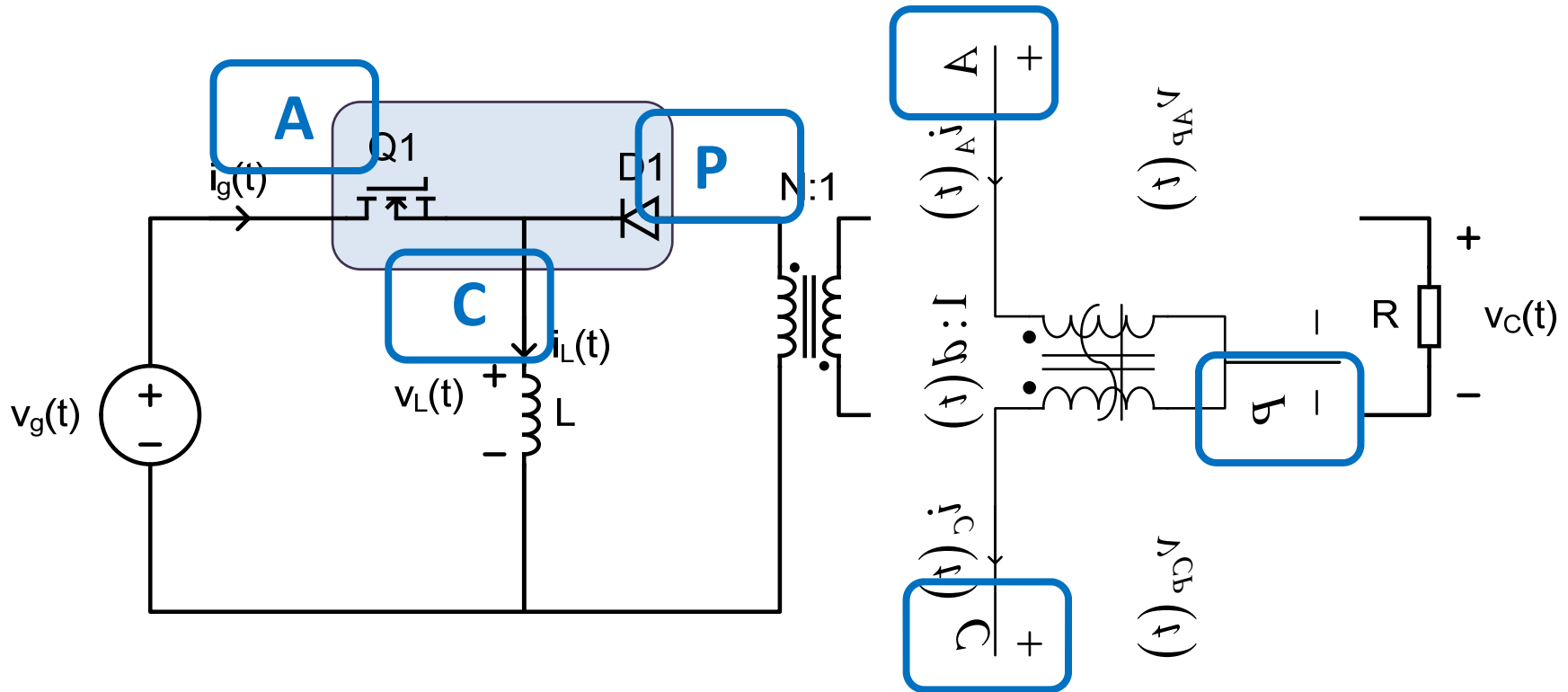
# Flyback Simulation With Average Switch Model



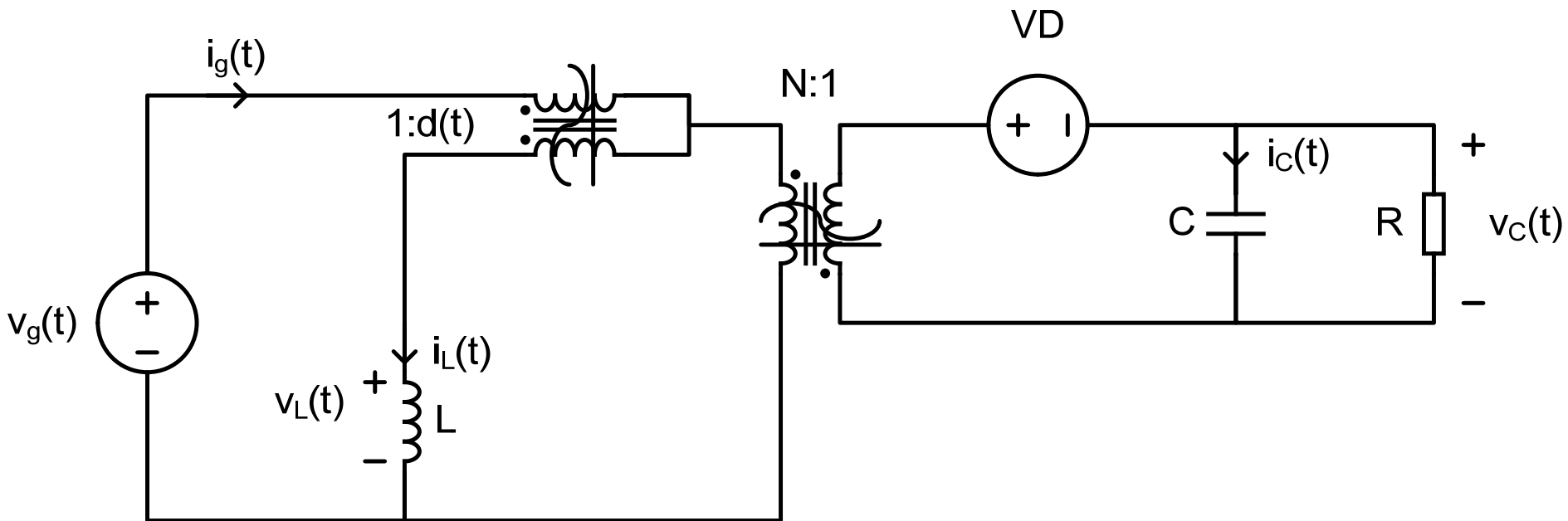
# Flyback Simulation With Average Switch Model



# Flyback Simulation With Average Switch Model



# Flyback Simulation With Average Switch Model



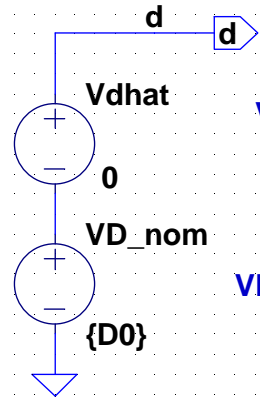
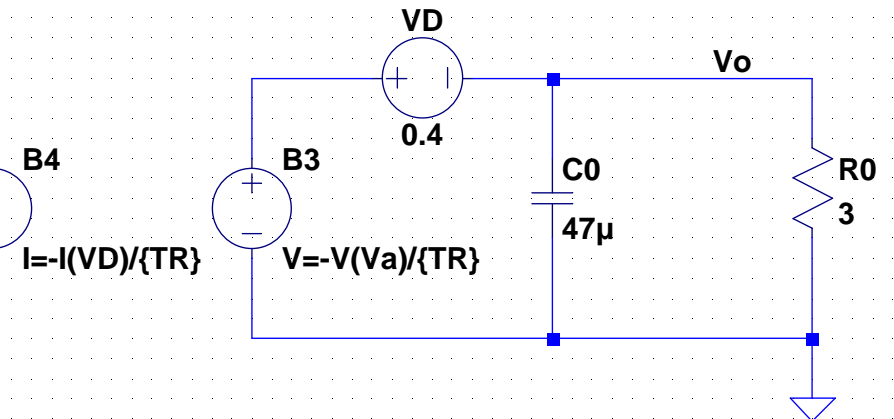
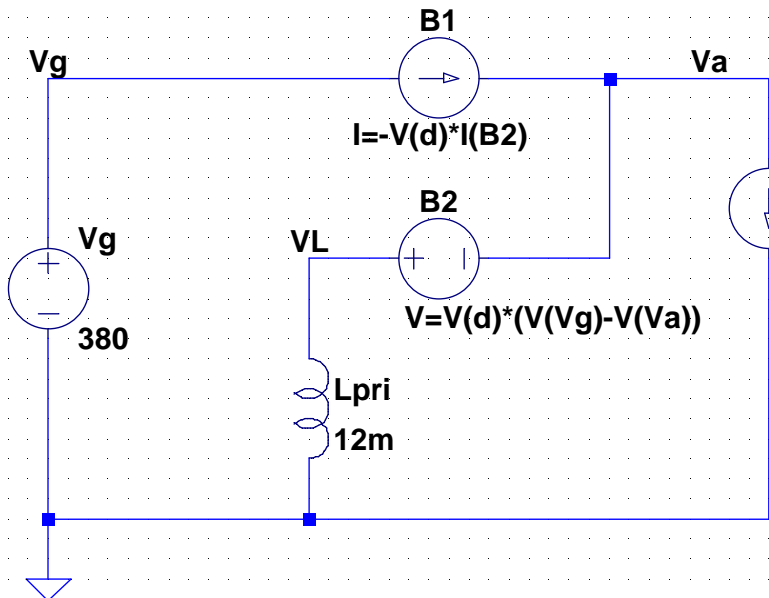
# Flyback Simulation With Average Switch Model



```
.IC V(Vo) = 12
.IC I(Lpri) = 0.494
```

```
.param D0 0.2646
.param TR 11
```

```
.op
```



Vdhat sets the variation around the dc operating

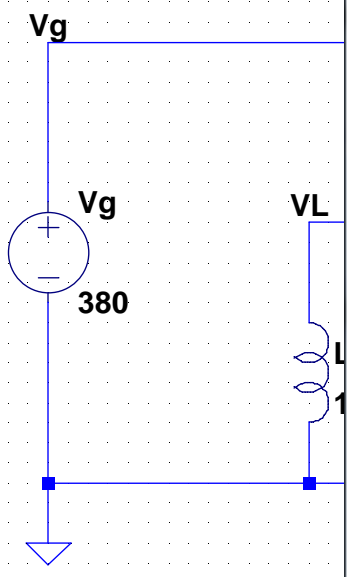
VD\_nom sets the dc duty cycle operating point

# Flyback Simulation With Average Switch Model



.IC V(Vo) = 12  
.IC I(Lpri) = 0.494

.param D0 0.2646  
.param TR 11 .op



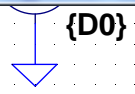
\* D:\Clients\APEC 2015\Seminar - Averaging\SPICE Flyback Average Model\Flyback Average Model 2015...

```
--- Operating Point ---
```

V(vg):	380	voltage
V(va):	-136.4	voltage
V(vl):	0.239502	voltage
V(n001):	12.4	voltage
V(vo):	12	voltage
V(d):	0.2646	voltage
V(n002):	0.2646	voltage
I(B4):	-0.363288	device_current
I(B3):	-3.99616	device_current
I(B2):	-0.494	device_current
I(B1):	0.130712	device_current
I(C0):	5.64e-016	device_current
I(Lpri):	0.494	device_current
I(R0):	4	device_current
I(Vd):	3.99616	device_current
I(Vd_nom):	0	device_current
I(Vdhat):	0	device_current
I(Vg):	-0.130712	device_current

c operating

ng point





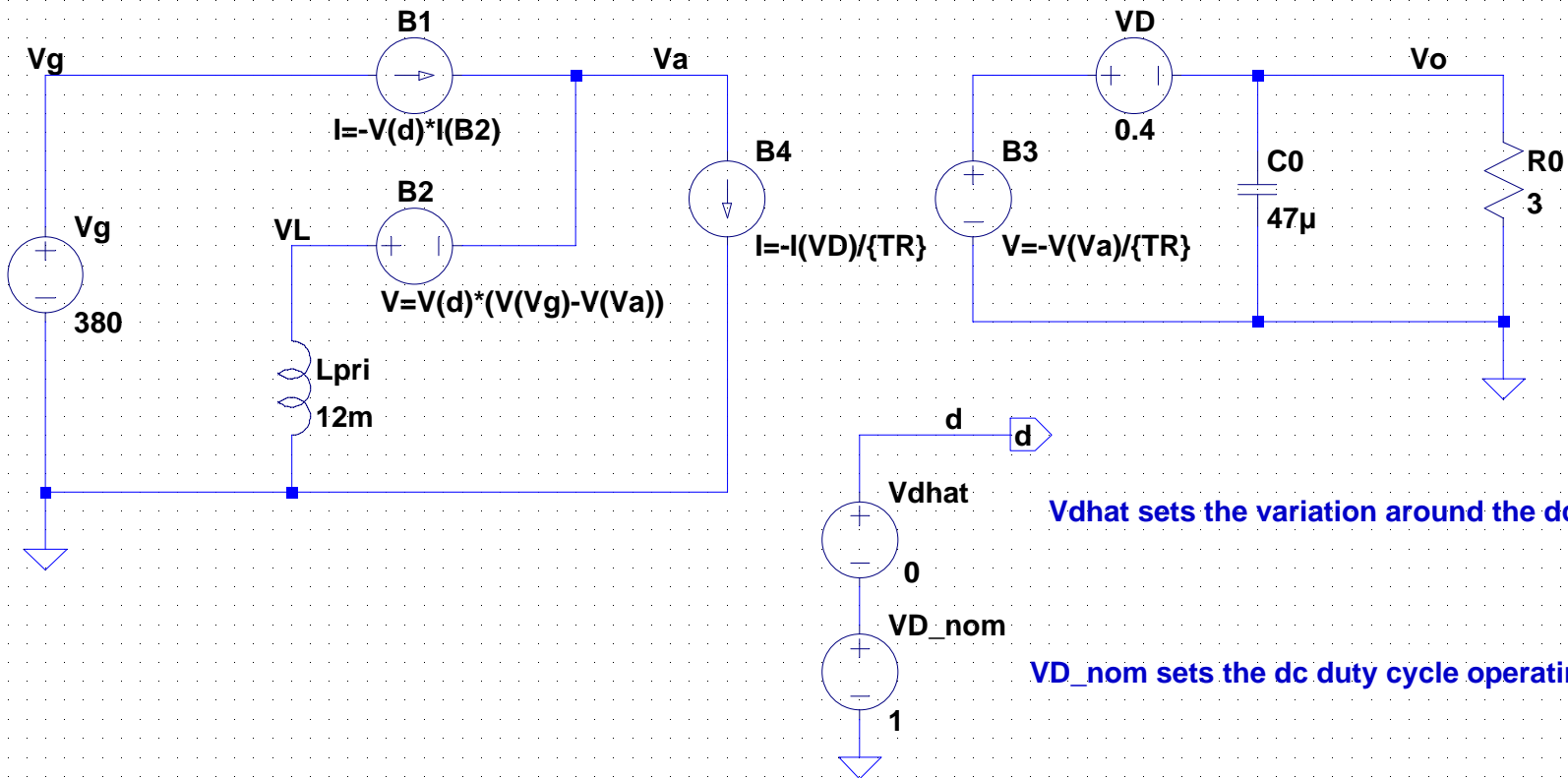
# Flyback Simulation With Average Switch Model



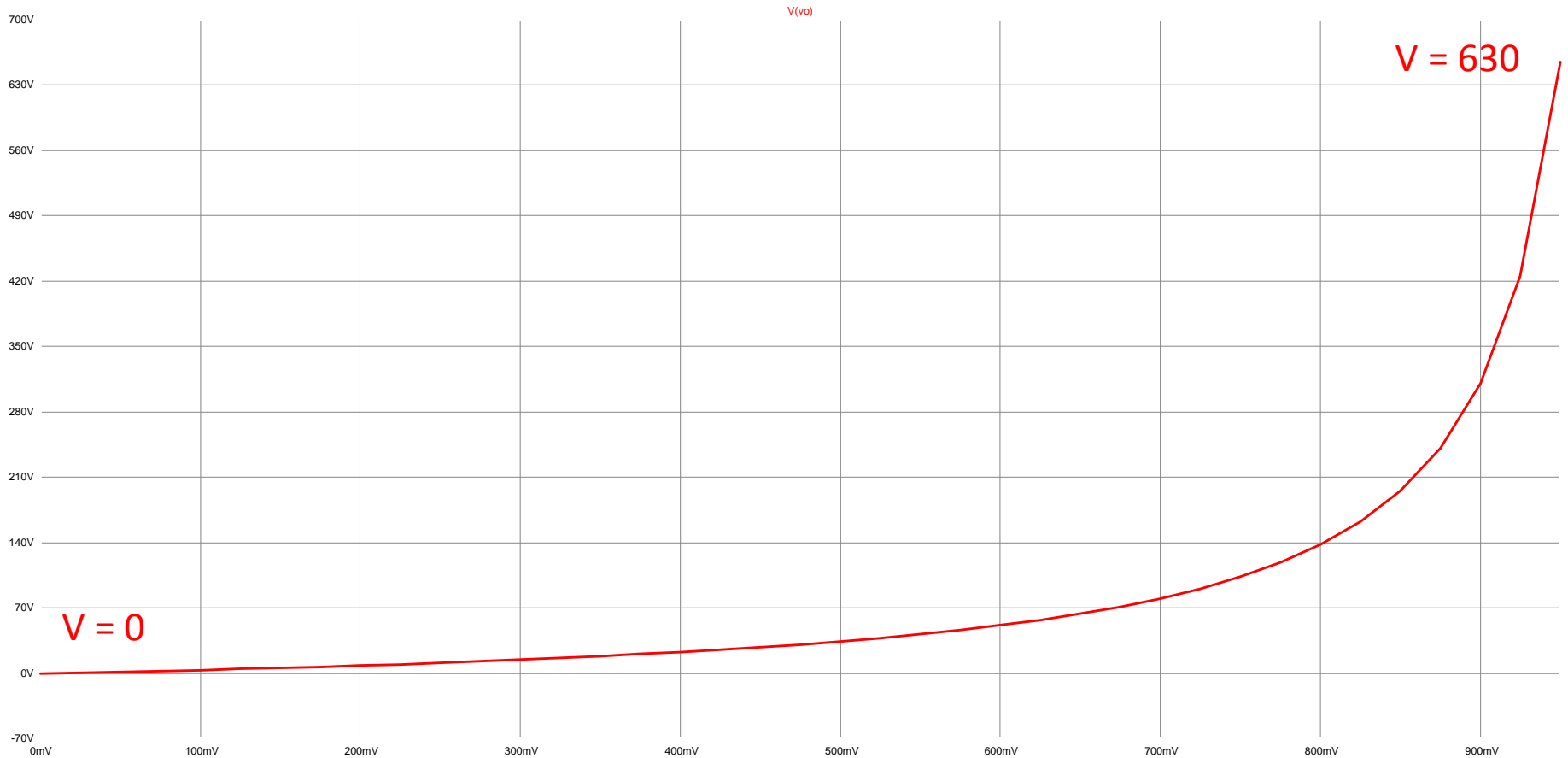
\*.IC V(Vo) = 12  
\*.IC I(Lpri) = 0.494

\*.param D0 0  
.param TR 11

.dc VD\_nom 0.0 0.95 0.025



# Flyback Simulation With Average Switch Model



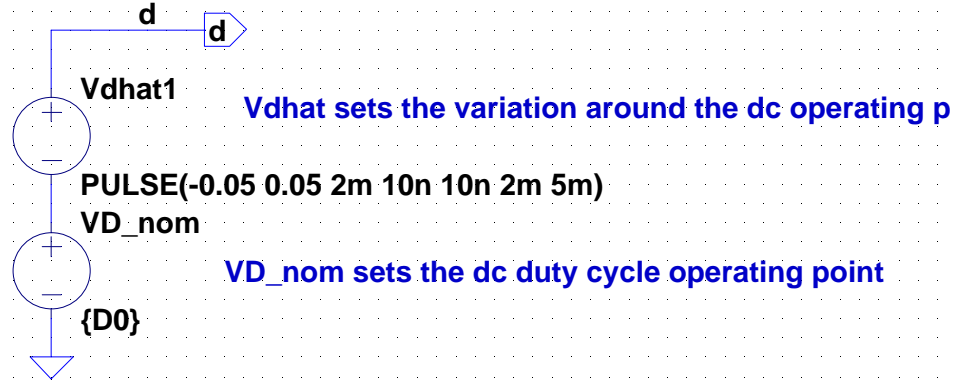
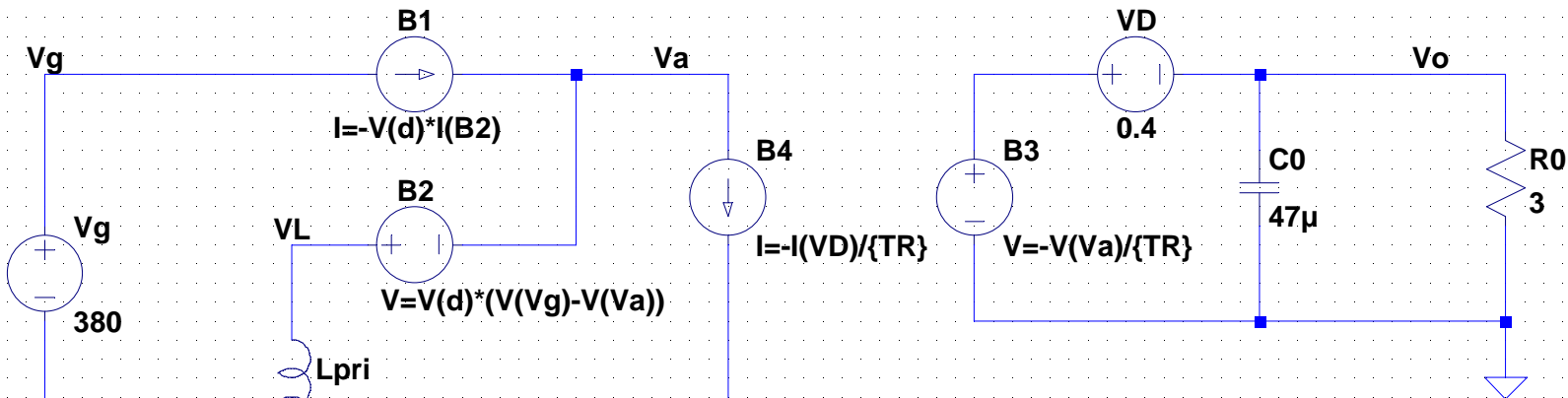
D = 0

D = 0.95

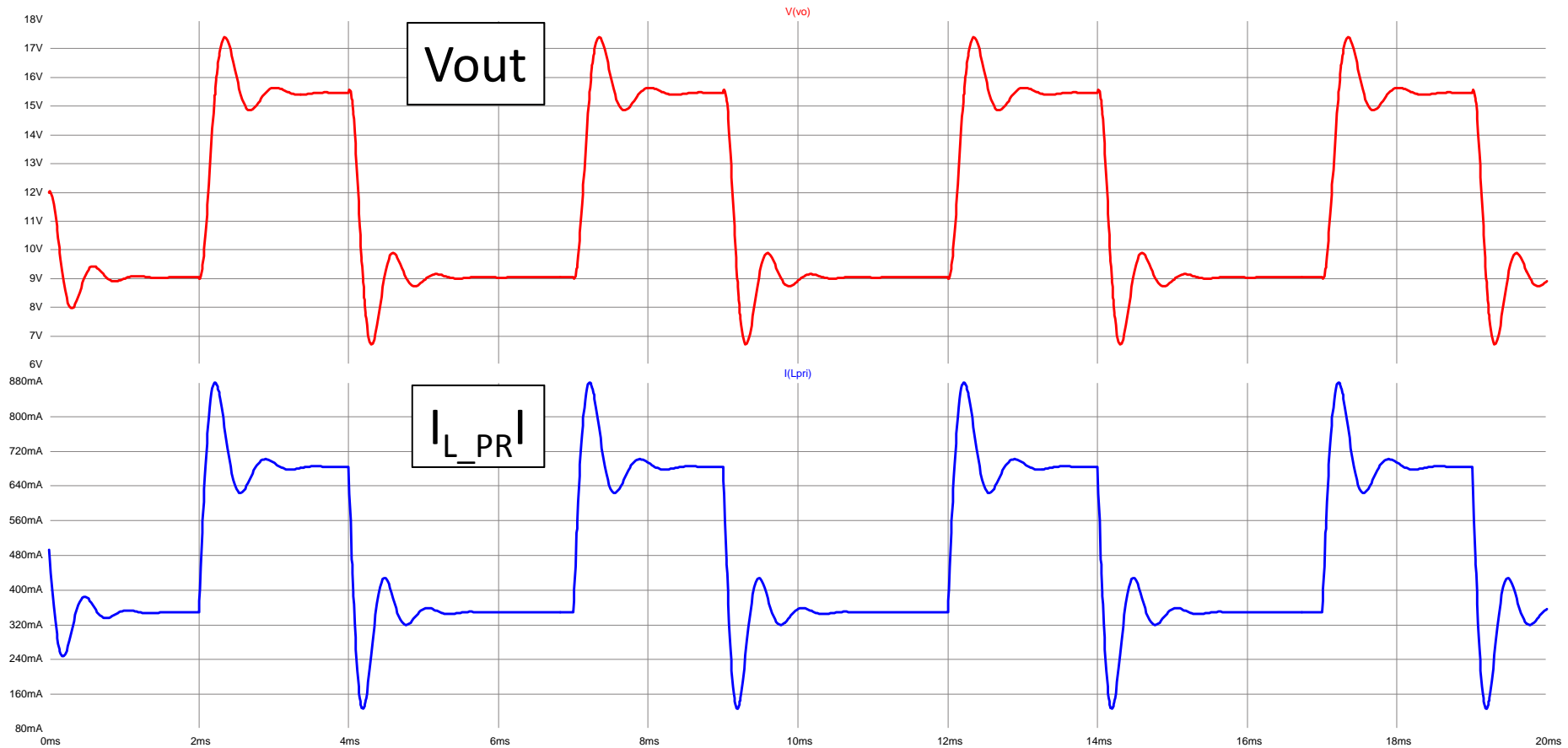
# Flyback Simulation With Average Switch Model



```
.IC V(Vo) = 12
.IC I(Lpri) = 0.494
.param D0 0.2646
.param TR 11
.tran 20m
```



# Flyback Simulation With Average Switch Model



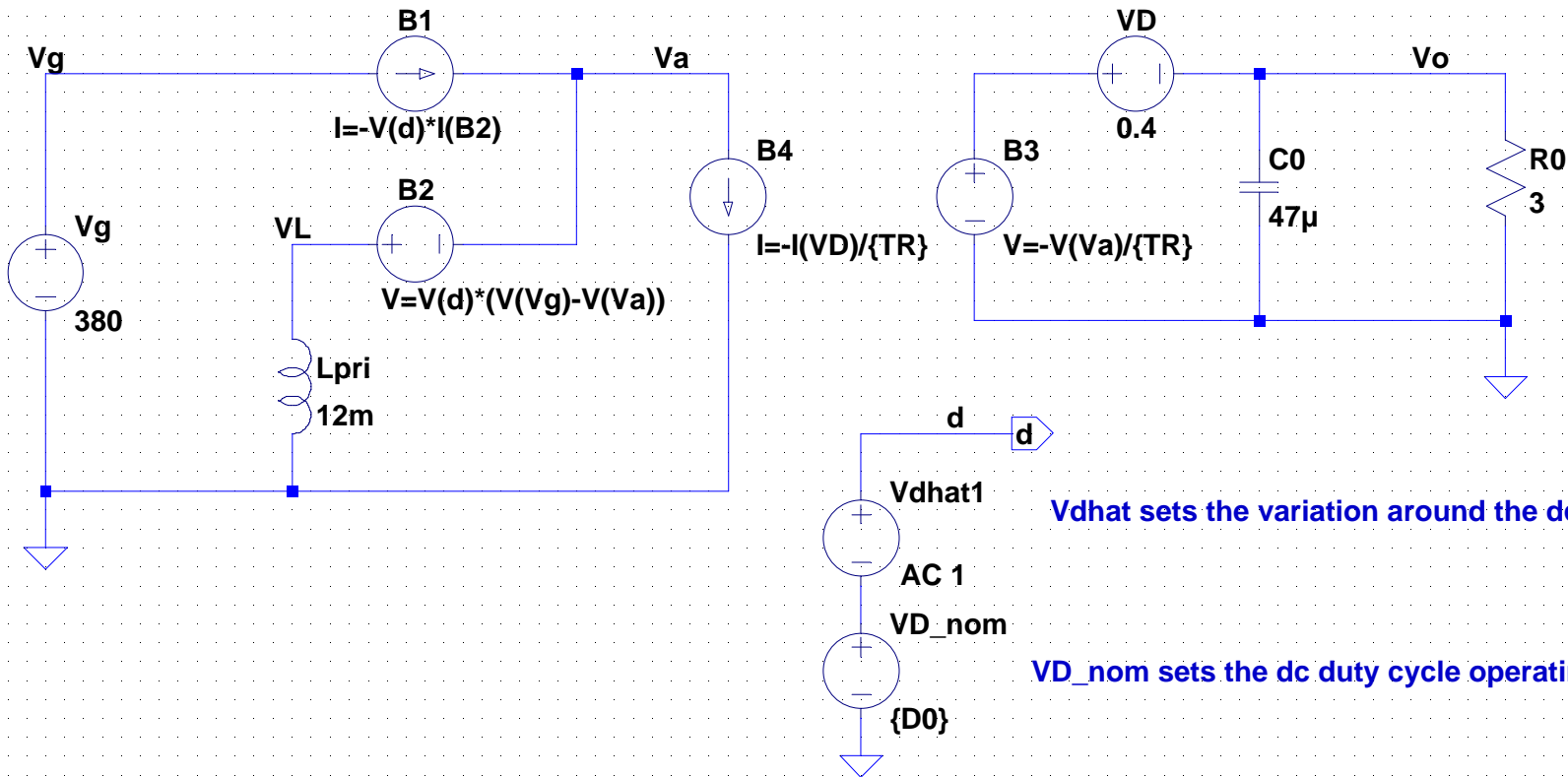
# Flyback Simulation With Average Switch Model



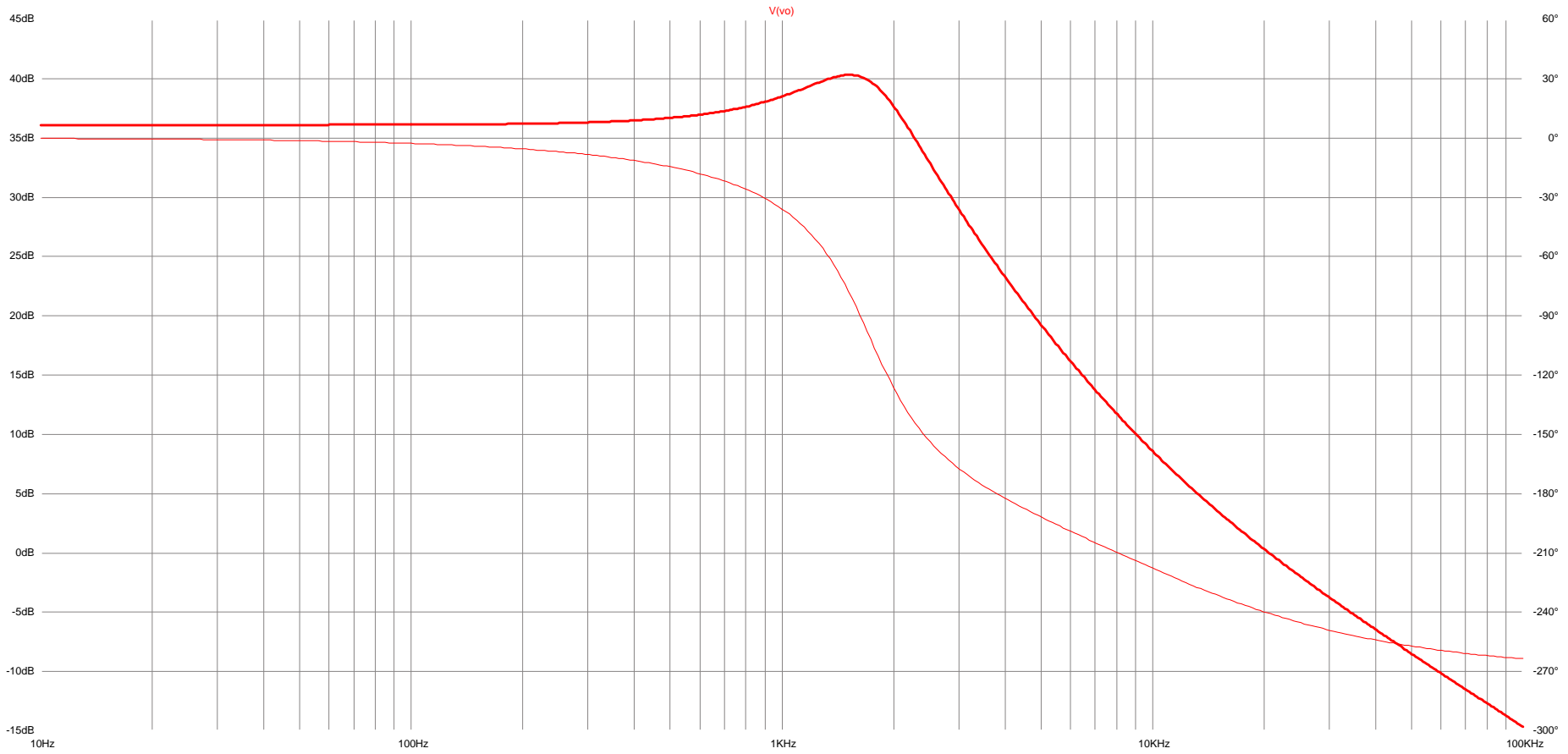
.IC V(Vo) = 12  
.IC I(Lpri) = 0.494

.param D0 0.2646  
.param TR 11

.ac dec 100 10 100k



# Flyback Simulation With Average Switch Model



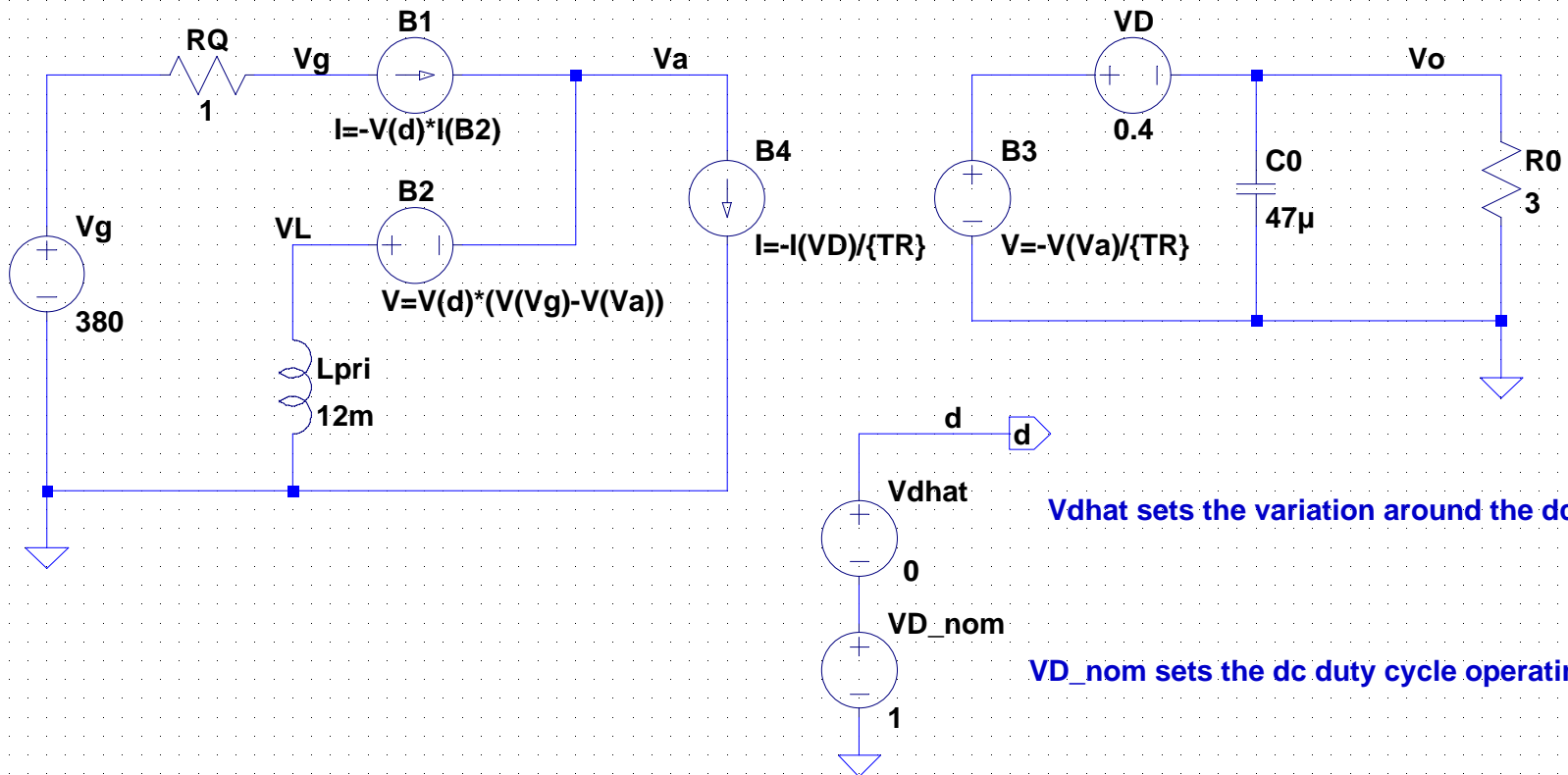
# Flyback Simulation With Average Switch Model



\*.IC V(Vo) = 12  
\*.IC I(Lpri) = 0.494

\*.param D0 0  
.param TR 11

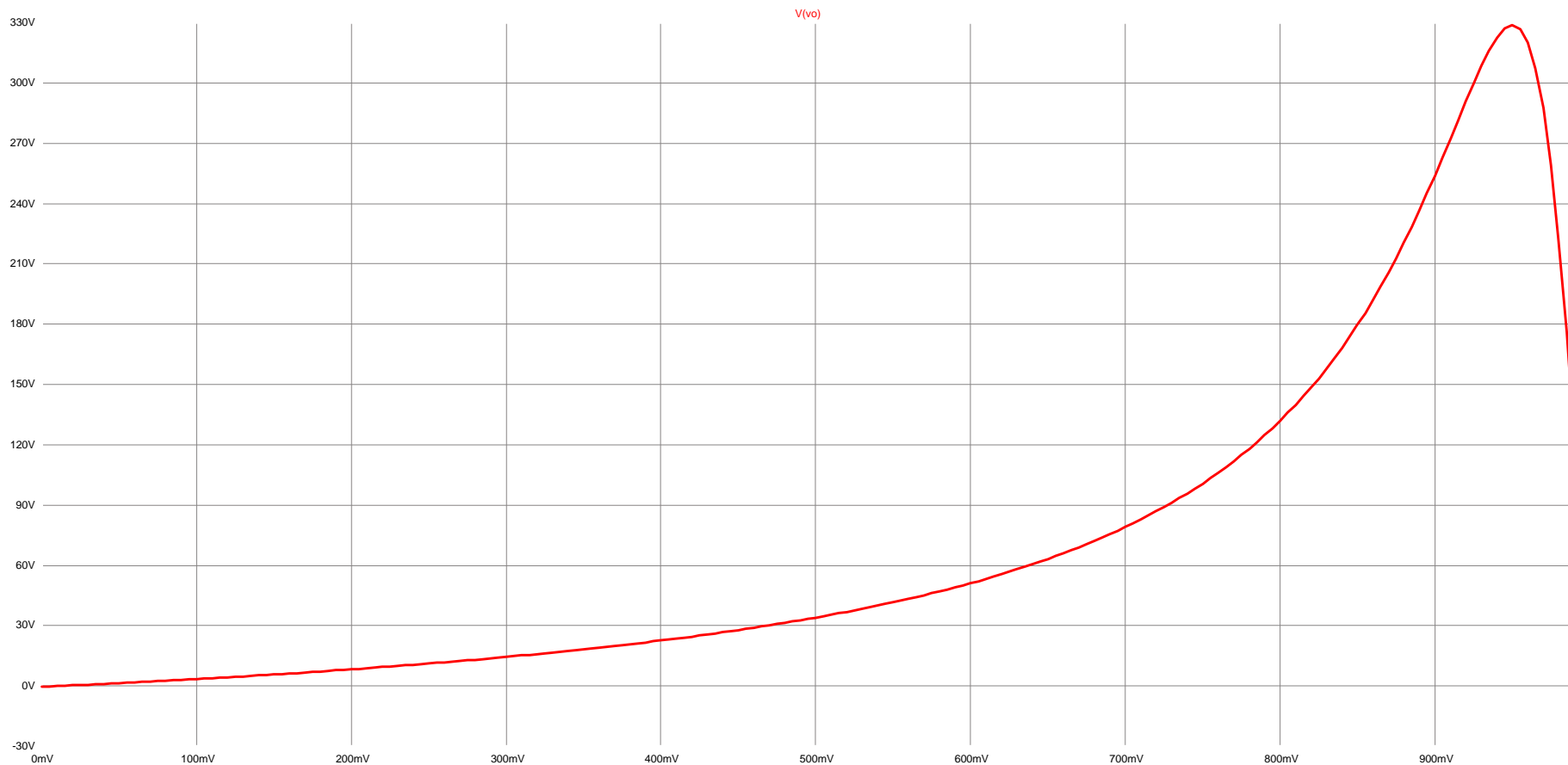
.dc VD\_nom 0.0 0.99 0.005



$V_{dhat}$  sets the variation around the dc operating po

$VD\_nom$  sets the dc duty cycle operating point

# Flyback Simulation With Average Switch Model



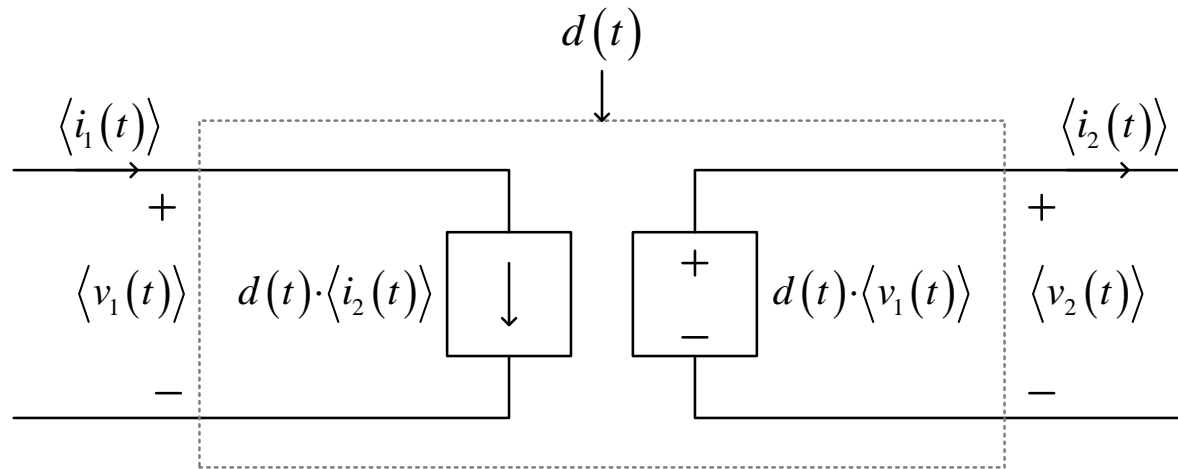
D = 0

D = 0.99





# Averaged Switch Small Signal Model



$$\langle v_2(t) \rangle = d(t) \cdot \langle v_1(t) \rangle$$

$$\langle i_1(t) \rangle = d(t) \cdot \langle i_2(t) \rangle$$

$$\langle v_1(t) \rangle = V_1 + \hat{v}_1(t)$$

$$\langle v_2(t) \rangle = V_2 + \hat{v}_2(t)$$

$$\langle i_1(t) \rangle = I_1 + \hat{i}_1(t)$$

$$\langle i_2(t) \rangle = I_2 + \hat{i}_2(t)$$

$$d(t) = D + \hat{d}(t)$$

# Averaged Switch Small Signal Model

$$\langle v_2(t) \rangle = d(t) \cdot \langle v_1(t) \rangle$$

$$\begin{aligned} V_2 + \hat{v}_2(t) &= (D + \hat{d}(t)) \cdot (V_1 + \hat{v}_1(t)) \\ &= D \cdot V_1 + D \cdot \hat{v}_1(t) + V_1 \cdot \hat{d}(t) + \hat{d}(t) \cdot \hat{v}_1(t) \end{aligned}$$

$$\hat{d}(t) \cdot \hat{v}_1(t) \approx 0$$

$$\begin{aligned} V_2 + \hat{v}_2(t) &= D \cdot V_1 + D \cdot \hat{v}_1(t) + V_1 \cdot \hat{d}(t) \\ &= D \cdot (V_1 + \hat{v}_1(t)) + V_1 \cdot \hat{d}(t) \end{aligned}$$

Discard Higher  
Order Nonlinear  
Terms

DC And Small Signal Terms!

# Averaged Switch Small Signal Model

$$\langle i_1(t) \rangle = d(t) \cdot \langle i_2(t) \rangle$$

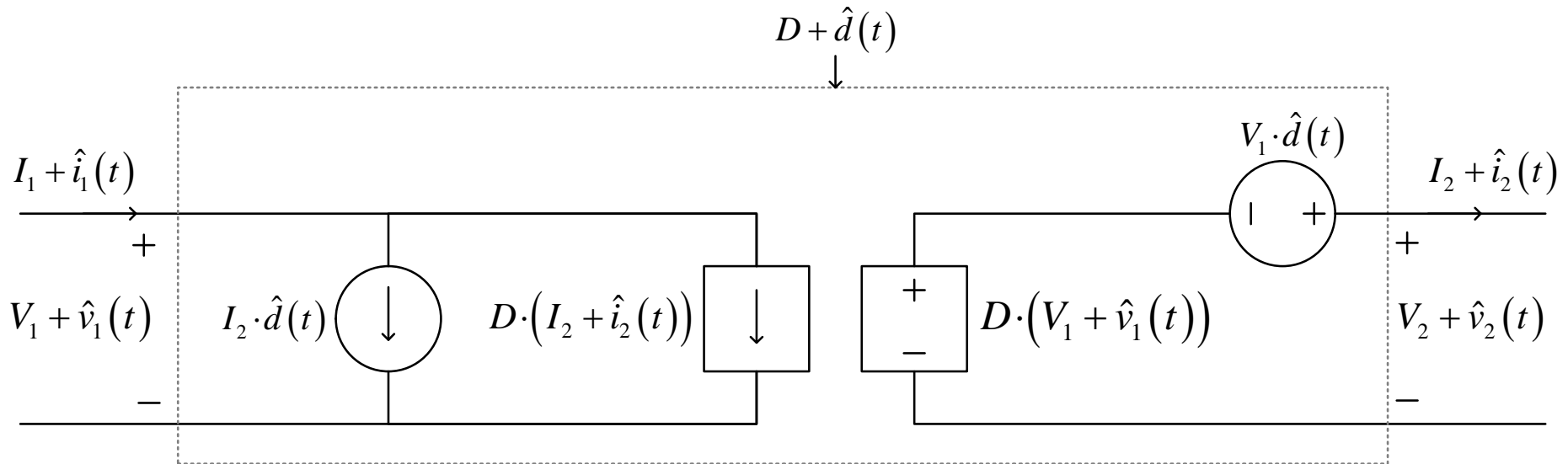
$$\begin{aligned} I_1 + \hat{i}_1(t) &= (D + \hat{d}(t)) \cdot (I_2 + \hat{i}_2(t)) \\ &= D \cdot I_2 + D \cdot \hat{i}_2(t) + I_2 \cdot \hat{d}(t) + \hat{d}(t) \cdot \hat{i}_2(t) \end{aligned}$$

$$\hat{d}(t) \cdot \hat{i}_2(t) \approx 0$$

$$\begin{aligned} I_1 + \hat{i}_1(t) &= D \cdot I_2 + D \cdot \hat{i}_2(t) + I_2 \cdot \hat{d}(t) \\ &= D \cdot (I_2 + \hat{i}_2(t)) + I_2 \cdot \hat{d}(t) \end{aligned}$$

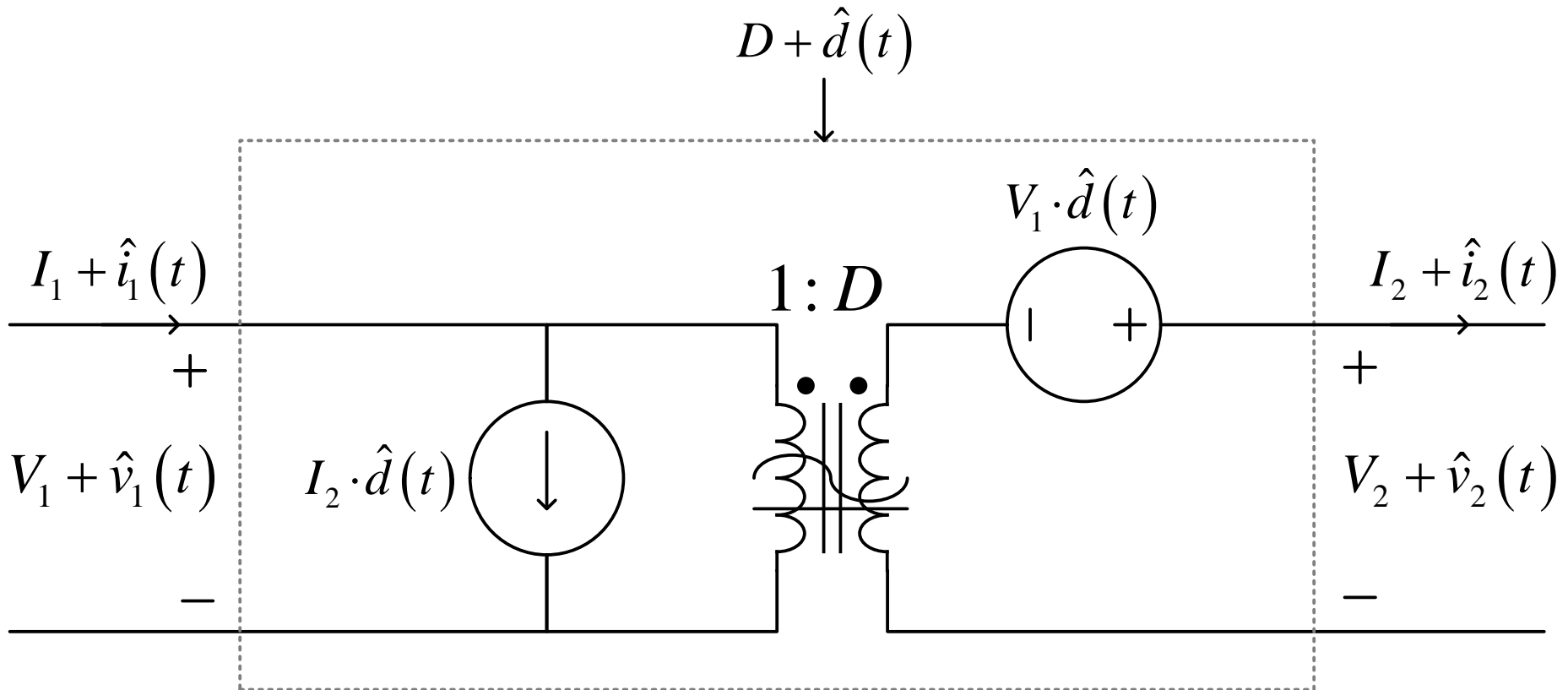
# Construct The Switch Model

$$I_1 + \hat{i}_1(t) = D \cdot (I_2 + \hat{i}_2(t)) + I_2 \cdot \hat{d}(t) \quad V_2 + \hat{v}_2(t) = D \cdot (V_1 + \hat{v}_1(t)) + V_1 \cdot \hat{d}(t)$$

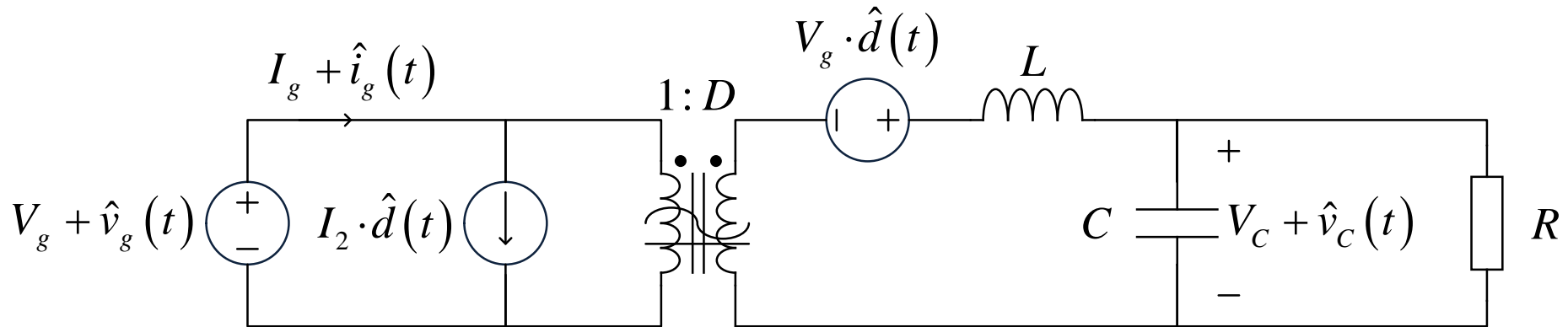


# Construct The Switch Model

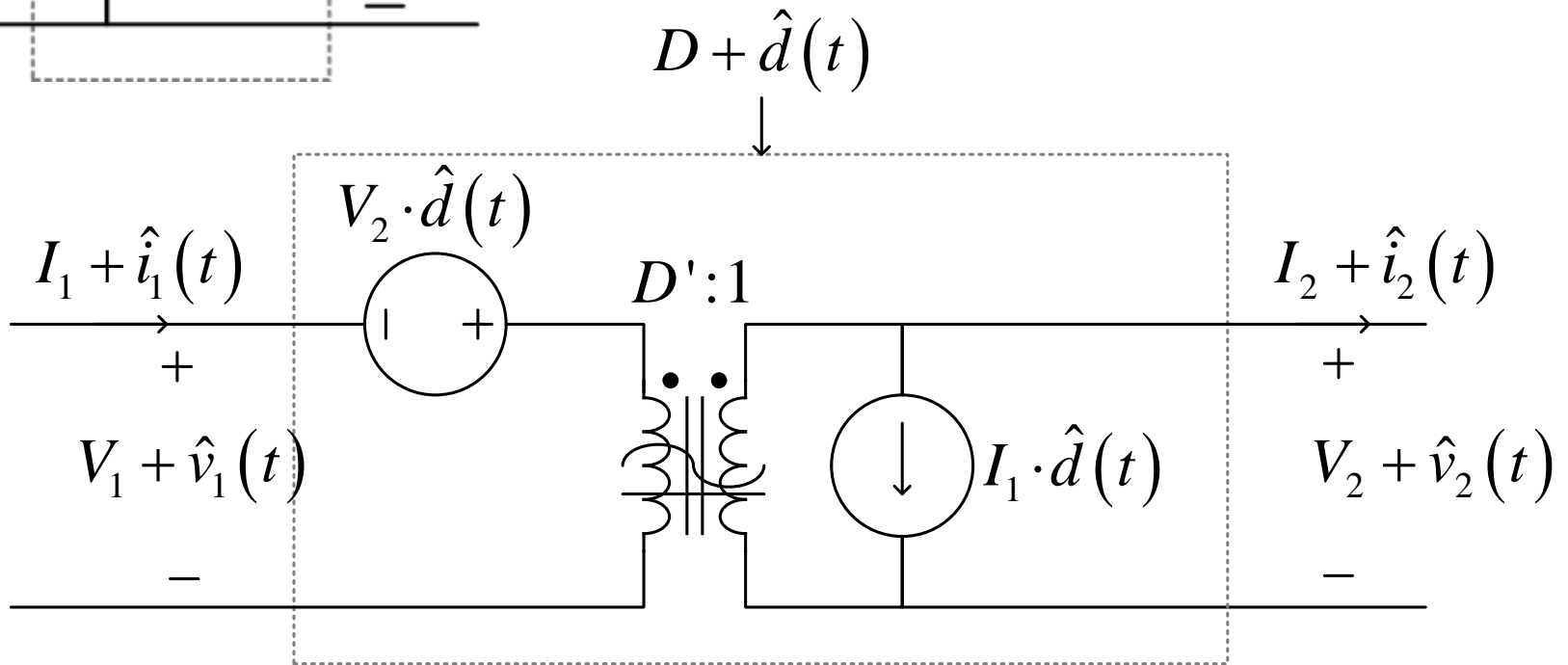
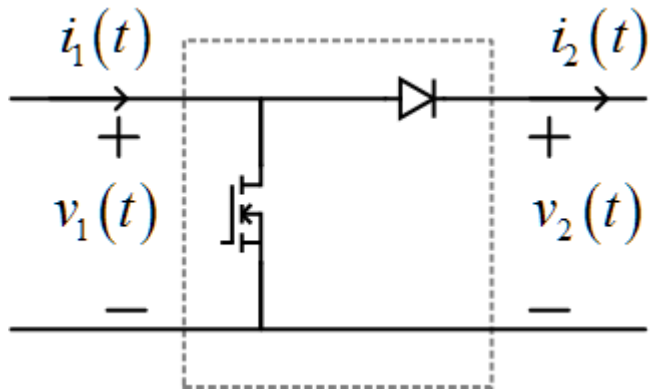
$$I_1 + \hat{i}_1(t) = D \cdot (I_2 + \hat{i}_2(t)) + I_2 \cdot \hat{d}(t) \quad V_2 + \hat{v}_2(t) = D \cdot (V_1 + \hat{v}_1(t)) + V_1 \cdot \hat{d}(t)$$



# Averaged Switch Small Signal Buck Converter Model

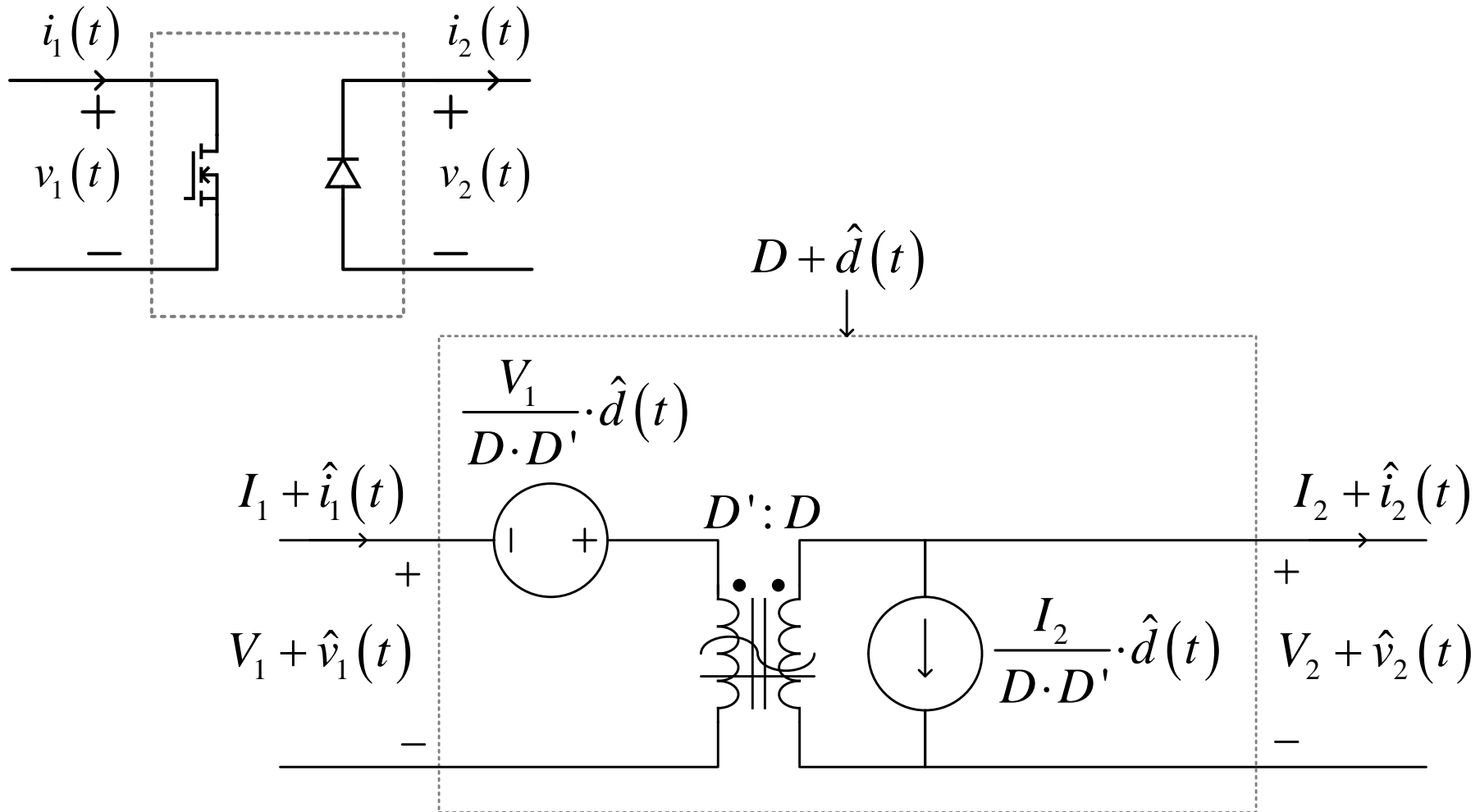


# Boost Switch Model



Re-drawn from "Fundamentals of Power Electronics", 2<sup>nd</sup> ed., Erickson and Maksimovic, Figure 7.50

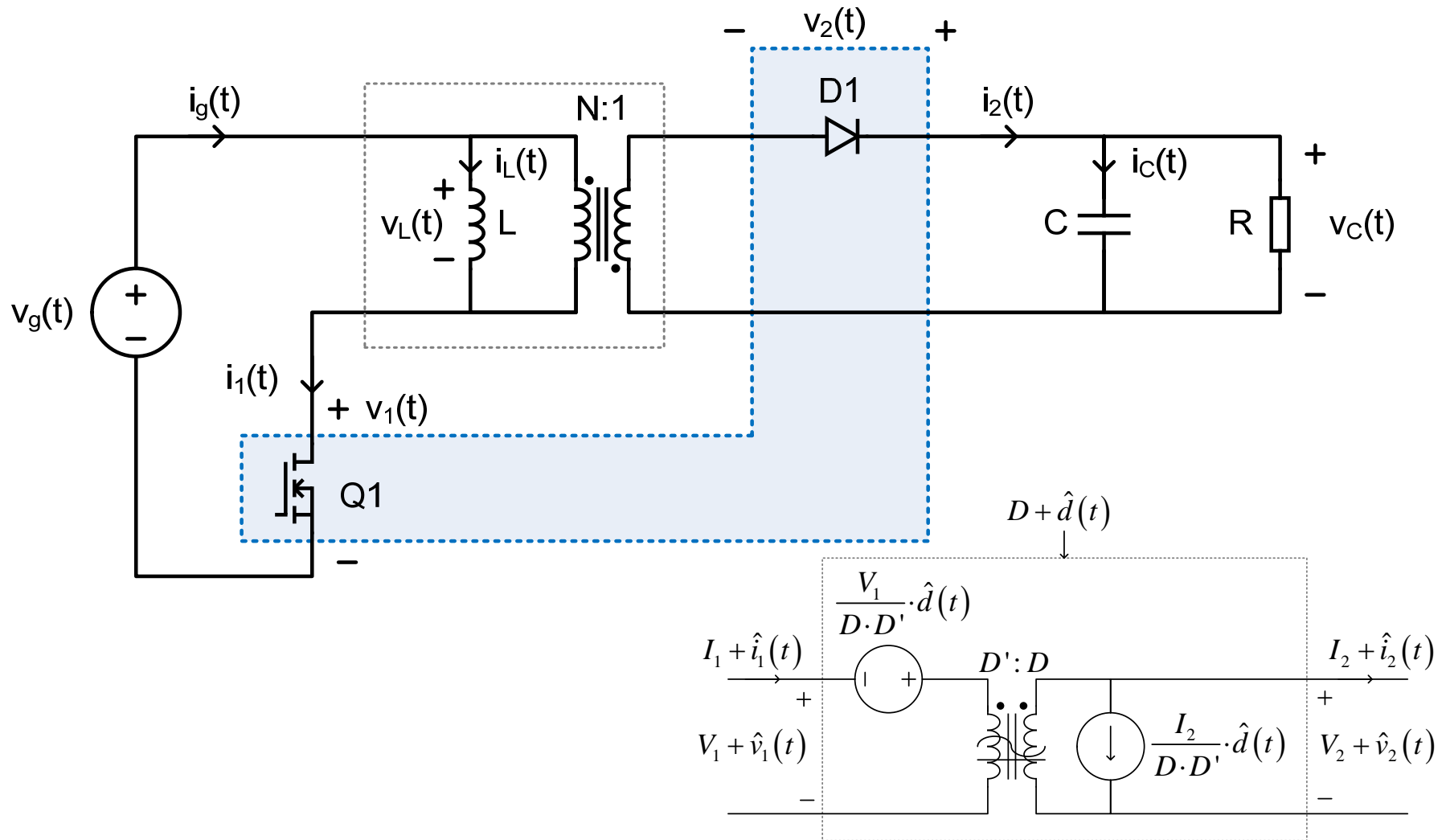
# General Two-Switch Network



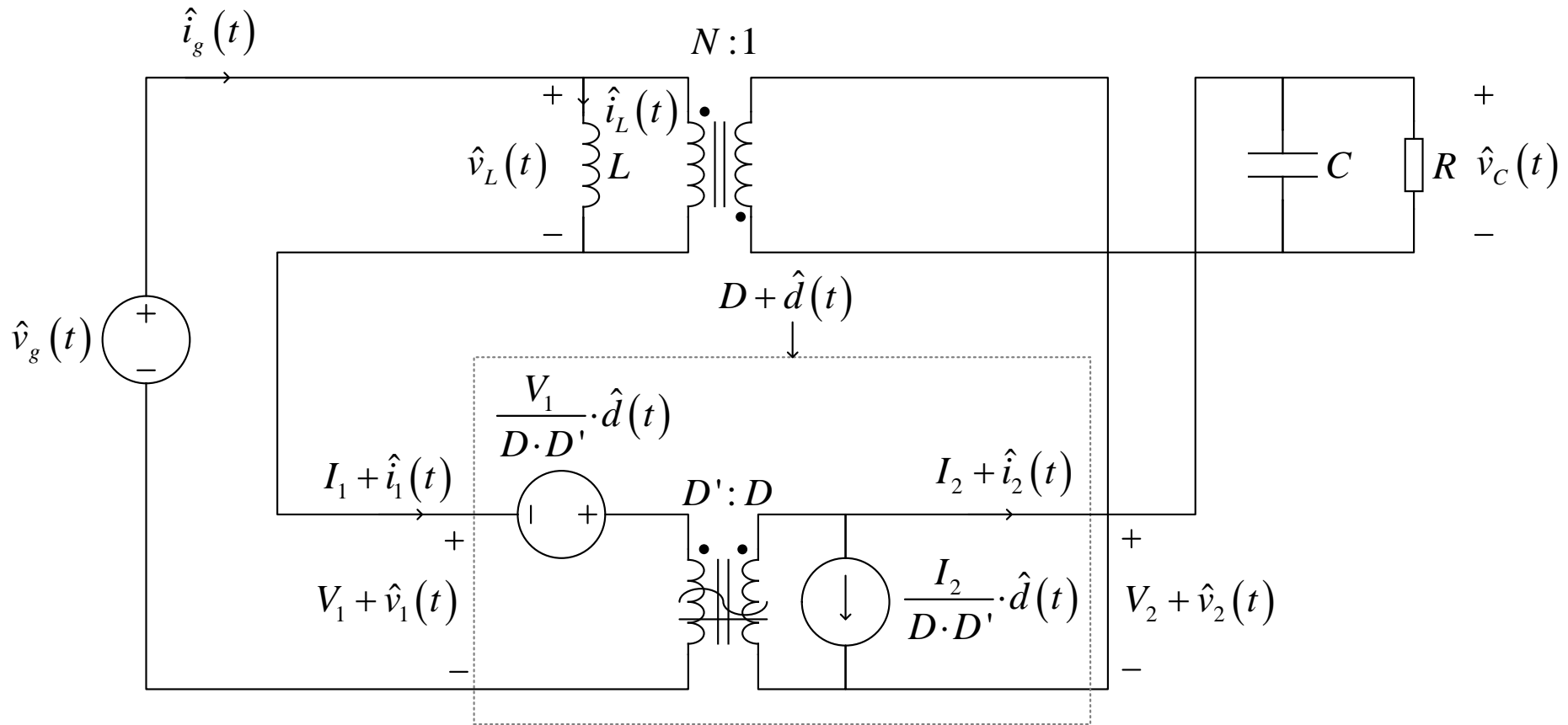
Re-drawn from "Fundamentals of Power Electronics", 2<sup>nd</sup> ed., Erickson and Maksimovic, Figure 7.50



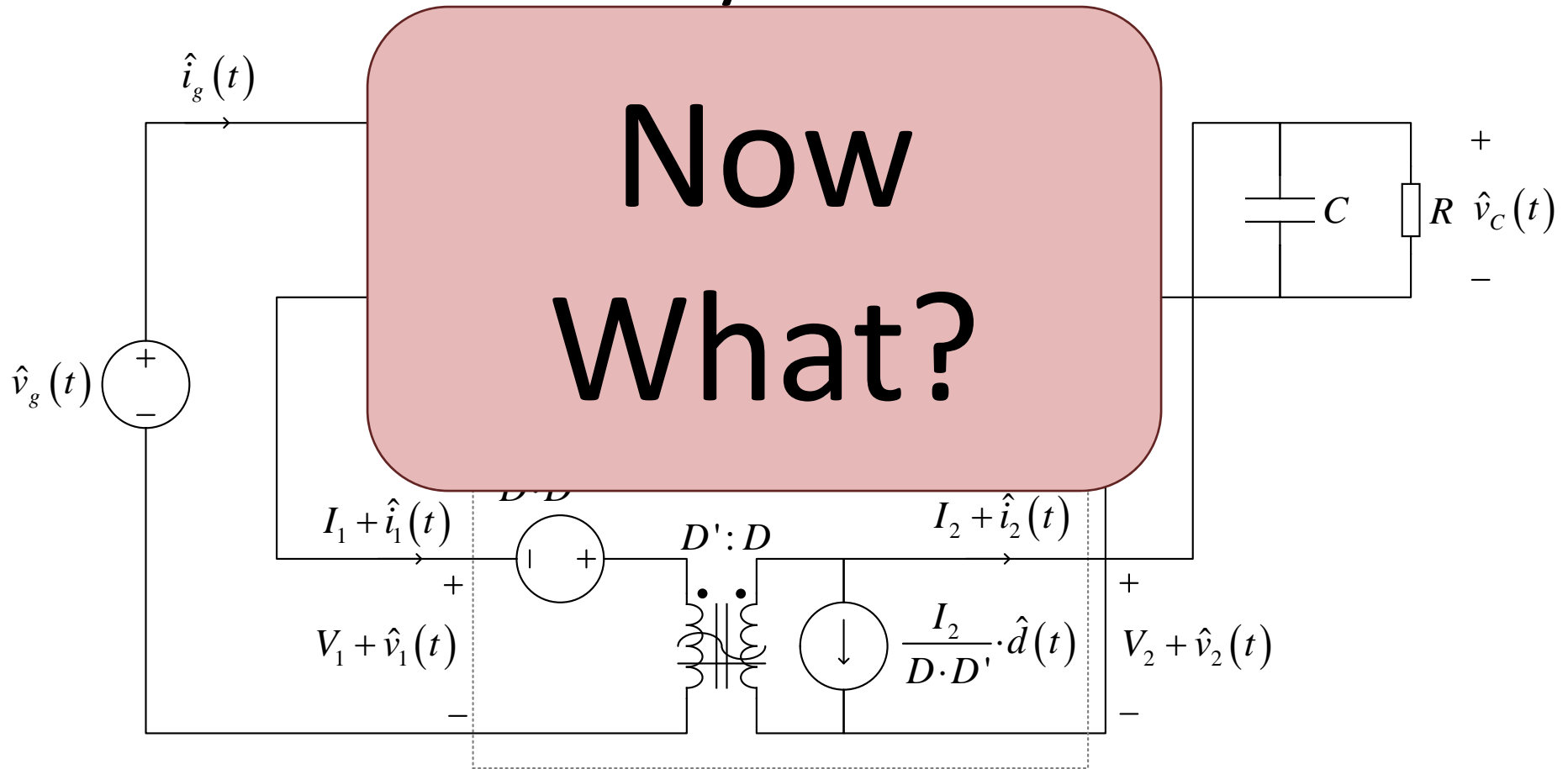
# Averaged Switch Small Signal Model: Flyback



# Averaged Switch Small Signal Model: Flyback

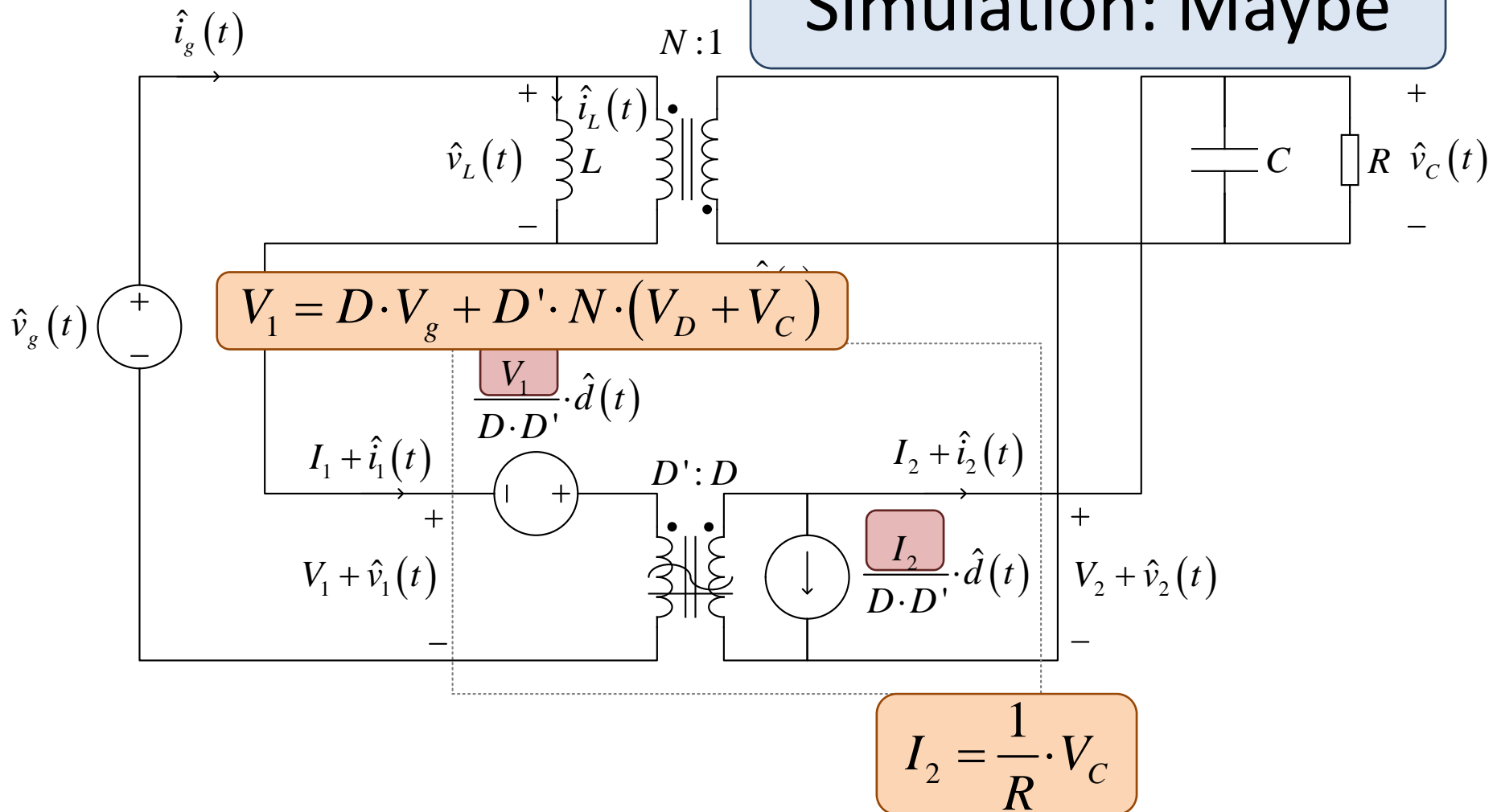


# Averaged Switch Small Signal Model: Flyback

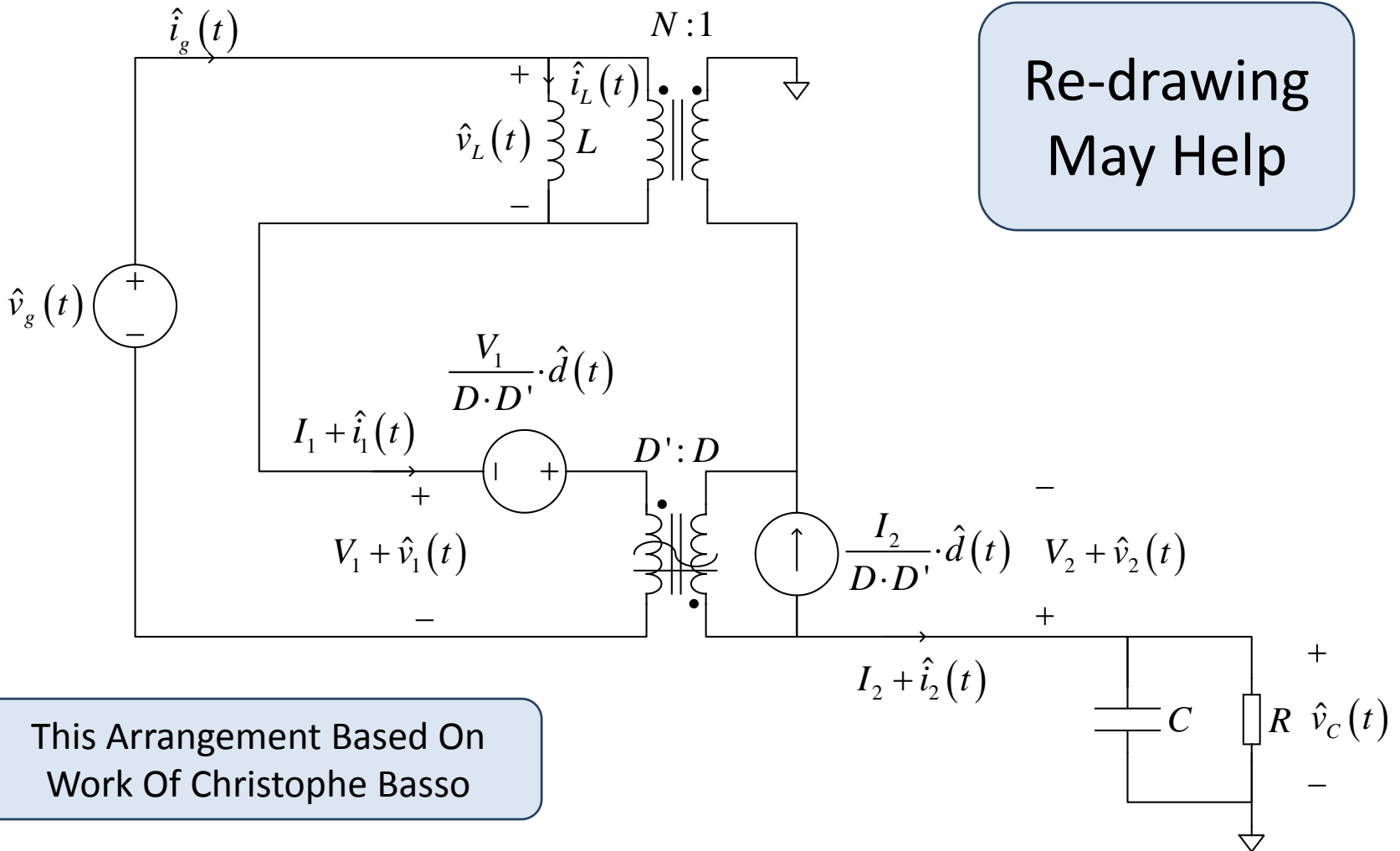


# Averaged Switch Small Signal Model: Flyback

Simulation: Maybe



# Averaged Switch Small Signal Model: Flyback

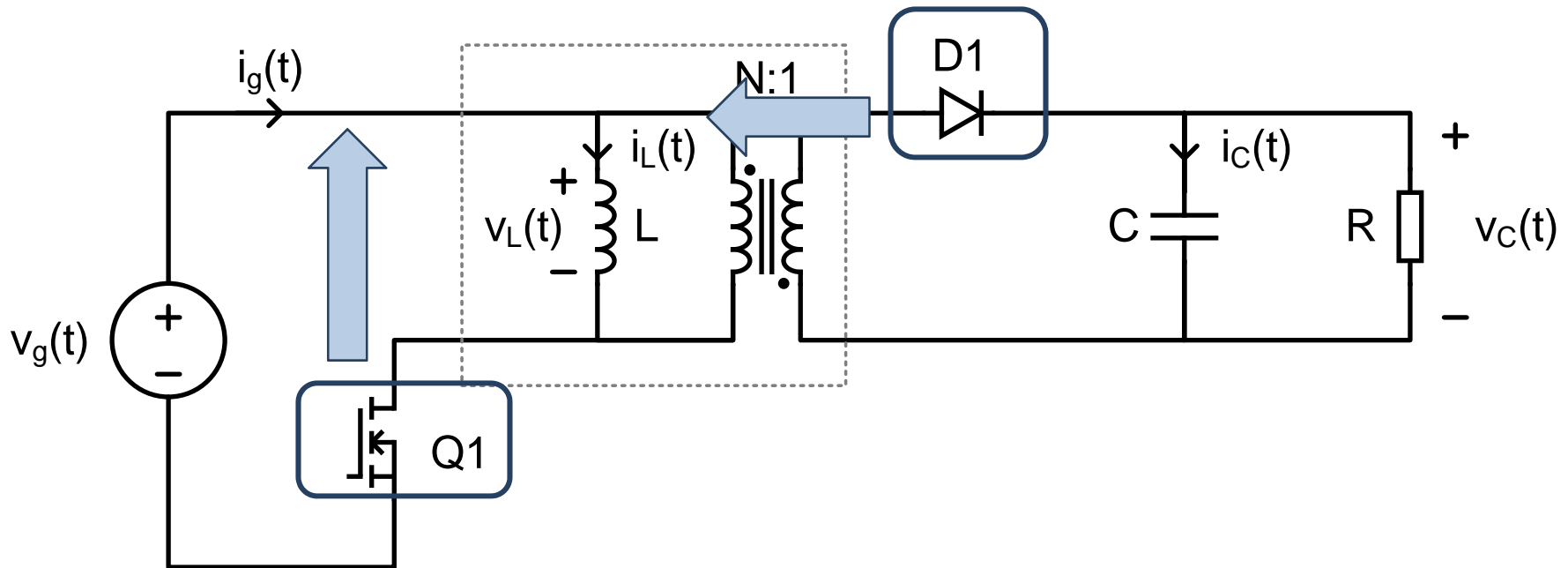


Re-drawing  
May Help

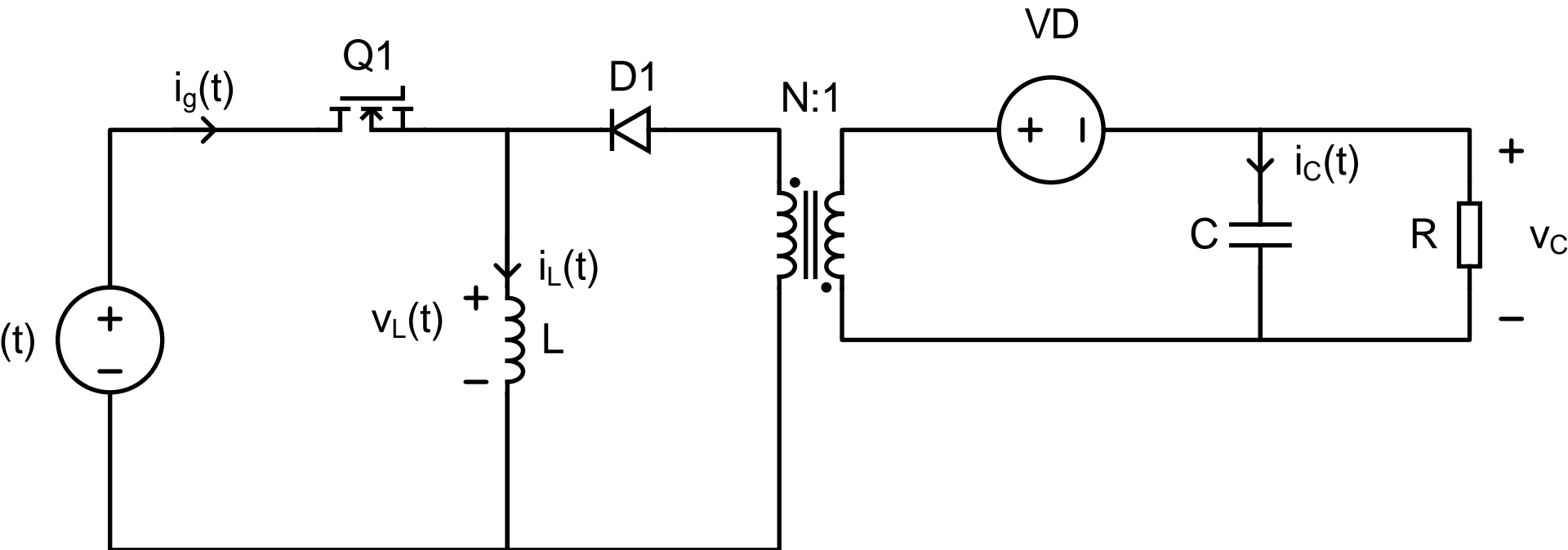
This Arrangement Based On  
Work Of Christophe Basso

# Averaged Switch Small Signal Model: + Flyback

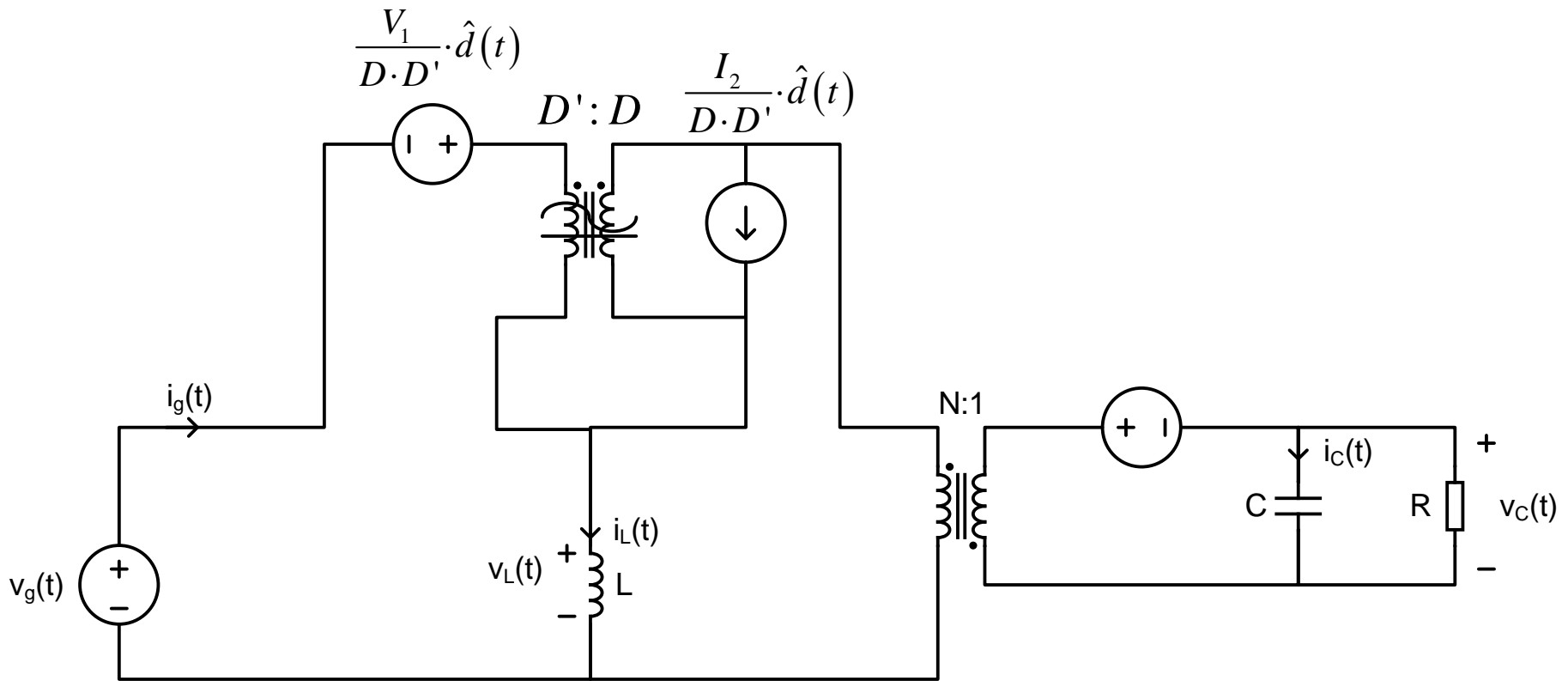
Re-draw  
As For Averaged  
Model



# Averaged Switch Small Signal Model: + Flyback

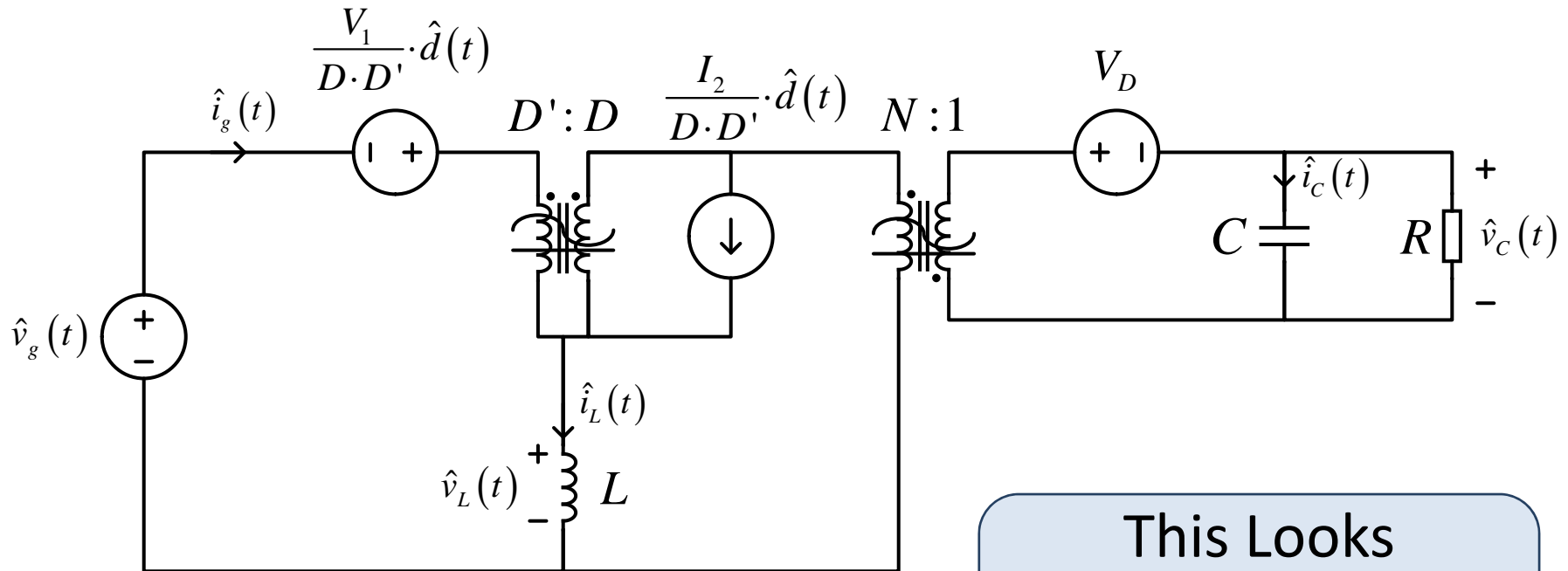


# Averaged Switch Small Signal Model: + Flyback





# Averaged Switch Small Signal Model: + Flyback

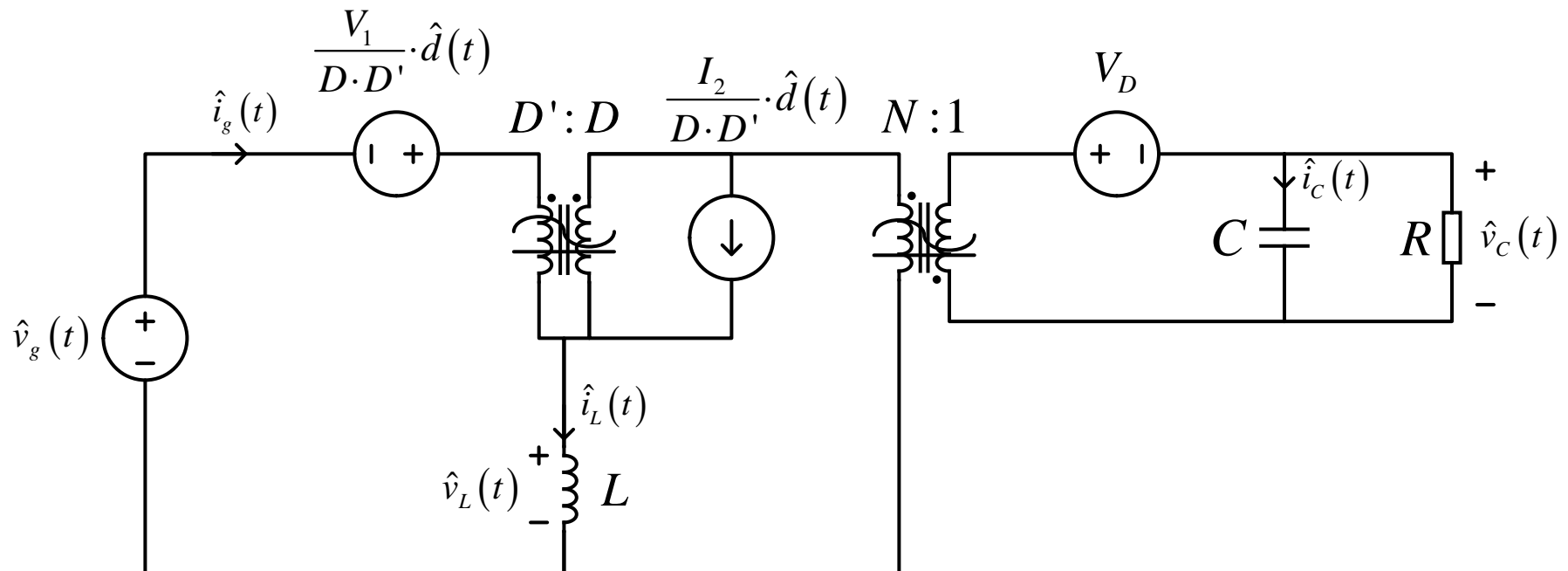


This Looks  
More  
Promising

# Averaged Switch Small Signal Model: !

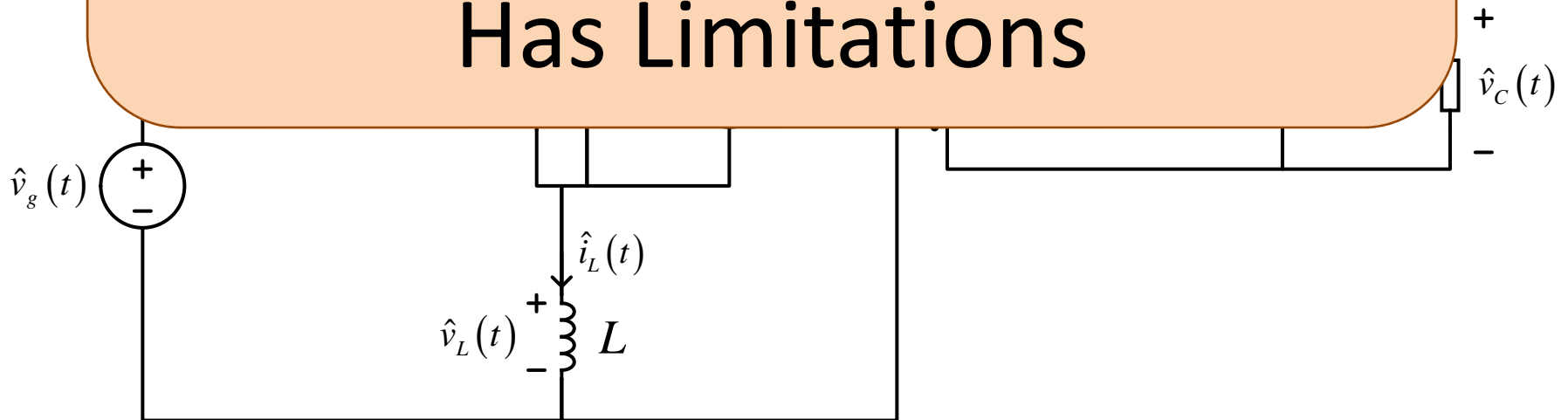
## Flyback

Derive Transfer Functions?  
Still Very Tedious

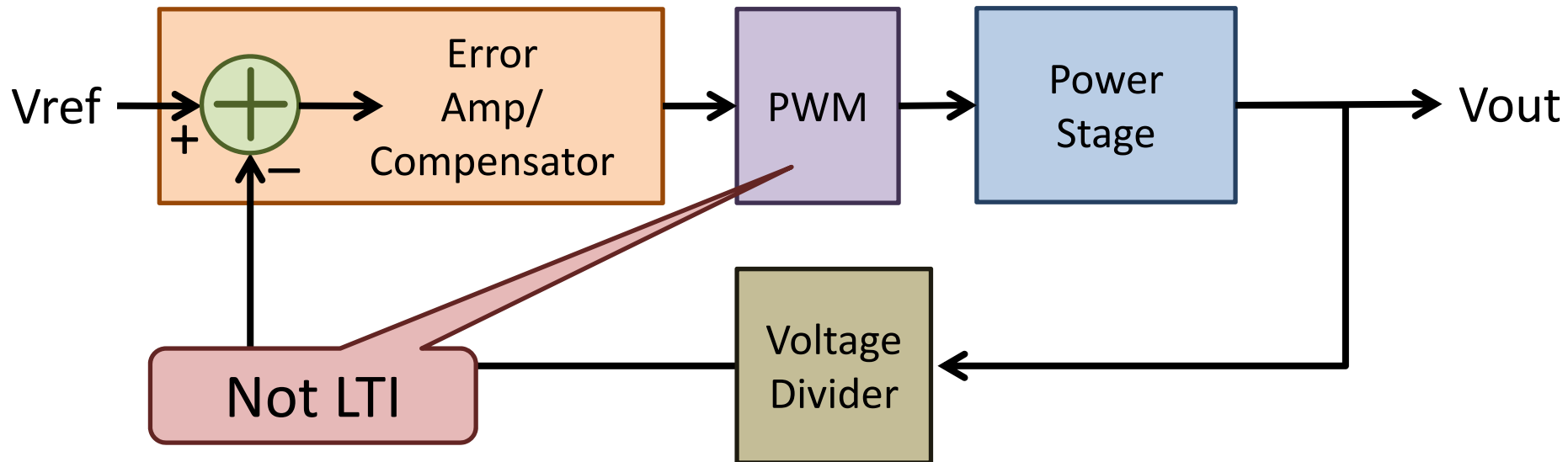


# Averaged Switch Small Signal Model: Flyback !

The Point Of This Example?  
Averaged Switch  
Small Signal Modeling  
Has Limitations

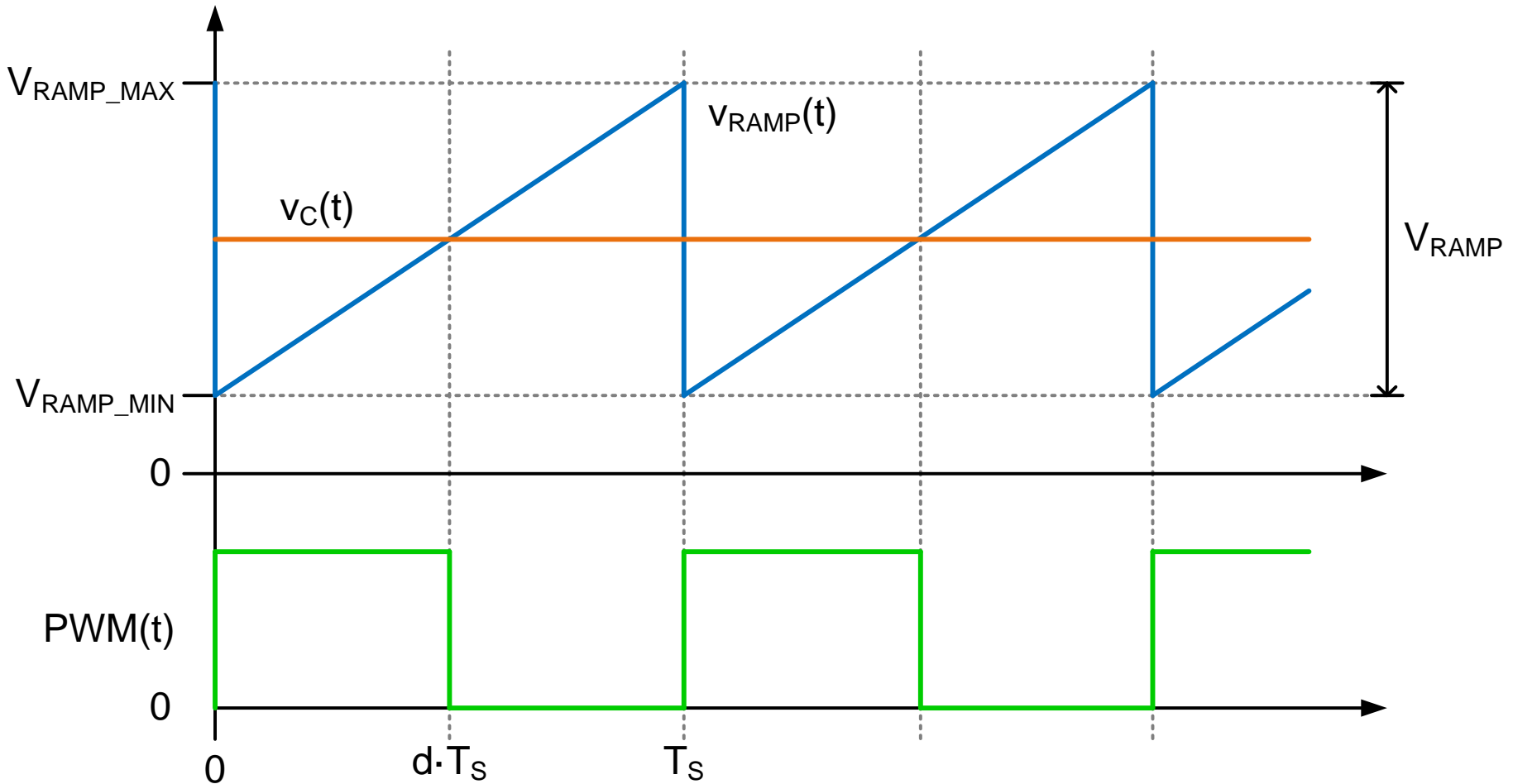


# Small Signal Model Of Pulse-Width Modulator

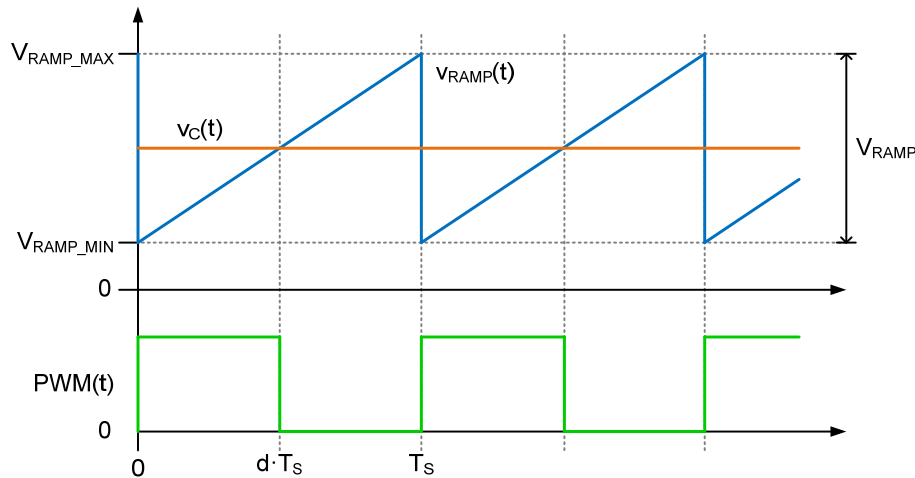


We Also Need A Small Signal Model For The Pulse Width Modulator

# Small Signal Model Of Pulse-Width Modulator



# Small Signal Model Of Pulse-Width Modulator



$$d(t) = \frac{v_C(t) - V_{RAMP\_MIN}}{V_{RAMP}}$$

$$= \frac{v_C(t)}{V_{RAMP}} - \frac{V_{RAMP\_MIN}}{V_{RAMP}}$$

$$d(t) = D + \hat{d}(t)$$

$$v_C(t) = V_C + \hat{v}_C(t)$$

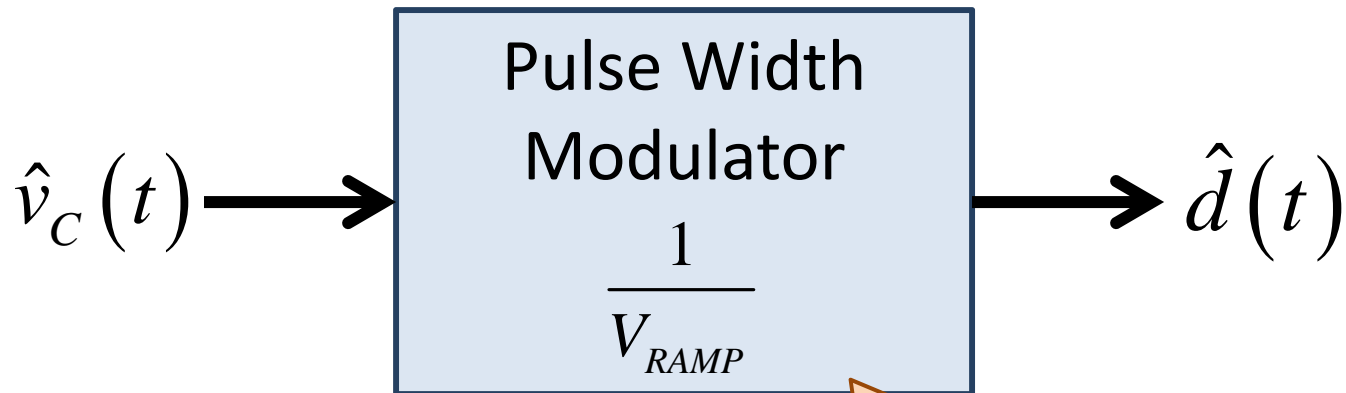
$$D + \hat{d}(t) = \frac{V_C + \hat{v}_C(t)}{V_{RAMP}} - \frac{V_{RAMP\_MIN}}{V_{RAMP}}$$

$$= \frac{\hat{v}_C(t)}{V_{RAMP}} + \frac{V_C - V_{RAMP\_MIN}}{V_{RAMP}}$$

$$D = \frac{V_C - V_{RAMP\_MIN}}{V_{RAMP}}$$

$$\hat{d}(t) = \frac{\hat{v}_C(t)}{V_{RAMP}}$$

# Small Signal Model Of Pulse-Width Modulator



PWM Has A Fixed Small Signal Gain

# More On Small Signal Modeling

- “Fundamentals of Power Electronics”, 2nd ed., Erickson and Maksimovic, Chapter 7
- V. Vorperian, "Simplified analysis of PWM converters using model of PWM switch. Continuous conduction mode," *Aerospace and Electronic Systems, IEEE Transactions on*, vol. 26, pp. 490-496, 1990.
- V. Vorperian, "Simplified analysis of PWM converters using model of PWM switch. II. Discontinuous conduction mode," *Aerospace and Electronic Systems, IEEE Transactions on*, vol. 26, pp. 497-505, 1990.
- Papers, seminars, books by Ray Ridley and Christophe Basso



# Summary

- We Need Small Signal Models To Use Standard Control Tools To Design The Loop
- Two Averaging Methods Shown To Derive A Small Signal Model Of A Switching Converter:
  - Average Inductor Voltages And Capacitor Currents
  - Average Switch Network Port Voltages And Currents
- Transfer Functions Of Interest Can Be Found From The Small Signal Models

You Can Download The Latest Version Of The Seminar  
In Adobe Acrobat (.pdf)

And Microsoft PowerPoint Show Format (.ppsx)

From The Embedded Power Labs website:

<http://www.embeddedpowerlabs.com/publications.html>

# About The Presenter

Bob White has over 30 years experience in power electronics. He has held managerial and individual contributor positions in product development, technology development, applications and systems engineering, and technical marketing. His areas of expertise include power systems for computing and telecommunications systems, digital power, and applications of wide bandgap power semiconductor devices. Bob is currently the president and chief engineer of Embedded Power Labs, a power electronics consulting company.



Bob has been very active in the IEEE Power Electronics Society and the APEC committees, including twice serving as the APEC General Chair.

He is a Fellow of the IEEE, has a BSEE from MIT, a MSEE from Worcester Polytechnic Institute and is currently pursuing a Ph.D. in power electronics at the University of Colorado-Boulder. He is also an Honorably Discharged veteran of service in the United States Air Force.